



**Escuela de Doctorado  
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# **Aprendizaje automático en el diseño de un detector de estrés a partir de señales biomédicas**

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## Índice General

### Memoria

Abstract

Introducción

Objetivos

Estado del arte

Metodología

Resultados

Conclusiones

Referencias Bibliográficas

### Apéndices



# Memoria

*Aprendizaje automático en el diseño de un detector de estrés a partir de señales biomédicas*



## **1. Memoria**

### **1.1. Abstract**

Automatic learning in the design of a stress detector from biomedical signals.

In this project the use of artificial neural networks to elaborate a stress detector is investigated. Specifically, we describe the development of a project to determine a classifier model of a system based on supervised automatic learning algorithms. We use the data of 15 subjects provided by the Siegen university and Robert Bosch GmbH in the development, and we study how to work with this data and the results obtained. This study is designed on Python programming language, which has libraries that facilitate this type of investigation.



## Índice

1.	Memoria .....	6
1.1.	Abstract .....	6
1.2.	Introducción .....	8
1.3.	Objetivos .....	10
1.4.	Estado del arte .....	10
1.5.	Metodología .....	12
1.5.1.	Análisis de datos .....	14
1.5.2.	RNA Detector Pectoral: .....	20
1.5.3.	RNA Detector de Pulsera .....	25
1.5.4.	RNA Ensemble .....	27
1.6.	Resultados .....	28
1.7.	Conclusiones .....	31
1.8.	Referencias Bibliográficas .....	33



## 1.2. Introducción

La presente investigación trata sobre el diseño de una red neuronal artificial para la detección de estrés a partir de señales biomédicas obtenidas mediante *wearables*, en este caso son una pulsera y un medidor de pecho. Las Redes Neuronales Artificiales (RNA) se enmarcan dentro de un campo de la inteligencia artificial, en definitiva, son “un modelo matemático de una red neuronal biológica formado por la unión de unidades más simples llamadas perceptrón” [2].

Debido a la creciente aparición de enfermedades provocadas por el estrés en la sociedad europea actual y gracias a diversos estudios médicos se han podido identificar estos tipos:

- Riesgos estrés prenatal aumenta riesgo enfermedades psiquiátricas. [1]
- Enfermedades cardiovasculares:
  - Ataque cardiaco.
  - Insuficiencia cardiaca.
  - Accidente cerebrovascular [17].
- Ansiedad [6].

El estrés es una reacción de alerta y activación ante una situación a la que no se puede atender si no se incrementa la actividad cognitiva, fisiológica y conductual. Las reacciones de estrés suelen acarrear diferentes respuestas emocionales, especialmente de ansiedad, que es una emoción natural que comprende las reacciones que tienen los seres humanos ante la amenaza de un resultado negativo o incierto [6].

Debido a los efectos negativos del estrés cobra relevancia su detección, para poder tomar medidas adecuadas a tiempo y evitar sus efectos negativos. Por ello, utilizando los datos de 15 sujetos facilitados por Robert Bosch GmbH<sup>1</sup> y University Siegen<sup>2</sup>, para la detección de estrés y diversión, se ha realizado una investigación sobre diferentes tipos de redes neuronales artificiales con la finalidad de diagnosticar estrés a partir de señales biomédicas.

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<sup>1</sup> Compañía alemana iniciada en 1886 por Robert Bosch

<sup>2</sup> <http://www.uni-siegen.de/start/>





El proyecto describe en la sección 1.3 los objetivos del mismo, en la sección 1.4 el estado del arte actual en este campo de estudio. La metodología empleada para el desarrollo de las diferentes pruebas de la investigación para el diseño de las RNA esta descrito en el apartado 1.5. Los resultados se muestran en el 1.6 y las conclusiones obtenidas en el 1.7. Los códigos desarrollados se encuentran en los Apéndices de la sección 2.



### 1.3. Objetivos

- Llevar a cabo una revisión bibliográfica sobre los métodos actuales utilizados para la detección de estrés.
- Realizar diferentes diseños de las redes neuronales artificiales para la realización de un detector de estrés a partir de señales biomédicas.
- Llevar a cabo el entrenamiento y la prueba de los diferentes modelos, métodos y comparar los resultados para saber cuál sería la opción más adecuada.

### 1.4. Estado del arte

Actualmente se investigan diferentes formas de diagnosticar el estrés, por ejemplo, la detección facial que se basa principalmente en los movimientos asimétricos de cejas y boca [18]. También existen estudios sobre el estrés en ambientes laborales que se detecta utilizando sensores ECG (electrocardiógrafo) y GSR (Respuesta galvánica de la piel), este último da una medida de la conductividad eléctrica de la piel. Estas medidas permiten clasificar situaciones de estrés y no estrés [21]. Así mismo existen diferentes estudios de como poder provocar estrés en condiciones de laboratorio: como el TSST (Prueba de estrés social) y Cold pressor test (prueba de presión fría), entre otros [5]. A la hora de detectar estrés algunos de las mediciones más utilizadas para ello serían:

- Actividad cardiaca.
- Actividad electrodérmica.
- Actividad cerebral.
- Información del habla.

Existe una investigación llevada a cabo en la Universidad de Siegen[20] que estudia distintos métodos para la detección de estrés en diferentes sujetos obteniendo dos conjuntos de datos para cada sujeto, uno a través de una banda pectoral la cual tiene los siguientes sensores:

- ACC: acelerómetro.
- RESP: Respiración.
- ECG: Electrocardiógrafo.
- EDA: Actividad electrodérmica.

- EMG: Electromiografía, es un procedimiento de diagnóstico que se utiliza para evaluar la salud de los músculos y las células nerviosas que los controlan [7].
- TEMP: Temperatura.

Y el otro conjunto de datos a través de una pulsera que lleva estos otros sensores:

- ACC: acelerómetro.
- BVP: Pulso sanguíneo.
- EDA: Actividad electrodérmica.
- TEMP: Temperatura.

Esta investigación utiliza diversos métodos para la detección del estrés y otros estados afectivos como la diversión y el estado base. Además, cuentan con estados de meditación que los usan para volver de cualquiera de los estados de estrés o diversión al estado base. Este estudio facilita los datos utilizados en este TFM [20].

Los métodos empleados por los investigadores de la Universidad de Siegen fueron:

- Árbol de decisión.
- Random Forest.
- AdaBoost.
- LDA (Análisis de discriminación lineal).
- kNN (Vecino cercano).

Obteniendo resultados para la detección de estrés y no estrés de hasta un 92%-93% para el detector de pecho y del 87%-88% para el de pulsera. Sin embargo, a la hora de detectar diversión su precisión baja, siendo de un 75%-76% para la pulsera y el detector de pecho.



## 1.5. Metodología

EL diseño de la RNA del detector de estrés de esta investigación se ha realizado utilizando Python<sup>3</sup>, debido a las grandes facilidades que ofrece a la hora de trabajar con redes neuronales a través del entorno del notebook de Jupiter<sup>4</sup> gracias a la flexibilidad que da a la hora del uso de las librerías la ejecución del código y la presentación del documento de salida.

Anaconda Navigator es una interfaz de usuario gráfica de escritorio incluida en Anaconda que le permite iniciar aplicaciones y administrar fácilmente paquetes, entornos y canales de conda sin la necesidad de usar comandos de línea de comandos [15].

### LAS LIBRERÍAS UTILIZADAS EN ESTA INVESTIGACIÓN

<b>KERAS</b>	Se trata una API <sup>5</sup> de redes neuronales de alto nivel, escrita en Python y capaz de ejecutarse sobre TensorFlow [8].
<b>TENSORFLOW</b>	Es una plataforma de código abierto de extremo a extremo para el aprendizaje automático [14].
<b>SCIKIT-LEARN</b>	Librería de herramientas simples y eficientes para minería y análisis de datos [13].
<b>MATPLOTLIB</b>	Es una librería de trazado 2D de Python para producir graficas en una variedad de formatos y entornos interactivos en todas las plataformas [9].
<b>PICKLE</b>	Se trata de un módulo que implementa protocolos binarios para serializar y deserializar una estructura de objeto Python [12].
<b>PANDAS</b>	Es una librería que proporciona estructuras de datos y herramientas de análisis de datos de alto rendimiento para el lenguaje de programación Python [11].
<b>NUMPY</b>	Es un paquete para la computación científica con Python, permite trabajar con matrices de forma sencilla, algebra lineal, entre otras funciones [10].

*Tabla 1 Finalidad de las librerías utilizadas*

<sup>3</sup> <https://www.python.org/>

<sup>4</sup> <https://jupyter.org/>

<sup>5</sup> Application Programming Interface

Las librerías descritas anteriormente (ver tabla 1) ofrecen las herramientas necesarias, según la función que permita desempeñar, para diseñar las redes neuronales artificiales. Estas son modelos computacionales que se basan en el funcionamiento del cerebro humano. No se conocen perfectamente los mecanismos del cerebro, aunque se sabe que está formado por un gran número de neuronas  $10^{12}$ , funcionando de forma paralela y que producen diferentes niveles de activación en neuronas adyacentes. De igual modo, las RNA están formadas por una cierta cantidad de unidades básicas de procesamiento llamadas perceptrones o neuronas, conectadas según ciertas reglas, donde cada conexión tiene asociado un peso [3].

Cuando se diseña una red neuronal se deben establecer las siguientes características:

- La cantidad de neuronas en cada capa.
- La cantidad de capas.
- La función de activación optimizador y pérdidas o función de coste.
- El tipo de conexión entre neuronas, en este caso se recomienda que sea hacia delante para el reconocimiento de patrones.
- El algoritmo de entrenamiento para conseguir que la red aprenda, este puede ser supervisado o no supervisado. En la presente investigación es supervisado puesto que conocemos la salida a la cual queremos que se adapte la red [3].

Las neuronas artificiales o perceptrones están formadas por:

- Conjunto de entradas  $X$  (ver figura 1): Representan las entradas de la neurona.
- Pesos sinápticos  $W$  (ver figura 1): Cada entrada tiene un peso que se va ajustando de forma automática a medida que la red neuronal va aprendiendo.
- Función de agregación,  $\Sigma$  (ver figura 1): Suma todas las entradas ponderadas por sus pesos.

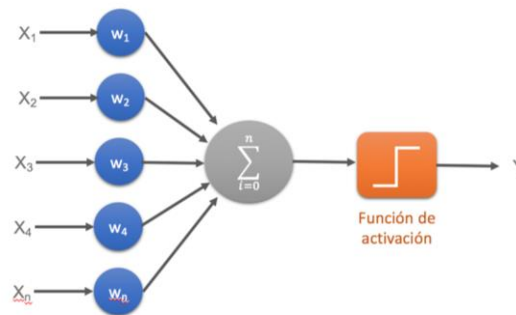


Figura 1 Imagen perceptrón [19]

Además, se debe definir la función de activación, la función de coste y el optimizador. La función de activación mantiene el conjunto de valores de salida en un rango determinado, la función de coste o *loss* trata de determinar el error entre el valor obtenido y el valor real, para poder entrenar la RNA. Por último, el optimizador facilita el gradiente en el que se ha de avanzar durante el entrenamiento de la red, es decir, da la dirección hacia donde debe ir la función, pues fija donde tiene la ratio de aumento más pronunciado [19].

Finalmente se define lo que es un ensemble, puesto que se hacen pruebas con el mismo en esta investigación. A la hora de trabajar con un ensemble se realiza el entrenamiento de dos o más RNA con diferentes conjuntos de datos para las mismas salidas, es decir, el conjunto principal de datos se divide en diferentes subconjuntos con distintas variables en cada uno. Posteriormente, con los resultados de ambas redes, se obtiene un valor final utilizando las salidas que han sido obtenidas de las diferentes redes, mediante algún algoritmo matemático u otra red neuronal [4].

### 1.5.1. Análisis de datos

En la presente investigación se utilizan los datos de 15 sujetos facilitados por Robert Bosch GmbH y University Siegen, como se ha comentado anteriormente. Los datos se encuentran en ficheros pkl, se trata de un objeto Python almacenado directamente en un archivo o cadena, ordenados con sus etiquetas según sea el detector de pecho o muñeca y por el tipo de sensor y separados en diferentes archivos según el sujeto.

En las figuras 2 a 12 se representan gráficamente para el sujeto 2 los datos que se obtienen de cada uno de los sensores, para el detector pectoral, el de pulsera y sus estados:

- Detector Pectoral:
  - Acelerómetro o ACC:

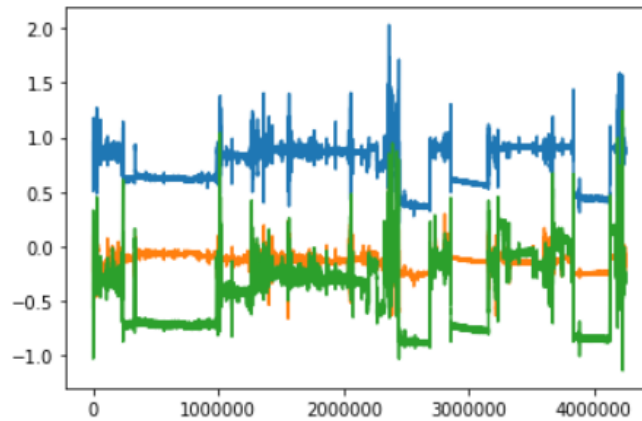


Figura 2 Señal acelerómetro Detector Pectoral

- Electrocardiograma o ECG:

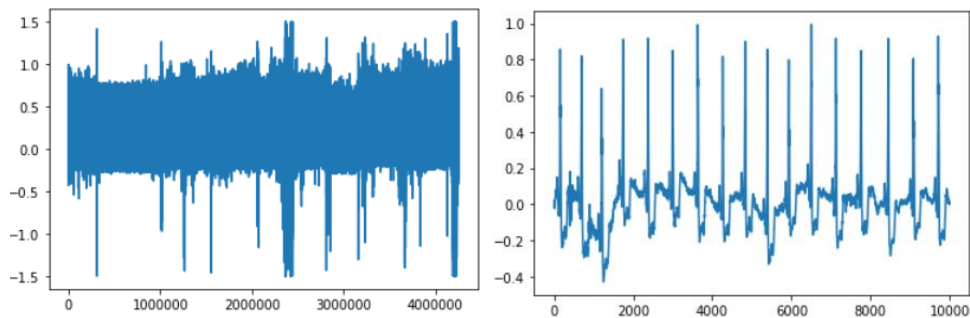


Figura 3 Señal electrocardiograma Detector Pectoral

- Electromiografía o EMG:

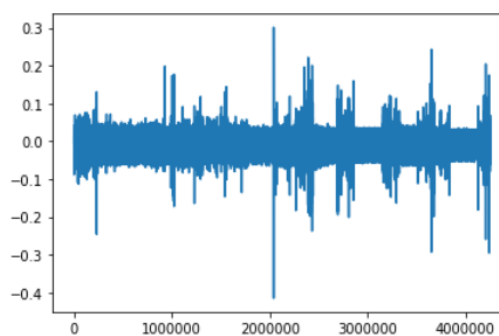


Figura 4 Señal Electromiografía Detector Pectoral



I-Memoria

- Actividad Electrodermica o EDA:

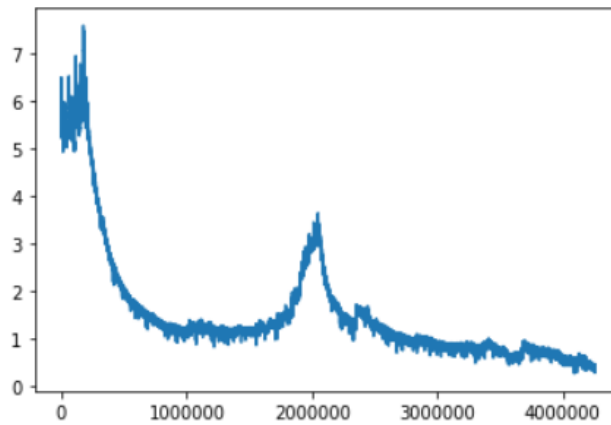


Figura 5 Señal Electrodermica Detector Pectoral

- Temperatura:

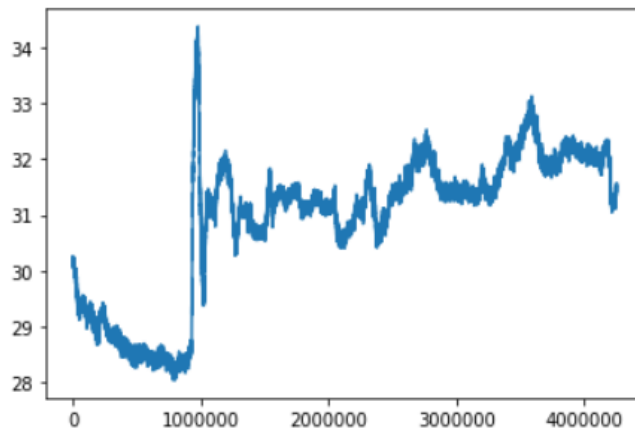


Figura 6 Señal de Temperatura Detector Pectoral

- Respiración:

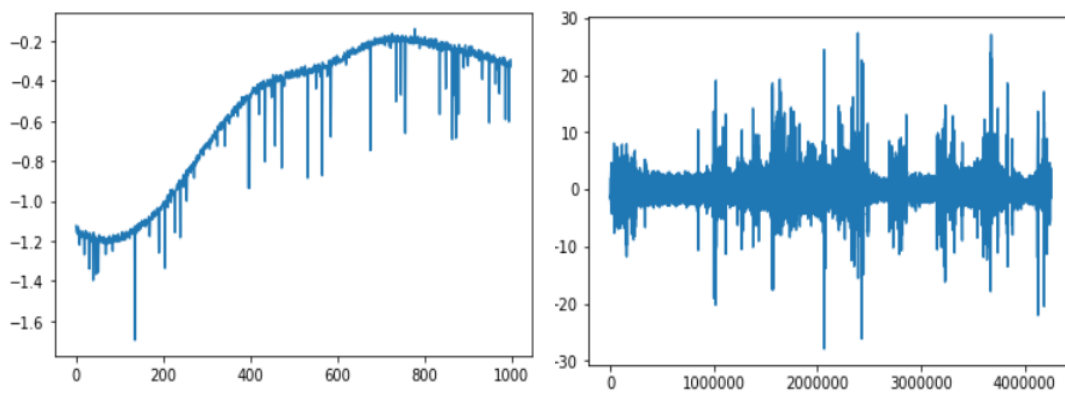


Figura 7 Señal Respiración Detector Pectoral



- Detector de Pulsera:
  - Acelerómetro o ACC:

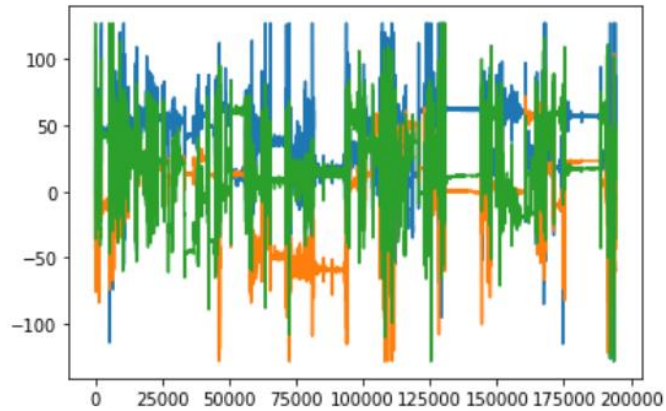


Figura 8 Señal acelerómetro Detector de pulsera

- Pulso sanguíneo o BVP:

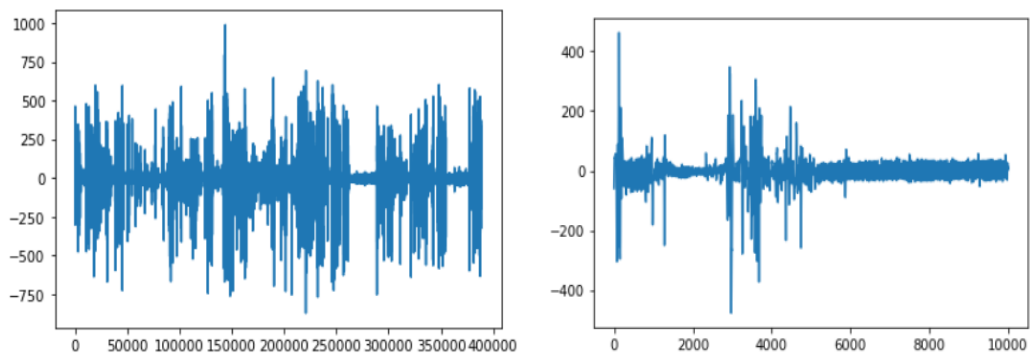


Figura 9 Señal de pulso sanguíneo Detector de pulsera

- Actividad Electrodermica o EDA:

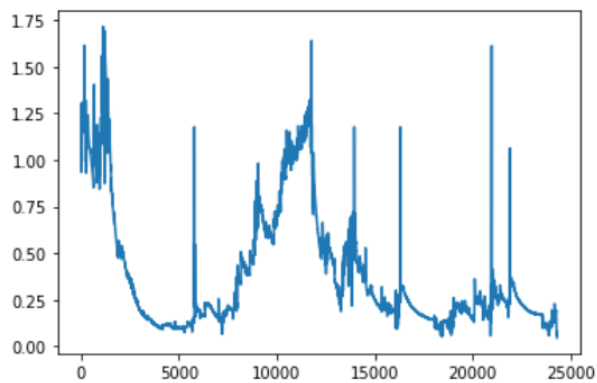


Figura 10 Señal de Actividad Electrodermica Detector de pulsera



I-Memoria

- Temperatura:

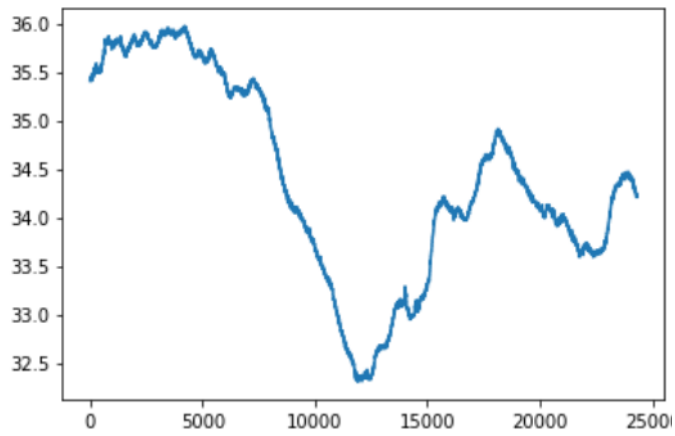


Figura 11 Señal Temperatura Detector de Pulsera

- Estados (ver tabla 2):

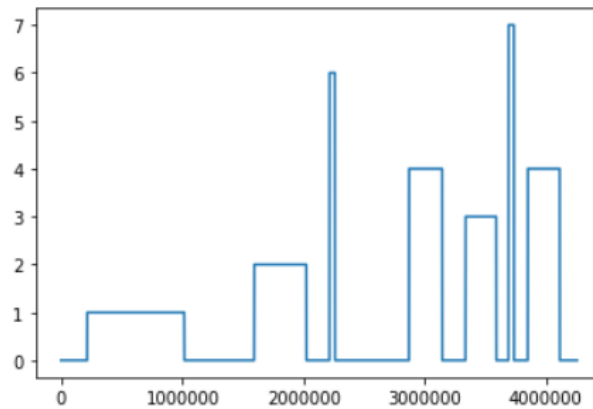


Figura 12 Estados del Sujeto

### 1.5.2. Flujograma del proceso

A continuación, vemos un flujograma de los pasos que sigue el código de la RNA:

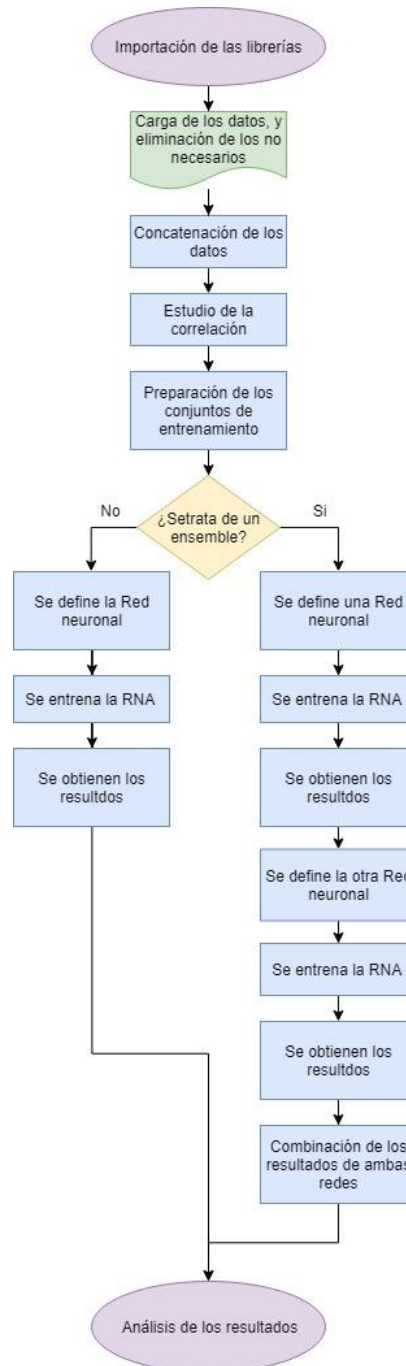


Figura 13 Flujograma del código de la RNA



### 1.5.3. RNA Detector Pectoral

La carga de los datos se realiza utilizando la librería pickle, posteriormente se guardan en variables para que se puedan unir en una matriz.

```
data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
```

Figura 14 Carga de los datos para el detector pectoral

Para cumplimentar la información se añade otra columna con la edad del sujeto, toda la información se concatena en una matriz en la que se descartan los datos que no son de interés para el entrenamiento de la RNA, puesto que no aportan información sobre estados de la investigación.

```
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

Figura 15 Creación de la matriz y eliminación de datos no utilizables

La descripción de los estados es:

ESTADOS	DESCRIPCIÓN
0	No definido / transitorio.
1	Línea de base.
2	Estrés.
3	Diversión.
4	Meditación.
5/6/7	Debe ignorarse en este conjunto de datos.

Tabla 2 Estados definidos en la investigación de referencia [16]

Se descartan los datos para salidas con valores superiores a 4 e inferiores a 1. La elevada cantidad de datos empleados conlleva un gran consumo de memoria RAM. Por esa razón, sirve para aliviar los requerimientos sobre este recurso y evitar posibles errores en la ejecución del código.

Una vez generada la matriz de datos de cada sujeto se unen:

```
MAT=np.concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15),axis=0)
```

Figura 16 Concatenación de las matrices de los sujetos

Se estudia la correlación de los datos de los diferentes sensores para determinar si existe algún dato que no sea de utilidad porque aporta la misma información o muy similar que otro sensor, es decir, que su correlación sea cercana a uno (ver tabla 3).

```
data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

Figura 17 Generación matriz de correlación

	0	1	2	3	4	5	6	7	8	9
0	1	-0.116371	0.111886	-0.0997043	4.41357e-05	-0.00957082	0.0941815	0.265322	-0.00163408	0.00518957
1	-0.116371	1	0.141815	0.736804	-0.000777993	0.0285744	0.0597632	0.176475	-0.00258757	-0.220018
2	0.111886	0.141815	1	0.15978	0.00130894	0.00706299	0.107432	0.287241	-0.00249185	-0.490428
3	-0.0997043	0.736804	0.15978	1	-0.000655872	0.0183223	0.000482257	0.113601	0.00185039	-0.0848492
4	4.41357e-05	-0.000777993	0.00130894	-0.000655872	1	-0.14177	-0.000186393	0.00384364	0.0064098	7.70639e-05
5	-0.00957082	0.0285744	0.00706299	0.0183223	-0.14177	1	-0.00713845	0.0676265	0.00390984	0.00842724
6	0.0941815	0.0597632	0.107432	0.000482257	-0.000186393	-0.00713845	1	0.149413	-0.000231788	-0.115606
7	0.265322	0.176475	0.287241	0.113601	0.00384364	0.0676265	0.149413	1	0.00795273	-0.066754
8	-0.00163408	-0.00258757	-0.00249185	0.00185039	0.0064098	0.00390984	-0.000231788	0.00795273	1	0.000472801
9	0.00518957	-0.220018	-0.490428	-0.0848492	7.70639e-05	0.00842724	-0.115606	-0.066754	0.000472801	1

Tabla 3 Correlación de las entradas frente a las salidas

Como se observa en la tabla 3, existe una correlación elevada entre las columnas 1 y 3 que se corresponden con señales del mismo sensor el acelerómetro, por lo tanto, no se procede a descartar la información de ninguno de los sensores. Puesto que, a la hora de descartar señales, sería de mayor relevancia aquella que permita eliminar los datos de un sensor en su totalidad, significando que este no aporta información puesto que sería la misma que da otro sensor. Como igualmente se dispondría de las señales recopiladas por el acelerómetro no se procede a su eliminación. Se procede a dividir los datos en los conjuntos de validación y entrenamiento:



## I-Memoria

```
X = MAT[:, 1:8]
Y = MAT[:, 0]
validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y, test_size=validation_size, random_state=seed)
```

Figura 18 Separación de los conjuntos de entrenamiento y test con una relación 80-20 y de manera aleatoria [3]

Los valores de las columnas en la matriz X varían cuando se usan los datos del medidor de pecho o de la pulsera, debido a la cantidad de sensores de cada uno. Una vez se tienen ambos conjuntos de datos se define la RNA, la figura 18 es un ejemplo de una de las redes utilizadas en la investigación.

```
model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')
```

Figura 19 Diseño de una de las redes neuronales utilizadas

Los optimizadores con los que se han realizado prueba son:

- Adadelta.
- Nadam.
- Rmsprop.

Para el caso de las funciones de coste:

- mean\_squared\_logarithmic\_error.
- mean\_absolute\_error.
- Hinge.

Los activadores utilizados son:

- Selu.
- Elu.
- Capas selu y elu.
- Linear.

Una vez definida la red se lleva a cabo su entrenamiento, según sea el detector de pecho o de pulsera variará la extensión del entrenamiento. Debido a la cantidad de datos

*Aprendizaje automático en el diseño...*

disponibles de cada detector, se varían los entrenamientos tanto en el Batch<sup>6</sup> como los Epochs<sup>7</sup>, así como la cantidad de veces que llevamos a cabo el entrenamiento:

```
NUM_EPOCHS =5
BATCH_SIZE = 200

history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS, validation_split=0.1)
```

Figura 20 Entrenamiento de la RNA

Cuando se completa el entrenamiento se calculan los resultados para el conjunto de validación (ver figura 20), y se redondean los valores obtenidos (ver figura 21), puesto que, la salida tiene que ser un número entero.

```
Y_test = model.predict(X_val).flatten()
```

Figura 21 Cálculo de las salidas para el conjunto de validación

```
Y_test =np.round(Y_test, 0)
```

Figura 22 Función para el redondeo de las salidas

La evaluación de los resultados se realiza de dos maneras: el error cuadrático y el número de aciertos. Pero se debe tener en cuenta que el error cuadrático no es una medida tan relevante en el caso de esta investigación, puesto que no interesa de la misma manera saber cuánto se aproxima a los valores sino cuantos ha acertado.

```
from sklearn.metrics import r2_score
r2 = r2_score(Y_test, Y_val)
print (r2)
```

Figura 23 Cálculo del error cuadrático

```
Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

Figura 24 Cálculo del porcentaje de aciertos

<sup>6</sup> Tamaño de los lotes de procesamiento.

<sup>7</sup> Número de veces que se entrena la red en ese entrenamiento.



Se genera una gráfica que sirve para detectar el tipo de errores que comete en la red.

```
plt.plot((Y_val),
         color="b", label="actual")
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```

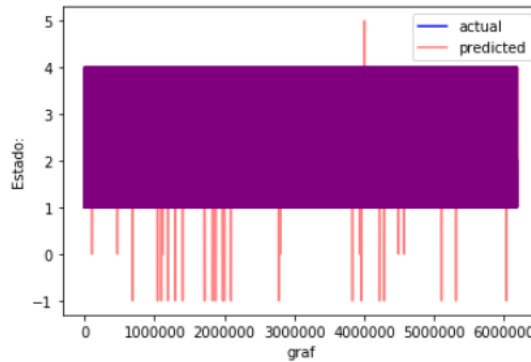


Figura 25 Gráfico en la que se muestran las salidas reales frente a las predichas

Pudiendo observar si los errores se encuentran entre los márgenes de las salidas o si al contrario son estados que no existen para nuestra red neuronal, nótese que a ella solo se le han descrito salidas entre 1 y 4.



#### 1.5.4. RNA Detector de Pulsera

Para el caso del medidor de pulsera los sensores trabajan a diferentes frecuencias, por lo tanto, dependiendo de la frecuencia de cada uno existen momentos en los que se reciben valores de unos sensores, pero de otros no. Debido a esto se descartan esos valores extra y se utilizan los valores que se dan en los mismos instantes de tiempo. Es decir, se eliminan los datos recibidos de los sensores que trabajan a mayor frecuencia porque sus valores no varían mucho en esos pequeños instantes de tiempo, hasta que los sensores de menor frecuencia vuelvan a dar un valor.

La carga de los datos del detector de pulsera se realiza de la misma forma que con el detector pectoral:

```
data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
```

Figura 26 Carga de datos para el medidor de pecho

Al tratar los datos del detector de pulsera se calcula qué sensor es el que tiene la mínima cantidad de datos, es decir el de menor frecuencia.

```
mind=min(len(a), len(b), len(c), len(d), len(A21))
```

Figura 27 Cálculo del valor mínimo de datos que se tienen

Con ello se calcula la diferencia de las frecuencias respecto a la mínima:

```
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
```

Figura 28 Relación de frecuencias de los diferentes sensores

Para llevar a cabo el código de la manera más general posible, se usa el valor de la relación entre las frecuencias y se crea un nuevo vector que se queda con el valor correspondiente a la menor frecuencia, creando un nuevo vector con datos a la menor frecuencia (ver figura 28). Se realiza para todas las entradas, se unen los datos y finalmente

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## I-Memoria

se descartan los correspondientes a las salidas 0,5,6,7 como se hacía con el medidor de pecho como se aprecia en la figura 13.

```
l1=int(len(a)/Call)
A=[]
for i in range(l1):
    k=i*Call
    at=a[int(k)]
    A.append(at)
```

Figura 29 Creación de arrays con los datos a la frecuencia de la menor de los sensores

El resto de pasos a aplicar en la metodología del detector de pulsera es igual a como se trabaja con el detector pectoral. Menos para la correlación puesto que se trata de sensores diferentes, por lo que su estudio varía.

	0	1	2	3	4	5	6	7
0	1	0.0129906	0.0970228	0.0768107	0.000704121	-0.028306	-0.339708	-0.0033121
1	0.0129906	1	-0.10602	0.112981	-0.000290653	0.182445	0.105206	0.225818
2	0.0970228	-0.10602	1	0.121402	0.00209529	-0.177823	0.0207045	-0.05912
3	0.0768107	0.112981	0.121402	1	0.000764396	-0.0207728	-0.0986843	-0.04957
4	0.000704121	-0.000290653	0.00209529	0.000764396	1	-0.000327508	-0.00232309	-0.00235096
5	-0.028306	0.182445	-0.177823	-0.0207728	-0.000327508	1	0.210019	0.0993003
6	-0.339708	0.105206	0.0207045	-0.0986843	-0.00232309	0.210019	1	0.32277
7	-0.0033121	0.225818	-0.05912	-0.04957	-0.00235096	0.0993003	0.32277	1

Tabla 4 Correlación de los datos del detector de pulsera

Se determina a partir de los valores de la tabla 4 que no existe ninguna correlación elevada entre los datos que se obtienen de los diferentes sensores del detector de pulsera.

### 1.5.5. RNA Ensemble

En esta investigación se utiliza un ensemble con los datos del medidor de pulsera. Por lo que el refinado de los datos se realiza de la misma forma, la principal diferencia data en crear dos conjuntos de datos después de haber definido los conjuntos de validación y entrenamiento como en la figura 16.

Se generan dos conjuntos, denominados A (formado por X\_trainA y X\_valA) y B (formado por X\_trainB y X\_valB) para los entrenamientos de las dos redes del ensemble. Para el conjunto A no se tiene en cuenta el ritmo cardiaco y para el conjunto B no se trabaja con la actividad electrodérmica.

```
X_trainA= np.delete(X_train,3 , 1)
X_trainB= np.delete(X_train,4 , 1)
X_valA= np.delete(X_val,3, 1)
X_valB= np.delete(X_val,4 , 1)
```

Figura 30 Generación de los conjuntos de datos para las dos RNA del ensemble

Se ha realizado el mismo procedimiento para las dos redes neuronales artificiales, que coincide con el que ha sido utilizado con las otras RNA, calculando los resultados obtenidos de ambas redes. Para obtener las salidas del ensemble se combinan usando el mínimo, el valor medio y el máximo entre ambas salidas.

```
YtA = np.asmatrix(Y_testA)
YtB = np.asmatrix(Y_testB)
ense1=np.zeros(len(Y_testA))
ense2=np.zeros(len(Y_testA))
ense3=np.zeros(len(Y_testA))
Yt=np.concatenate((YtA.T,YtB.T),axis=1)
for i in range(len(Yt)):
    ense1[i]=np.min(Yt[i,:])
    ense2[i]=np.max(Yt[i,:])
    ense3[i]=np.mean(Yt[i,:])
ense3 =np.round(ense3, 0)
```

Figura 31 Calculo de las salidas del ensemble

Para la media, además se redondea la salida porque tiene que ser un valor entero. Finalmente se obtienen el error de ajuste y el número de aciertos para cada una de las salidas y se comparan con los que se han obtenido antes de realizar el ensemble.



## 1.6. Resultados

Los resultados calculados según los tipos de ejecución se encuentran representados en las tablas 5 a 8, se puede comprobar en los apéndices 1 a 32, para cada una de las ejecuciones, los resultados que han sido obtenidos. Para cada tabla se especifica el tipo de red, activador, la función de coste, el número de apéndice en el que se recoge la salida de la ejecución del código, el error cuadrático(R2) y porcentaje de acierto(F1).

### DETECTOR PECTORAL

RED	Activador	Función de coste	Apéndice	R2	F1
ELU 5 CAPAS	Adadelta	MAE <sup>8</sup>	1	99,18%	99,40%
ELU Y SELU 5 CAPAS	Adadelta	MAE	2	98,79%	99,12%
SELU 5 CAPAS	Adadelta	MAE	3	98,32%	98,78%
LINEAR 5 CAPAS	Adadelta	MAE	4	-442%	27,26%
ELU 5 CAPAS	Nadam	MAE	5	99,00%	99,28%
ELU 5 CAPAS	Rmsprop	MAE	6	98,53%	98,94%
ELU 5 CAPAS	Adadelta	MSLE <sup>9</sup>	7	99,28%	99,28%
ELU 5 CAPAS	Adadelta	Hinge <sup>10</sup>	8	-726,61	14,44%
ELU 7 CAPAS	Adadelta	MAE	9	99,08%	99,43%
ELU 4 CAPAS	Adadelta	MAE	10	98,93%	99,08%

*Tabla 5 Resultados RNA Detector Pectoral*

<sup>8</sup> Error absoluto medio

<sup>9</sup> Error logarítmico cuadrado medio

<sup>10</sup> Error de máximo excedente

### DETECTOR DE PULSERA (CON MEDITACIÓN)

ENTRENAMIENTOS	Red	Activador	Función de coste	Apéndice	R2	F1
<b>3</b>	Elu 4 capas	Adadelta	MAE	11	95,41%	96,53%
	Elu 5 capas	Adadelta	MAE	12	95,17%	97,28%
	Elu 7 capas	Adadelta	MAE	13	91,56%	95,13%
<b>2</b>	Elu 4 capas	Adadelta	MAE	14	95,63%	97,46%
	Elu 5 capas	Adadelta	MAE	15	95,30%	97,22%
	Elu 7 capas	Adadelta	MAE	16	93,81%	96,75%
<b>1</b>	Elu 4 capas	Adadelta	MAE	17	94,73%	96,11%
	Elu 5 capas	Adadelta	MAE	18	96,32%	97,61%
	Elu 7 capas	Adadelta	MAE	19	95,57%	97,26%
<b>2</b>	Elu y Selu 5 capas	Adadelta	MAE	20	96,00%	97,78%

Tabla 6 Resultados detector de pulsera con meditación

### DETECTOR DE PULSERA (SIN MEDITACIÓN)

ENTRENAMIENTOS	Red	Activador	Función de coste	Apéndice	R2	F1
<b>2</b>	Elu y Selu 5 capas	Adadelta	MAE	21	89,23%	96,91%
<b>3</b>	Elu 4 capas	Adadelta	MAE	22	94,82%	98,17%
	Elu 5 capas	Adadelta	MAE	23	93,43%	97,75%
	Elu 7 capas	Adadelta	MAE	24	85,73%	95,78%
<b>2</b>	Elu 4 capas	Adadelta	MAE	25	94,50%	98,11%
	Elu 5 capas	Adadelta	MAE	26	93,73%	98,14%
	Elu 7 capas	Adadelta	MAE	27	90,39%	97,31%
<b>1</b>	Elu 4 capas	Adadelta	MAE	28	89,11%	96,55%
	Elu 5 capas	Adadelta	MAE	29	89,35%	97,30%
	Elu 7 capas	Adadelta	MAE	30	91,13%	96,78%

Tabla 7 Resultados detector de pulsera sin meditación

**ENSEMBLE**

<b>CONJUNTO O TIPO DE ENSEMBLE</b>	Red	Act	F	Ap	R	F
	ivador	unción	de coste	índice	2	1
<b>CONJUNTO A</b>	Elu 5 capas	Adadelta	MAE	31	94,55%	97,15%
<b>CONJUNTO B</b>	Elu 5 capas	Adadelta	MAE	31	92,37%	94,30%
<b>MINIMO</b>	Elu 5 capas	Adadelta	MAE	31	93,05%	95,60%
<b>MAXIMO</b>	Elu 5 capas	Adadelta	MAE	31	93,87%	95,86%
<b>MEDIA</b>	Elu 5 capas	Adadelta	MAE	31	94,86%	95,56%
<b>CONJUNTO A</b>	Elu 4 capas	Adadelta	MAE	32	96,23%	97,18%
<b>CONJUNTO B</b>	Elu 4 capas	Adadelta	MAE	32	93,34%	95,20%
<b>MINIMO</b>	Elu 4 capas	Adadelta	MAE	32	94,14%	95,47%
<b>MAXIMO</b>	Elu 4 capas	Adadelta	MAE	32	95,47%	96,91%
<b>MEDIA</b>	Elu 4 capas	Adadelta	MAE	32	96,05%	96,50%

*Tabla 8 Resultados de los ensemble para el detector de pulsera*

## 1.7. Conclusiones

En la presente investigación se estudian los datos de 15 sujetos, a los que se les ha provocado estrés mediante test destinados para tal efecto, afecto y meditación, con el fin de estudiar sus señales biomédicas en esos casos. Para ello, se utilizan dos detectores, una banda pectoral y una pulsera, con sensores específicos.

El objetivo principal de la investigación ha sido diseñar redes neuronales artificiales para la realización de un detector de estrés a partir de señales biomédicas y el análisis de sus resultados. Por la gran cantidad de datos con los que se trabaja, los requerimientos respecto a la RAM necesaria son elevados, así mismo, para poder trabajar de una forma más eficiente con ellos se utiliza la GPU además de la CPU evitando un consumo elevado en la misma a la hora de entrenar la red neuronal.

En la evaluación de los resultados se utilizan los métodos de: Ajuste de los resultados, error cuadrático, y la tasa de acierto, sin embargo, para esta aplicación el primero no tiene tanta relevancia, puesto que, al tratarse de un clasificador con los estados de salida definidos saber cuántas veces se ha acertado con la salida correspondiente indica mejor como está trabajando la RNA. Así mismo, se pueden comparar los resultados obtenidos con los de la investigación de Schmidt, P., Reiss, A., Duerichen, R., Marberger, C., y Van Laerhoven, K. Introducing WESAD, a Multimodal Dataset for Wearable Stress and Affect Detection[20] en la que se estudia para el mismo conjunto de sujetos pero utilizando otros métodos.

En el desarrollo de las RNA se ha estudiado en un principio como se comportaba con diferentes tipos de redes neuronales, mostrando algunas que no son válidas, para el detector de pecho, que se encuentran en los apéndices 4 y 8.

Si se analizan los resultados obtenidos se puede determinar que las mejores configuraciones de red para este propósito son de tipo ELU aunque las redes SELU también trabajan de forma eficiente, así como la combinación de ambas. Porque se trata de tipos de neuronas similares, donde la SELU solo añade un escalar al tipo ELU. En cuanto a la función de coste vemos como el error medio absoluto y el error medio logarítmico cuadrado trabajan de manera correcta. Para el optimizador ocurre lo mismo vemos como tanto el optimizador Nadam como el Adadelta consiguen buenos resultados, pero algo mejores en el caso del segundo.



## I-Memoria

En el detector de pulsera se estudia cómo puede influir el largo del entrenamiento en los resultados de diferentes redes neuronales con diferentes complejidades, pudiendo determinarse que con los entrenamientos más extensos y redes más complejas no se consiguen los mejores resultados. También, se estudia excluyendo el estado de la meditación para comparar mejor los resultados con los del estudio de Robert Bosch GmbH y University Siegen. Por otra parte, se ha estudiado la posible mejora de los resultados con el uso de ensembles. Sin embargo, no se consigue una mejora de los resultados obtenidos con una simple red o respecto a los que se consiguen con uno de los conjuntos empleados para el ensemble. Aunque, en el caso del ajuste de los resultados si se produce una mejora en el primero de ellos.

Si comparamos los resultados obtenidos con los del otro estudio vemos que ellos estudian varios supuestos como se muestra en el estado del arte del presente proyecto. Ellos estudian la detección de estrés y no estrés solamente obteniendo hasta un 92%-93% de acierto para el detector de pecho y del 87%-88% para el de pulsera. En esta investigación no se ha estudiado solo la detección de estrés y no estrés puesto que con los demás estados ya obtenemos resultados mayores al 99% para el detector de pecho y del 97-98% para el de pulsera. Cuando se incluyen estados de afecto en el estudio de Robert Bosch GmbH y University Siegen su precisión es de un 75%-76% para la pulsera y el detector de pecho, mientras que en esta investigación también se está detectando el estado de meditación consiguiendo los resultados anteriormente mencionados.

Frente a futuras investigaciones existen algunos campos en los que se podría ampliar la investigación:

- Utilizar ensemble en los cuales se aproveche la salida de una de las redes como entrada de la siguiente o con otros métodos para combinar los resultados
- En el caso del detector de pulsera se podría replicar o interpolar los datos para los sensores de menores frecuencias, en lugar de lo comentado en el apartado 1.5.2, para evitar de reducir la cantidad de datos utilizados como se realiza en esta investigación aumentarla para mejorar los resultados.



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# Apéndices

*Aprendizaje automático en el diseño de un detector de estrés a partir de señales  
biomédicas*

## 2. Apéndices

### Índice de apéndices

Apéndice 1.....	pág. 38
Apéndice 2.....	pág. 47
Apéndice 3.....	pág. 56
Apéndice 4.....	pág. 65
Apéndice 5.....	pág. 74
Apéndice 6.....	pág. 83
Apéndice 7.....	pág. 92
Apéndice 8.....	pág. 101
Apéndice 9.....	pág. 110
Apéndice 10.....	pág. 119
Apéndice 11.....	pág. 128
Apéndice 12.....	pág. 168
Apéndice 13.....	pág. 208
Apéndice 14.....	pág. 248
Apéndice 15.....	pág. 281
Apéndice 16.....	pág. 314
Apéndice 17.....	pág. 347
Apéndice 18.....	pág. 374
Apéndice 19.....	pág. 401
Apéndice 20.....	pág. 428
Apéndice 21.....	pág. 461

Apéndice 22.....	pág. 494
Apéndice 23.....	pág. 533
Apéndice 24.....	pág. 572
Apéndice 25.....	pág. 612
Apéndice 26.....	pág. 645
Apéndice 27.....	pág. 678
Apéndice 28.....	pág. 711
Apéndice 29.....	pág. 738
Apéndice 30.....	pág. 765
Apéndice 31.....	pág. 792
Apéndice 32.....	pág. 828

# Chest\_elux5\_Adadel\_mae\_Final

August 13, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
```

```
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
```

```
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
```



```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
```

```
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
```

```
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x23894efab70>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
```

```

validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)

```

Definimos la arquitectura de la red:

```

[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')

```

Entrenamos la red:

```

[21]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
    →validation_split=0.1)

```

Train on 22271762 samples, validate on 2474641 samples

Epoch 1/5

```

22271762/22271762 [=====] - 385s 17us/step - loss:
0.1249 - val_loss: 0.0589

```

Epoch 2/5

```

22271762/22271762 [=====] - 352s 16us/step - loss:
0.0467 - val_loss: 0.0392

```

Epoch 3/5

```

22271762/22271762 [=====] - 354s 16us/step - loss:
0.0381 - val_loss: 0.0323

```

Epoch 4/5

```

22271762/22271762 [=====] - 352s 16us/step - loss:
0.0342 - val_loss: 0.0335

```

Epoch 5/5

```

22271762/22271762 [=====] - 358s 16us/step - loss:
0.0320 - val_loss: 0.0267

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: "+ np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

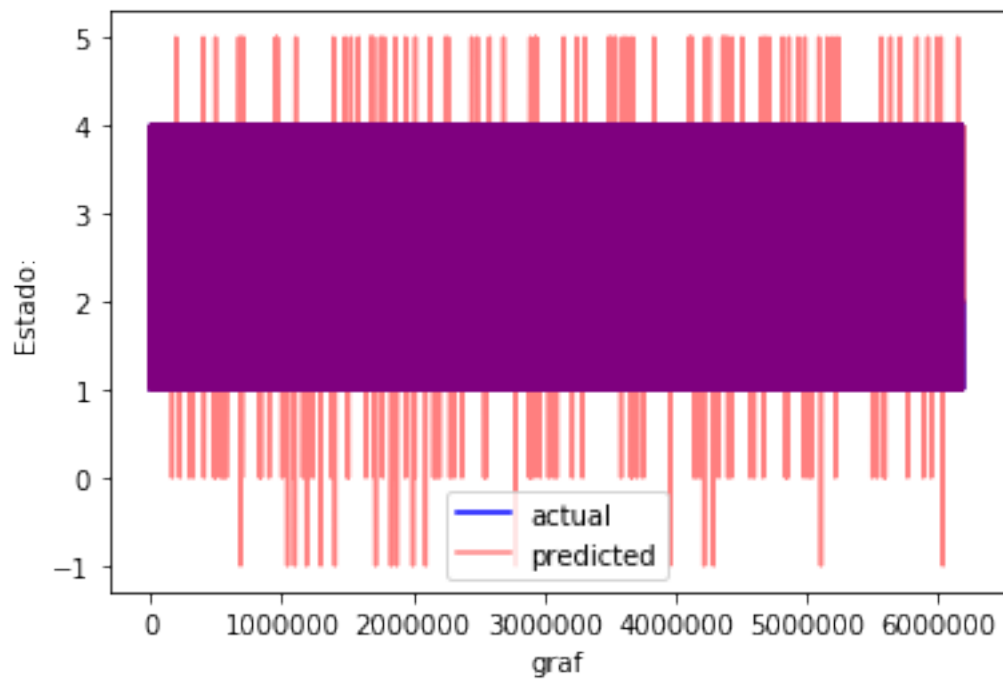
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

0.9918323255486744

```
[26]: plt.plot((Y_val),
            color="b", label="actual")
plt.plot((Y_test),
            color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.994040184586011

[ ]:

# Chest\_eluslux5\_Adadel\_mae\_Final

August 13, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
```

```
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
```



```
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
```

```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
```

```
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
```

```
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x2328189ada0>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
```

```

validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)

```

Definimos la arquitectura de la red:

```

[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('selu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('selu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')

```

Entrenamos la red:

```

[21]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
    →validation_split=0.1)

```

Train on 22271762 samples, validate on 2474641 samples

```

Epoch 1/5
22271762/22271762 [=====] - 395s 18us/step - loss:
0.1354 - val_loss: 0.0537
Epoch 2/5
22271762/22271762 [=====] - 393s 18us/step - loss:
0.0519 - val_loss: 0.0373
Epoch 3/5
22271762/22271762 [=====] - 388s 17us/step - loss:
0.0429 - val_loss: 0.0374
Epoch 4/5
22271762/22271762 [=====] - 387s 17us/step - loss:
0.0384 - val_loss: 0.0350
Epoch 5/5
22271762/22271762 [=====] - 389s 17us/step - loss:
0.0357 - val_loss: 0.0332

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: "+ np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

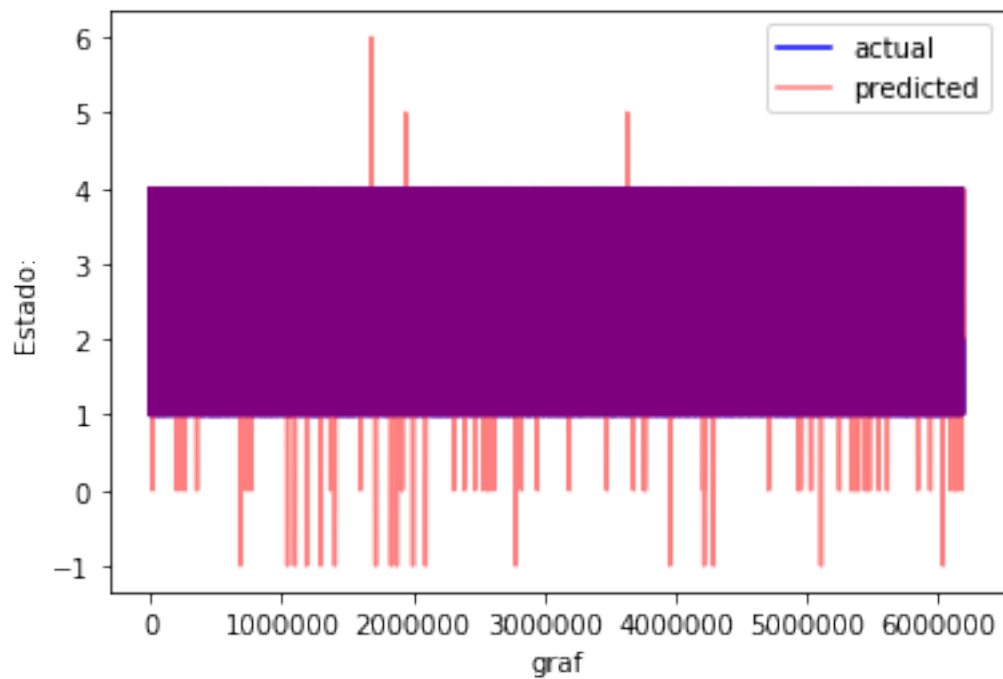
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

0.9879145895694361

```
[26]: plt.plot((Y_val),
            color="b", label="actual")
plt.plot((Y_test),
            color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.9912582046264177

[ ]:

# Chest\_selux5\_Adadel\_mae\_Final

August 16, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
      from keras.layers.core import Dense, Activation
      from keras.models import Sequential, Model
      from keras.layers import Activation
      from sklearn.preprocessing import StandardScaler
      import matplotlib.pyplot as plt
      import pickle
      import numpy as np
      import pandas
      from pandas import set_option
      from matplotlib import pyplot
      from sklearn.model_selection import train_test_split
      from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
      a=data['signal']['chest']['ACC']
      b=data['signal']['chest']['ECG']
      c=data['signal']['chest']['EMG']
      d=data['signal']['chest']['EDA']
      e=data['signal']['chest']['Temp']
      f=data['signal']['chest']['Resp']
      A2l=data['label']
      A2a=27*(np.ones((len(a),1)))
      A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
      B1 = np.asmatrix(A2l)
      B1=B1.T
      MAT1=np.concatenate((B1,A2),axis=1)
      MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
      MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```



```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
→concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x1a78ff3d710>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
Y = MAT[:, 0]
validation_size = 0.2
seed = 7
```

```
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
→test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)
```

Definimos la arquitectura de la red:

```
[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('selu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('selu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')
```

Entrenamos la red:

```
[21]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
→validation_split=0.1)
```

```
Train on 22271762 samples, validate on 2474641 samples
Epoch 1/5
22271762/22271762 [=====] - 386s 17us/step - loss:
0.1355 - val_loss: 0.0587
Epoch 2/5
22271762/22271762 [=====] - 389s 17us/step - loss:
0.0495 - val_loss: 0.0405
Epoch 3/5
22271762/22271762 [=====] - 375s 17us/step - loss:
0.0410 - val_loss: 0.0409
Epoch 4/5
22271762/22271762 [=====] - 372s 17us/step - loss:
0.0370 - val_loss: 0.0349
Epoch 5/5
22271762/22271762 [=====] - 373s 17us/step - loss:
0.0348 - val_loss: 0.0380
```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: " + np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

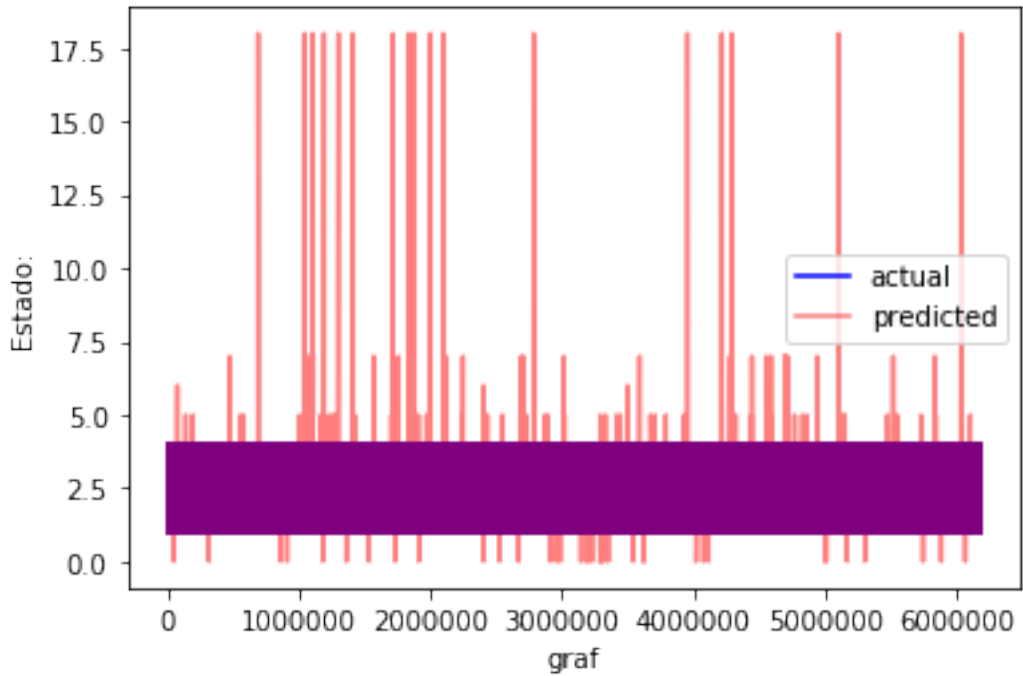
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

```
0.9832446518938989
```

```
[26]: plt.plot((Y_val),
            color="b", label="actual")
plt.plot((Y_test),
            color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.987896099974768

[ ]:



# Chest\_linearx5\_Adadel\_mae\_Final

August 16, 2019

## 1 Chest data

Librerias:

```
[2]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[3]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[17]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[18]: MAT=np.
→concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[19]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[19]: <pandas.io.formats.style.Styler at 0x2b10db7ab00>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[20]: X = MAT[:, 1:10]
Y = MAT[:, 0]
validation_size = 0.2
seed = 7
```

```
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
→test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)
```

Definimos la arquitectura de la red:

```
[35]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('linear'),
    Dense(70),
    Activation('linear'),
    Dense(48),
    Activation('linear'),
    Dense(24),
    Activation('linear'),
    Dense(1),
    Activation('linear'),
])

model.compile(optimizer='Adadelta', loss='mae')
```

Entrenamos la red:

```
[36]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
→validation_split=0.1)
```

```
Train on 22271762 samples, validate on 2474641 samples
Epoch 1/5
22271762/22271762 [=====] - 359s 16us/step - loss:
0.9948 - val_loss: 0.9842
Epoch 2/5
22271762/22271762 [=====] - 357s 16us/step - loss:
0.9873 - val_loss: 0.9841
Epoch 3/5
22271762/22271762 [=====] - 356s 16us/step - loss:
0.9866 - val_loss: 0.9852
Epoch 4/5
22271762/22271762 [=====] - 356s 16us/step - loss:
0.9863 - val_loss: 0.9839
Epoch 5/5
22271762/22271762 [=====] - 355s 16us/step - loss:
0.9860 - val_loss: 0.9840
```

```
[37]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[38]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[39]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: " + np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

```
Estado: 1., predicted:2.
Estado: 4., predicted:2.
Estado: 4., predicted:2.
Estado: 3., predicted:2.
Estado: 4., predicted:2.
Estado: 3., predicted:2.
Estado: 1., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:2.
Estado: 4., predicted:3.
Estado: 1., predicted:2.
Estado: 2., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:2.
Estado: 1., predicted:2.
Estado: 4., predicted:3.
Estado: 2., predicted:2.
Estado: 4., predicted:3.
Estado: 1., predicted:2.
Estado: 4., predicted:2.
Estado: 1., predicted:2.
Estado: 3., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:3.
Estado: 1., predicted:3.
Estado: 1., predicted:2.
```

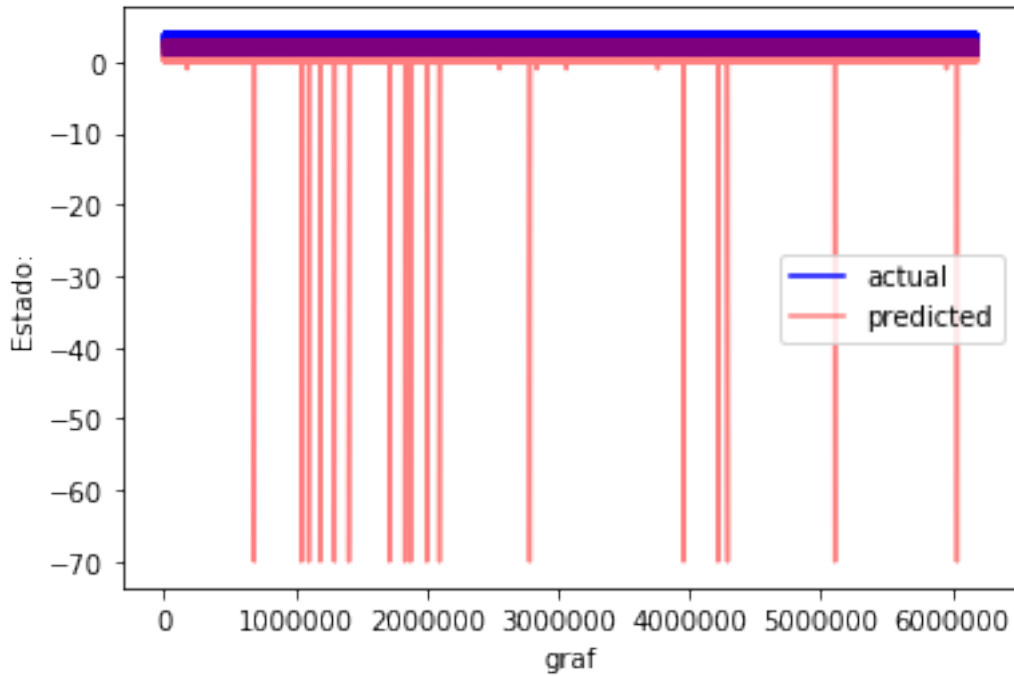
Evaluamos los resultados:

```
[40]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

```
-4.4242401679490415
```



```
[41]: plt.plot((Y_val),
            color="b", label="actual")
plt.plot((Y_test),
            color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[42]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[42]: 0.27255855032513004

[ ]:

# Chest\_elux5\_Nadam\_mae\_Final

August 16, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
```

```
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
```

```
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
```

```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
```

```
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
```

```
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x146a47da358>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
```

```

validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)

```

Definimos la arquitectura de la red:

```

[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Nadam', loss='mae')

```

Entrenamos la red:

```

[21]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
    →validation_split=0.1)

```

Train on 22271762 samples, validate on 2474641 samples

Epoch 1/5

```

22271762/22271762 [=====] - 386s 17us/step - loss:
0.0701 - val_loss: 0.0450

```

Epoch 2/5

```

22271762/22271762 [=====] - 381s 17us/step - loss:
0.0261 - val_loss: 0.0210

```

Epoch 3/5

```

22271762/22271762 [=====] - 381s 17us/step - loss:
0.0224 - val_loss: 0.0187

```

Epoch 4/5

```

22271762/22271762 [=====] - 382s 17us/step - loss:
0.0208 - val_loss: 0.0391

```

Epoch 5/5

```

22271762/22271762 [=====] - 382s 17us/step - loss:
0.0200 - val_loss: 0.0152

```



```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: "+ np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

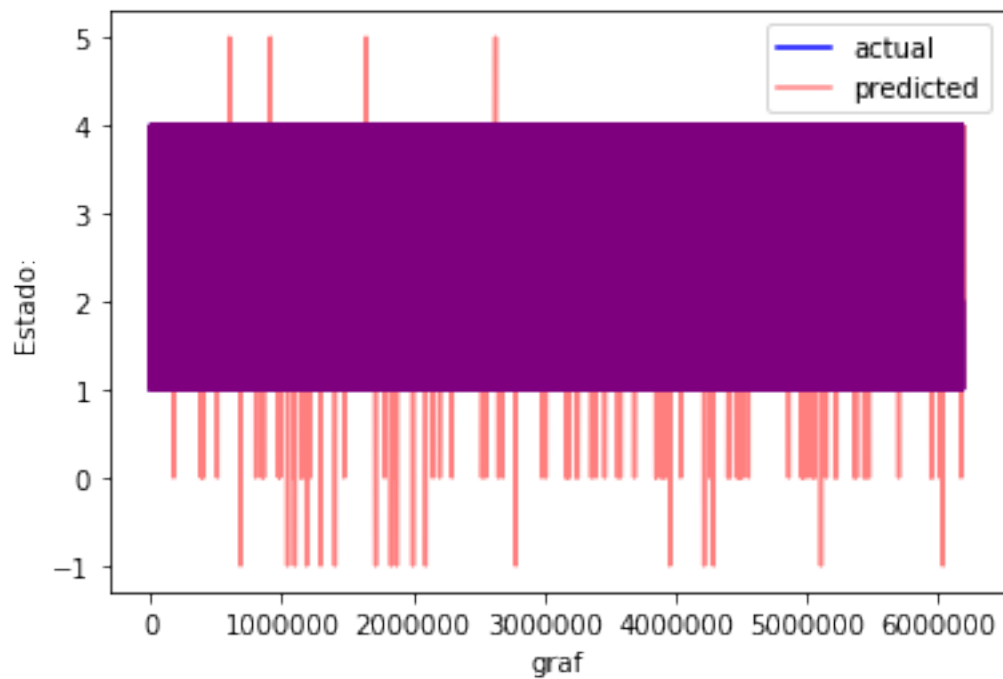
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

0.9899588276899651

```
[26]: plt.plot((Y_val),
            color="b", label="actual")
plt.plot((Y_test),
            color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.9928455059571484

[ ]:

# Chest\_elux5\_Rmsprop\_mae\_Final

August 16, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a), 1)))
A2=np.concatenate((a,b,c,d,e,f,A2a), axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
```

```

MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T

```

```

MAT4=np.concatenate((B4,A5),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)

```

```

[8]: data = pickle.load(open('S8.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T

```

```

MAT7 = np.concatenate((B7,A8),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T

```

```

MAT10 = np.concatenate((B10,A11),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T

```

```

MAT13 = np.concatenate((B13,A15),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```

[17]: MAT=np.
      →concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT

```

Comprobamos su correlación:

```

[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')

```

```

[18]: <pandas.io.formats.style.Styler at 0x266292a8cc0>

```

Dividimos en los conjuntos de validación y entrenamiento:



```
[19]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

      #scaler = StandardScaler()
      #X_train = scaler.fit_transform(X_train)
      #X_val = scaler.fit_transform(X_val)
```

Definimos la arquitectura de la red:

```
[20]: model = Sequential([
      Dense(128, input_shape=(9,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),
      Dense(48),
      Activation('elu'),
      Dense(24),
      Activation('elu'),
      Dense(1),
      Activation('elu'),
      ])

      model.compile(optimizer='Rmsprop', loss='mae')
```

Entrenamos la red:

```
[21]: NUM_EPOCHS = 5
      BATCH_SIZE = 200

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.1)
```

```
Train on 22271762 samples, validate on 2474641 samples
Epoch 1/5
22271762/22271762 [=====] - 308s 14us/step - loss:
0.1342 - val_loss: 0.0470
Epoch 2/5
22271762/22271762 [=====] - 303s 14us/step - loss:
0.0492 - val_loss: 0.0521
Epoch 3/5
22271762/22271762 [=====] - 304s 14us/step - loss:
0.0410 - val_loss: 0.0373
Epoch 4/5
22271762/22271762 [=====] - 302s 14us/step - loss:
0.0389 - val_loss: 0.0327
Epoch 5/5
```

```
22271762/22271762 [=====] - 300s 13us/step - loss:
0.0383 - val_loss: 0.0287
```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↳array2string(prediction))
```

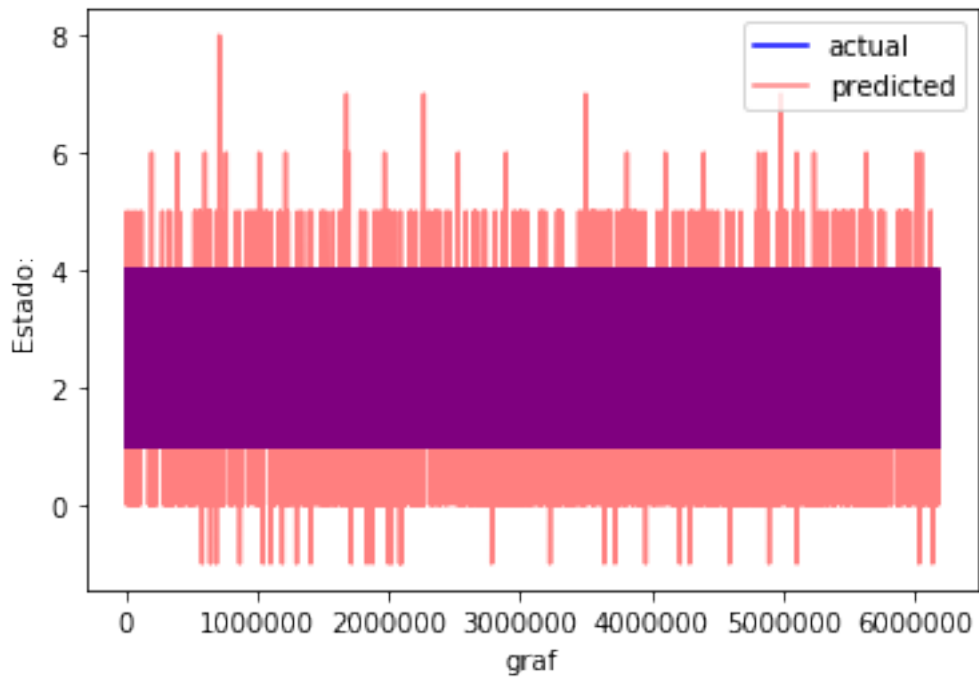
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
r2 = r2_score(Y_test, Y_val)
print (r2)
```

0.9853921976325933

```
[26]: plt.plot((Y_val),
             color="b", label="actual")
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.9894395969612393

[ ]:

# Chest\_elux5\_Adadel\_msle\_Final

August 19, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
```

```
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
```

```
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
```

```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
```

```
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
```



```
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x1faeb361a58>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
```

```

validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)

```

Definimos la arquitectura de la red:

```

[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='msle')

```

Entrenamos la red:

```

[21]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
    →validation_split=0.1)

```

Train on 22271762 samples, validate on 2474641 samples

Epoch 1/5

```

22271762/22271762 [=====] - 367s 16us/step - loss:
0.0117 - val_loss: 0.0020

```

Epoch 2/5

```

22271762/22271762 [=====] - 362s 16us/step - loss:
0.0027 - val_loss: 0.0128

```

Epoch 3/5

```

22271762/22271762 [=====] - 365s 16us/step - loss:
0.0021 - val_loss: 0.0037

```

Epoch 4/5

```

22271762/22271762 [=====] - 363s 16us/step - loss:
0.0018 - val_loss: 0.0021

```

Epoch 5/5

```

22271762/22271762 [=====] - 364s 16us/step - loss:
0.0015 - val_loss: 8.3507e-04

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: "+ np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

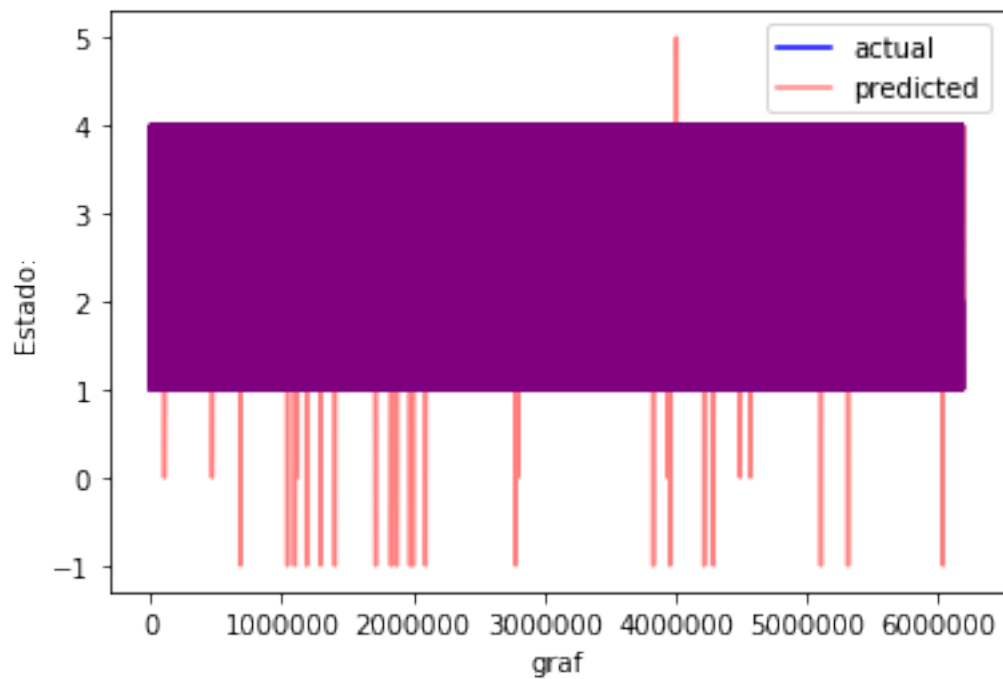
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

0.9928146995809906

```
[26]: plt.plot((Y_val),
            color="b", label="actual")
plt.plot((Y_test),
            color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.9928419498849207

[ ]:

# Chest\_elux5\_Adadel\_hinge\_Final

August 19, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a), 1)))
A2=np.concatenate((a,b,c,d,e,f,A2a), axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
```

```

MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T

```

```

MAT4=np.concatenate((B4,A5),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)

```

```

[8]: data = pickle.load(open('S8.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T

```

```

MAT7 = np.concatenate((B7,A8),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T

```



```

MAT10 = np.concatenate((B10,A11),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T

```

```

MAT13 = np.concatenate((B13,A15),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl','rb'),encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```

[17]: MAT=np.
      →concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT

```

Comprobamos su correlación:

```

[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')

```

```

[18]: <pandas.io.formats.style.Styler at 0x1921d7b8ac8>

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
Y = MAT[:, 0]
validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
→test_size=validation_size, random_state=seed)

#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)
```

Definimos la arquitectura de la red:

```
[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='hinge')
```

Entrenamos la red:

```
[21]: NUM_EPOCHS = 5
BATCH_SIZE = 200

history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
→validation_split=0.1)
```

```
Train on 22271762 samples, validate on 2474641 samples
Epoch 1/5
22271762/22271762 [=====] - 358s 16us/step - loss:
3.3479e-05 - val_loss: 9.6984e-06
Epoch 2/5
22271762/22271762 [=====] - 354s 16us/step - loss:
7.8126e-06 - val_loss: 9.6984e-06
Epoch 3/5
22271762/22271762 [=====] - 354s 16us/step - loss:
7.8126e-06 - val_loss: 9.6984e-06
Epoch 4/5
22271762/22271762 [=====] - 355s 16us/step - loss:
7.8126e-06 - val_loss: 9.6984e-06
Epoch 5/5
```

```
22271762/22271762 [=====] - 376s 17us/step - loss:
7.8126e-06 - val_loss: 9.6984e-06
```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↳array2string(prediction))
```

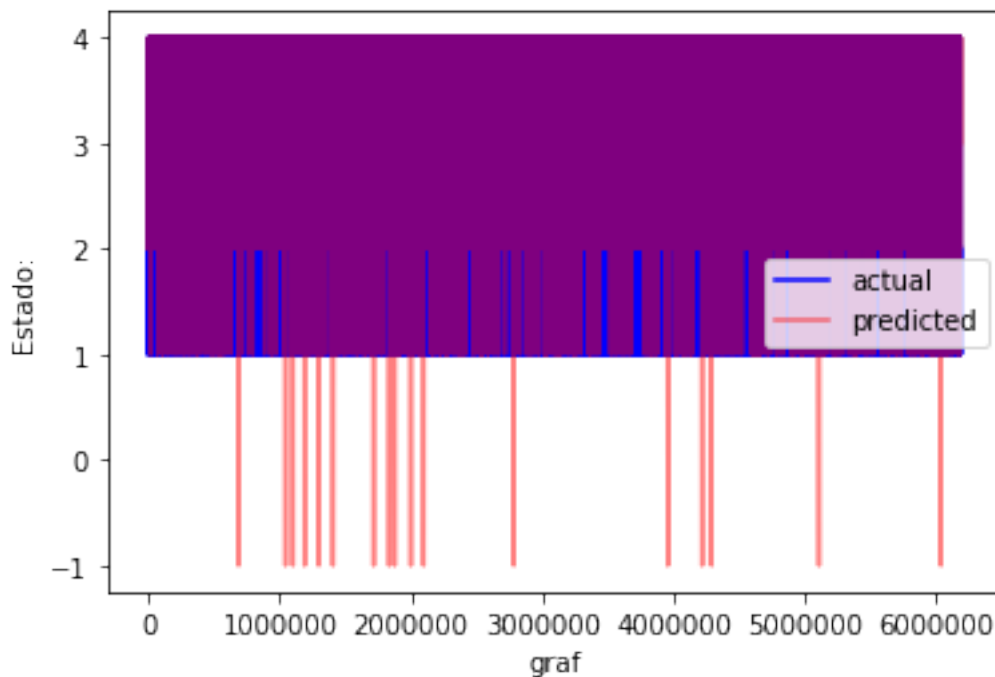
```
Estado: 1., predicted:2.
Estado: 4., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:3.
Estado: 3., predicted:2.
Estado: 1., predicted:3.
Estado: 2., predicted:3.
Estado: 2., predicted:3.
Estado: 1., predicted:3.
Estado: 3., predicted:3.
Estado: 4., predicted:3.
Estado: 4., predicted:3.
Estado: 1., predicted:4.
Estado: 2., predicted:3.
Estado: 1., predicted:3.
Estado: 4., predicted:3.
Estado: 4., predicted:3.
Estado: 1., predicted:4.
Estado: 2., predicted:3.
Estado: 1., predicted:3.
Estado: 4., predicted:3.
Estado: 2., predicted:3.
Estado: 4., predicted:3.
Estado: 1., predicted:2.
Estado: 4., predicted:3.
Estado: 1., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:3.
Estado: 2., predicted:3.
Estado: 4., predicted:3.
Estado: 1., predicted:3.
Estado: 1., predicted:3.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
r2 = r2_score(Y_test, Y_val)
print (r2)
```

-7.246078264733157

```
[26]: plt.plot((Y_val),
              color="b", label="actual")
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.1443957675628346

[ ]:

# Chest\_elux7\_Adadel\_mae\_Final

August 13, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
```

```
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
```

```
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
```



```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
```

```
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
```

```
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x264ffc03c18>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[19]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
```

```

validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)
#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)

```

Definimos la arquitectura de la red:

```

[20]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(60),
    Activation('elu'),
    Dense(40),
    Activation('elu'),
    Dense(40),
    Activation('elu'),
    Dense(30),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')

```

Entrenamos la red:

```

[21]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
    →validation_split=0.1)

```

```

Train on 22271762 samples, validate on 2474641 samples
Epoch 1/5
22271762/22271762 [=====] - 466s 21us/step - loss:
0.0954 - val_loss: 0.0439
Epoch 2/5
22271762/22271762 [=====] - 458s 21us/step - loss:
0.0340 - val_loss: 0.0309
Epoch 3/5
22271762/22271762 [=====] - 458s 21us/step - loss:
0.0296 - val_loss: 0.0266
Epoch 4/5
22271762/22271762 [=====] - 461s 21us/step - loss:
0.0276 - val_loss: 0.0229

```

```
Epoch 5/5
22271762/22271762 [=====] - 462s 21us/step - loss:
0.0262 - val_loss: 0.0216
```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))
```

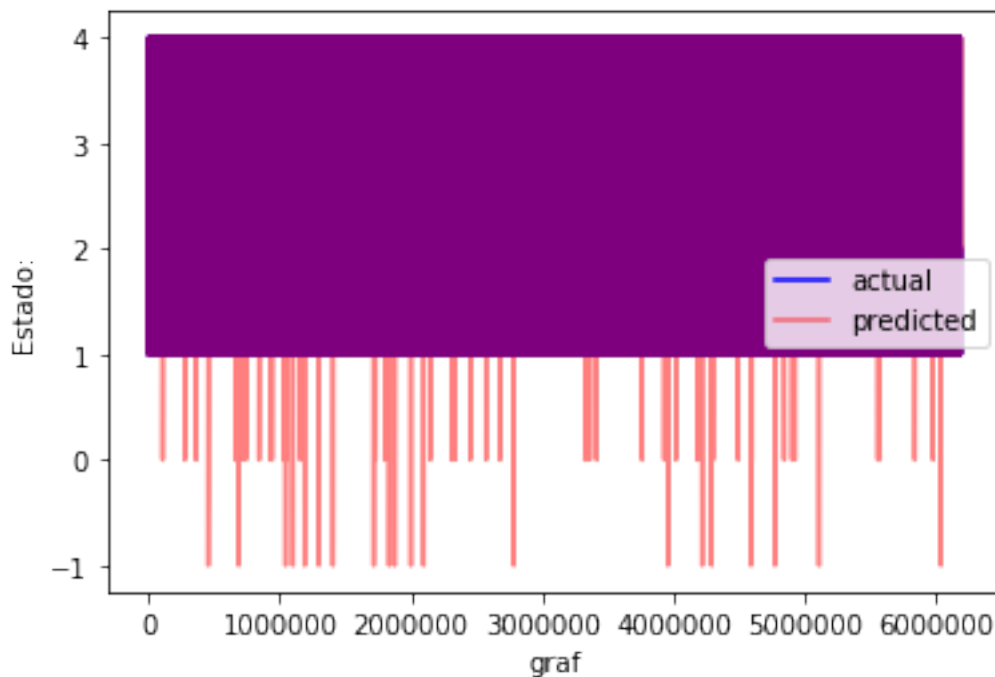
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
r2 = r2_score(Y_test, Y_val)
print (r2)
```

0.9908086594460415

```
[26]: plt.plot((Y_val),
             color="b", label="actual")
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.9943419658064259

[ ]:

# Chest\_elux4\_Adadel\_mae\_Final

August 13, 2019

## 1 Chest data

Librerias:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Chest

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A2l=data['label']
A2a=27*(np.ones((len(a),1)))
A2=np.concatenate((a,b,c,d,e,f,A2a),axis=1)
B1 = np.asmatrix(A2l)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
```

```
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)
```

```
[3]: data = pickle.load(open('S3.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A3l=data['label']
A3a=25*(np.ones((len(a),1)))
A3=np.concatenate((a,b,c,d,e,f,A3a),axis=1)
B2 = np.asmatrix(A3l)
B2=B2.T
MAT2=np.concatenate((B2,A3),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)
```

```
[4]: data = pickle.load(open('S4.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A4l=data['label']
A4a=35*(np.ones((len(a),1)))
A4=np.concatenate((a,b,c,d,e,f,A4a),axis=1)
B3 = np.asmatrix(A4l)
B3=B3.T
MAT3=np.concatenate((B3,A4),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)
```

```
[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A5l=data['label']
A5a=27*(np.ones((len(a),1)))
A5=np.concatenate((a,b,c,d,e,f,A5a),axis=1)
B4 = np.asmatrix(A5l)
B4=B4.T
MAT4=np.concatenate((B4,A5),axis=1)
```



```
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)
```

```
[6]: data = pickle.load(open('S6.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A6l=data['label']
A6a=28*(np.ones((len(a),1)))
A6=np.concatenate((a,b,c,d,e,f,A6a),axis=1)
B5 = np.asmatrix(A6l)
B5=B5.T
MAT5=np.concatenate((B5,A6),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)
```

```
[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A7l=data['label']
A7a=27*(np.ones((len(a),1)))
A7=np.concatenate((a,b,c,d,e,f,A7a),axis=1)
B6 = np.asmatrix(A7l)
B6=B6.T
MAT6=np.concatenate((B6,A7),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A8l=data['label']
A8a=26*(np.ones((len(a),1)))
A8=np.concatenate((a,b,c,d,e,f,A8a),axis=1)
B7 = np.asmatrix(A8l)
B7=B7.T
MAT7 = np.concatenate((B7,A8),axis=1)
```

```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A9l=data['label']
A9a=28*(np.ones((len(a),1)))
A9=np.concatenate((a,b,c,d,e,f,A9a),axis=1)
B8 = np.asmatrix(A9l)
B8=B8.T
MAT8 = np.concatenate((B8,A9),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A10l=data['label']
A10a=26*(np.ones((len(a),1)))
A10=np.concatenate((a,b,c,d,e,f,A10a),axis=1)
B9 = np.asmatrix(A10l)
B9=B9.T
MAT9 = np.concatenate((B9,A10),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)
```

```
[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A11l=data['label']
A11a=28*(np.ones((len(a),1)))
A11=np.concatenate((a,b,c,d,e,f,A11a),axis=1)
B10 = np.asmatrix(A11l)
B10=B10.T
MAT10 = np.concatenate((B10,A11),axis=1)
```

```
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)
```

```
[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A13l=data['label']
A13a=24*(np.ones((len(a),1)))
A13=np.concatenate((a,b,c,d,e,f,A13a),axis=1)
B11 = np.asmatrix(A13l)
B11=B11.T
MAT11 = np.concatenate((B11,A13),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)
```

```
[13]: data = pickle.load(open('S14.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A14l=data['label']
A14a=24*(np.ones((len(a),1)))
A14=np.concatenate((a,b,c,d,e,f,A14a),axis=1)
B12 = np.asmatrix(A14l)
B12=B12.T
MAT12 = np.concatenate((B12,A14),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)
```

```
[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A15l=data['label']
A15a=29*(np.ones((len(a),1)))
A15=np.concatenate((a,b,c,d,e,f,A15a),axis=1)
B13 = np.asmatrix(A15l)
B13=B13.T
MAT13 = np.concatenate((B13,A15),axis=1)
```

```
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)
```

```
[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A16l=data['label']
A16a=29*(np.ones((len(a),1)))
A16=np.concatenate((a,b,c,d,e,f,A16a),axis=1)
B14 = np.asmatrix(A16l)
B14=B14.T
MAT14 = np.concatenate((B14,A16),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)
```

```
[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['chest']['ACC']
b=data['signal']['chest']['ECG']
c=data['signal']['chest']['EMG']
d=data['signal']['chest']['EDA']
e=data['signal']['chest']['Temp']
f=data['signal']['chest']['Resp']
A17l=data['label']
A17a=29*(np.ones((len(a),1)))
A17=np.concatenate((a,b,c,d,e,f,A17a),axis=1)
B15 = np.asmatrix(A17l)
B15=B15.T
MAT15 = np.concatenate((B15,A17),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)
```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Comprobamos su correlación:

```
[18]: data=pandas.DataFrame(MAT)
corr = data.corr()
corr.style.background_gradient(cmap='coolwarm')
```

```
[18]: <pandas.io.formats.style.Styler at 0x1ab9003dba8>
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[22]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
```

```

validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)
#scaler = StandardScaler()
#X_train = scaler.fit_transform(X_train)
#X_val = scaler.fit_transform(X_val)

```

Definimos la arquitectura de la red:

```

[26]: model = Sequential([
    Dense(128, input_shape=(9,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')

```

Entrenamos la red:

```

[27]: NUM_EPOCHS = 5
    BATCH_SIZE = 200

    history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
    →validation_split=0.1)

```

```

Train on 22271762 samples, validate on 2474641 samples
Epoch 1/5
22271762/22271762 [=====] - 329s 15us/step - loss:
0.1802 - val_loss: 0.0869
Epoch 2/5
22271762/22271762 [=====] - 330s 15us/step - loss:
0.0735 - val_loss: 0.0642
Epoch 3/5
22271762/22271762 [=====] - 322s 14us/step - loss:
0.0602 - val_loss: 0.0464
Epoch 4/5
22271762/22271762 [=====] - 316s 14us/step - loss:
0.0535 - val_loss: 0.0594
Epoch 5/5
22271762/22271762 [=====] - 331s 15us/step - loss:
0.0488 - val_loss: 0.0485

```

```

[28]: Y_test = model.predict(X_val).flatten()

```

Redondeamos los resultados puesto que deben de ser enteros:

```
[29]: Y_test = np.round(Y_test, 0)
```

Mostramos una parte de los resultados:

```
[30]: for i in range(30):
      YA= np.squeeze(np.asarray(Y_val))
      label = YA[i]
      prediction = Y_test[i]
      print("Estado: " + np.array2string(label) + ", predicted:" + np.
      →array2string(prediction))
```

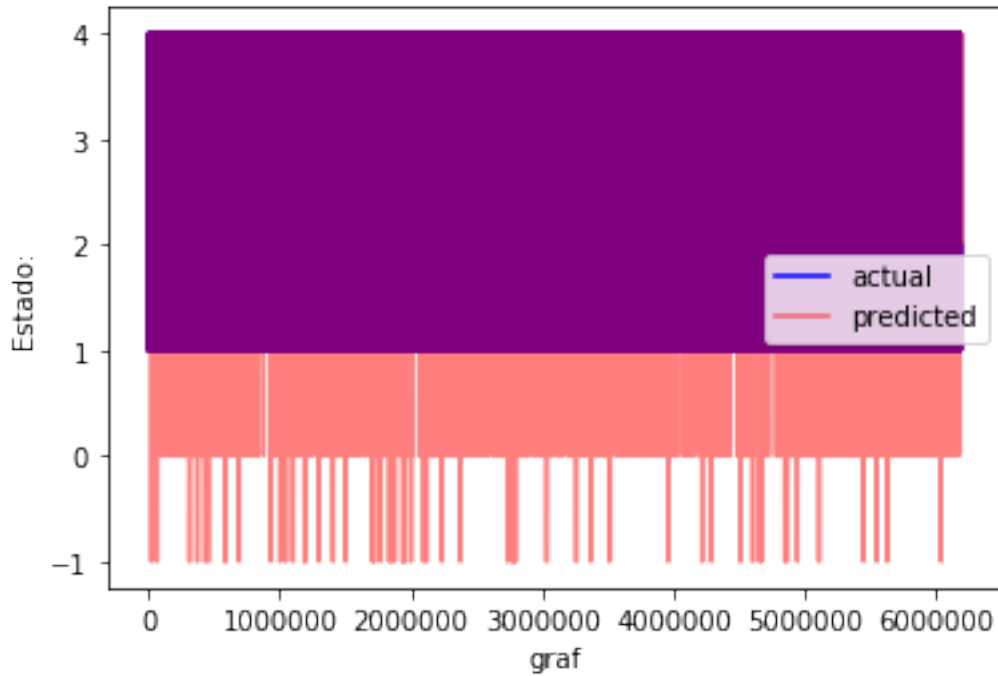
```
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[31]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

```
0.9892761203009343
```

```
[32]: plt.plot((Y_val),
             color="b", label="actual")
plt.plot((Y_test),
             color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[33]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[33]: 0.9907550204061972
```

```
[:]
```

# Wrist\_elux4\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```



```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```



```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```



```
Dense(60),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')
```

WARNING: Logging before flag parsing goes to stderr.  
W0830 18:43:38.173150 21680 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 18:43:38.218029 21680 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 18:43:38.230027 21680 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 18:43:38.287892 21680 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```
[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

W0830 18:43:38.476339 21680 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 18:43:38.482322 21680 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.5812 -  
val\_loss: 0.4073

Epoch 2/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.3536 -  
val\_loss: 0.3165

Epoch 3/100  
115092/115092 [=====] - 17s 145us/step - loss: 0.2866 -  
val\_loss: 0.2833

Epoch 4/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.2494 -  
val\_loss: 0.3436

Epoch 5/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.2250 -  
val\_loss: 0.2282

Epoch 6/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.2052 -  
val\_loss: 0.1929

Epoch 7/100  
115092/115092 [=====] - 17s 147us/step - loss: 0.1894 -  
val\_loss: 0.2017

Epoch 8/100  
115092/115092 [=====] - 17s 146us/step - loss: 0.1784 -  
val\_loss: 0.1831

Epoch 9/100  
115092/115092 [=====] - 16s 137us/step - loss: 0.1686 -  
val\_loss: 0.1819

Epoch 10/100  
115092/115092 [=====] - 16s 138us/step - loss: 0.1580 -  
val\_loss: 0.1538

Epoch 11/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1504 -  
val\_loss: 0.1528

Epoch 12/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.1441 -  
val\_loss: 0.1321

Epoch 13/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.1389 -  
val\_loss: 0.1535

Epoch 14/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1344 -  
val\_loss: 0.1532

Epoch 15/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1312 -  
val\_loss: 0.1380

Epoch 16/100  
115092/115092 [=====] - 17s 145us/step - loss: 0.1277 -

val\_loss: 0.1224  
Epoch 17/100  
115092/115092 [=====] - 16s 137us/step - loss: 0.1253 -  
val\_loss: 0.1261  
Epoch 18/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1230 -  
val\_loss: 0.1179  
Epoch 19/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.1208 -  
val\_loss: 0.1232  
Epoch 20/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1185 -  
val\_loss: 0.1284  
Epoch 21/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1163 -  
val\_loss: 0.1255  
Epoch 22/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1146 -  
val\_loss: 0.1445  
Epoch 23/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1131 -  
val\_loss: 0.1094  
Epoch 24/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1117 -  
val\_loss: 0.1152  
Epoch 25/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1098 -  
val\_loss: 0.1301  
Epoch 26/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1077 -  
val\_loss: 0.1117  
Epoch 27/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1063 -  
val\_loss: 0.1067  
Epoch 28/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1045 -  
val\_loss: 0.1212  
Epoch 29/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1033 -  
val\_loss: 0.1202  
Epoch 30/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.1018 -  
val\_loss: 0.1172  
Epoch 31/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1013 -  
val\_loss: 0.1151  
Epoch 32/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1005 -

```
val_loss: 0.1122
Epoch 33/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0990 -
val_loss: 0.1118
Epoch 34/100
115092/115092 [=====] - 17s 143us/step - loss: 0.0981 -
val_loss: 0.1119
Epoch 35/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0970 -
val_loss: 0.1033
Epoch 36/100
115092/115092 [=====] - 17s 144us/step - loss: 0.0965 -
val_loss: 0.1110
Epoch 37/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0963 -
val_loss: 0.1015
Epoch 38/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0952 -
val_loss: 0.1066
Epoch 39/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0945 -
val_loss: 0.0912
Epoch 40/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0935 -
val_loss: 0.1089
Epoch 41/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0926 -
val_loss: 0.0947
Epoch 42/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0923 -
val_loss: 0.1089
Epoch 43/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0919 -
val_loss: 0.0998
Epoch 44/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0905 -
val_loss: 0.0956
Epoch 45/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0903 -
val_loss: 0.0940
Epoch 46/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0896 -
val_loss: 0.0944
Epoch 47/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0891 -
val_loss: 0.1151
Epoch 48/100
115092/115092 [=====] - 17s 143us/step - loss: 0.0889 -
```

val\_loss: 0.0930  
Epoch 49/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0883 -  
val\_loss: 0.1023  
Epoch 50/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0879 -  
val\_loss: 0.0896  
Epoch 51/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0876 -  
val\_loss: 0.0967  
Epoch 52/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0870 -  
val\_loss: 0.0813  
Epoch 53/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0869 -  
val\_loss: 0.1002  
Epoch 54/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0860 -  
val\_loss: 0.0872  
Epoch 55/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0857 -  
val\_loss: 0.0865  
Epoch 56/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0856 -  
val\_loss: 0.0881  
Epoch 57/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0848 -  
val\_loss: 0.0999  
Epoch 58/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0843 -  
val\_loss: 0.0879  
Epoch 59/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0834 -  
val\_loss: 0.1008  
Epoch 60/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0837 -  
val\_loss: 0.0929  
Epoch 61/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0832 -  
val\_loss: 0.0933  
Epoch 62/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0830 -  
val\_loss: 0.0816  
Epoch 63/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0821 -  
val\_loss: 0.0925  
Epoch 64/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0819 -

```
val_loss: 0.1027
Epoch 65/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0817 -
val_loss: 0.0785
Epoch 66/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0813 -
val_loss: 0.0972
Epoch 67/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0811 -
val_loss: 0.0925
Epoch 68/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0807 -
val_loss: 0.0849
Epoch 69/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0804 -
val_loss: 0.0926
Epoch 70/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0805 -
val_loss: 0.0949
Epoch 71/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0797 -
val_loss: 0.0780
Epoch 72/100
115092/115092 [=====] - 17s 144us/step - loss: 0.0793 -
val_loss: 0.0815
Epoch 73/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0791 -
val_loss: 0.0853
Epoch 74/100
115092/115092 [=====] - 17s 143us/step - loss: 0.0788 -
val_loss: 0.0920
Epoch 75/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0784 -
val_loss: 0.0776
Epoch 76/100
115092/115092 [=====] - 17s 144us/step - loss: 0.0787 -
val_loss: 0.0939
Epoch 77/100
115092/115092 [=====] - 17s 147us/step - loss: 0.0783 -
val_loss: 0.0944
Epoch 78/100
115092/115092 [=====] - 16s 139us/step - loss: 0.0776 -
val_loss: 0.0852
Epoch 79/100
115092/115092 [=====] - 17s 147us/step - loss: 0.0777 -
val_loss: 0.0940
Epoch 80/100
115092/115092 [=====] - 17s 151us/step - loss: 0.0772 -
```

val\_loss: 0.0819  
Epoch 81/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0772 -  
val\_loss: 0.0717  
Epoch 82/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0768 -  
val\_loss: 0.1034  
Epoch 83/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0766 -  
val\_loss: 0.0871  
Epoch 84/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0765 -  
val\_loss: 0.0743  
Epoch 85/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0759 -  
val\_loss: 0.0854  
Epoch 86/100  
115092/115092 [=====] - 16s 138us/step - loss: 0.0753 -  
val\_loss: 0.0716  
Epoch 87/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0753 -  
val\_loss: 0.0804  
Epoch 88/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0754 -  
val\_loss: 0.0880  
Epoch 89/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0749 -  
val\_loss: 0.0889  
Epoch 90/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0746 -  
val\_loss: 0.0814  
Epoch 91/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0746 -  
val\_loss: 0.0799  
Epoch 92/100  
115092/115092 [=====] - 15s 134us/step - loss: 0.0742 -  
val\_loss: 0.0739  
Epoch 93/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0735 -  
val\_loss: 0.0780  
Epoch 94/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0735 -  
val\_loss: 0.0731  
Epoch 95/100  
115092/115092 [=====] - 16s 137us/step - loss: 0.0735 -  
val\_loss: 0.0914  
Epoch 96/100  
115092/115092 [=====] - 16s 137us/step - loss: 0.0735 -

```
val_loss: 0.0852
Epoch 97/100
115092/115092 [=====] - 16s 138us/step - loss: 0.0730 -
val_loss: 0.0790
Epoch 98/100
115092/115092 [=====] - 16s 137us/step - loss: 0.0725 -
val_loss: 0.0786
Epoch 99/100
115092/115092 [=====] - 16s 139us/step - loss: 0.0727 -
val_loss: 0.0780
Epoch 100/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0727 -
val_loss: 0.0880
```

```
[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 115092 samples, validate on 28773 samples

```
Epoch 1/100
115092/115092 [=====] - 16s 139us/step - loss: 0.0727 -
val_loss: 0.0755
Epoch 2/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0720 -
val_loss: 0.0659
Epoch 3/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0725 -
val_loss: 0.0786
Epoch 4/100
115092/115092 [=====] - 17s 146us/step - loss: 0.0718 -
val_loss: 0.0770
Epoch 5/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0719 -
val_loss: 0.0659
Epoch 6/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0718 -
val_loss: 0.0738
Epoch 7/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0715 -
val_loss: 0.0833
Epoch 8/100
115092/115092 [=====] - 16s 136us/step - loss: 0.0714 -
val_loss: 0.0682
Epoch 9/100
115092/115092 [=====] - 16s 136us/step - loss: 0.0712 -
```



```

val_loss: 0.0770
Epoch 10/100
115092/115092 [=====] - 17s 145us/step - loss: 0.0707 -
val_loss: 0.0658
Epoch 11/100
115092/115092 [=====] - 18s 153us/step - loss: 0.0712 -
val_loss: 0.0657
Epoch 12/100
115092/115092 [=====] - 18s 153us/step - loss: 0.0706 -
val_loss: 0.0877
Epoch 13/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0710 -
val_loss: 0.0706
Epoch 14/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0704 -
val_loss: 0.0815
Epoch 15/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0707 -
val_loss: 0.0800
Epoch 16/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0700 -
val_loss: 0.0781
Epoch 17/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0698 -
val_loss: 0.0713
Epoch 18/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0696 -
val_loss: 0.0776
Epoch 19/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0696 -
val_loss: 0.0718
Epoch 20/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0696 -
val_loss: 0.1008
Epoch 21/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0703 -
val_loss: 0.0745
Epoch 22/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0698 -
val_loss: 0.0753
Epoch 23/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0691 -
val_loss: 0.0699
Epoch 24/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0691 -
val_loss: 0.0790
Epoch 25/100
115092/115092 [=====] - 17s 146us/step - loss: 0.0693 -

```

val\_loss: 0.0781  
Epoch 26/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0692 -  
val\_loss: 0.0720  
Epoch 27/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0691 -  
val\_loss: 0.0818  
Epoch 28/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0692 -  
val\_loss: 0.0674  
Epoch 29/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0689 -  
val\_loss: 0.0828  
Epoch 30/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0684 -  
val\_loss: 0.0773  
Epoch 31/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0688 -  
val\_loss: 0.0681  
Epoch 32/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0685 -  
val\_loss: 0.0773  
Epoch 33/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0685 -  
val\_loss: 0.0786  
Epoch 34/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0683 -  
val\_loss: 0.0691  
Epoch 35/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0679 -  
val\_loss: 0.0753  
Epoch 36/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0686 -  
val\_loss: 0.0779  
Epoch 37/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0680 -  
val\_loss: 0.0764  
Epoch 38/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0678 -  
val\_loss: 0.0751  
Epoch 39/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0682 -  
val\_loss: 0.0707  
Epoch 40/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0679 -  
val\_loss: 0.0850  
Epoch 41/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0680 -

val\_loss: 0.0692  
Epoch 42/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0678 -  
val\_loss: 0.0691  
Epoch 43/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0681 -  
val\_loss: 0.0722  
Epoch 44/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0679 -  
val\_loss: 0.0851  
Epoch 45/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0676 -  
val\_loss: 0.0679  
Epoch 46/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0677 -  
val\_loss: 0.0751  
Epoch 47/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0681 -  
val\_loss: 0.0749  
Epoch 48/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0674 -  
val\_loss: 0.0715  
Epoch 49/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0674 -  
val\_loss: 0.0800  
Epoch 50/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0678 -  
val\_loss: 0.0692  
Epoch 51/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0675 -  
val\_loss: 0.0659  
Epoch 52/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0673 -  
val\_loss: 0.0714  
Epoch 53/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0671 -  
val\_loss: 0.0723  
Epoch 54/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0669 -  
val\_loss: 0.0799  
Epoch 55/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0673 -  
val\_loss: 0.0746  
Epoch 56/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0674 -  
val\_loss: 0.0755  
Epoch 57/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0669 -

```
val_loss: 0.0684
Epoch 58/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0671 -
val_loss: 0.0712
Epoch 59/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0671 -
val_loss: 0.0980
Epoch 60/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0681 -
val_loss: 0.0724
Epoch 61/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0664 -
val_loss: 0.0689
Epoch 62/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0666 -
val_loss: 0.0717
Epoch 63/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0666 -
val_loss: 0.0723
Epoch 64/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0665 -
val_loss: 0.0686
Epoch 65/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0665 -
val_loss: 0.0807
Epoch 66/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0668 -
val_loss: 0.0730
Epoch 67/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0659 -
val_loss: 0.0699
Epoch 68/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0662 -
val_loss: 0.0647
Epoch 69/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0663 -
val_loss: 0.0875
Epoch 70/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0662 -
val_loss: 0.0762
Epoch 71/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0659 -
val_loss: 0.0839
Epoch 72/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0663 -
val_loss: 0.0820
Epoch 73/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0667 -
```

val\_loss: 0.0857  
Epoch 74/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0665 -  
val\_loss: 0.0885  
Epoch 75/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0678 -  
val\_loss: 0.0728  
Epoch 76/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0660 -  
val\_loss: 0.0758  
Epoch 77/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0666 -  
val\_loss: 0.0700  
Epoch 78/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0662 -  
val\_loss: 0.0662  
Epoch 79/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0662 -  
val\_loss: 0.0756  
Epoch 80/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0658 -  
val\_loss: 0.0763  
Epoch 81/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0658 -  
val\_loss: 0.0742  
Epoch 82/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0659 -  
val\_loss: 0.0763  
Epoch 83/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0656 -  
val\_loss: 0.0716  
Epoch 84/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0662 -  
val\_loss: 0.1091  
Epoch 85/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0662 -  
val\_loss: 0.0720  
Epoch 86/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0661 -  
val\_loss: 0.0699  
Epoch 87/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0657 -  
val\_loss: 0.0800  
Epoch 88/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0660 -  
val\_loss: 0.0790  
Epoch 89/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0660 -

```

val_loss: 0.0766
Epoch 90/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0660 -
val_loss: 0.0741
Epoch 91/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0665 -
val_loss: 0.0719
Epoch 92/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0663 -
val_loss: 0.0667
Epoch 93/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0666 -
val_loss: 0.0730
Epoch 94/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0663 -
val_loss: 0.0763
Epoch 95/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0664 -
val_loss: 0.0751
Epoch 96/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0660 -
val_loss: 0.0761
Epoch 97/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0663 -
val_loss: 0.0723
Epoch 98/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0661 -
val_loss: 0.0738
Epoch 99/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0664 -
val_loss: 0.0674
Epoch 100/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0662 -
val_loss: 0.0724

```

```

[22]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 115092 samples, validate on 28773 samples
Epoch 1/100
115092/115092 [=====] - 17s 149us/step - loss: 0.0662 -
val_loss: 0.0662
Epoch 2/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0664 -

```

val\_loss: 0.0647  
Epoch 3/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0665 -  
val\_loss: 0.0848  
Epoch 4/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0664 -  
val\_loss: 0.0666  
Epoch 5/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0662 -  
val\_loss: 0.0698  
Epoch 6/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0663 -  
val\_loss: 0.0654  
Epoch 7/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0665 -  
val\_loss: 0.0749  
Epoch 8/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0657 -  
val\_loss: 0.0792  
Epoch 9/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0659 -  
val\_loss: 0.0680  
Epoch 10/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0661 -  
val\_loss: 0.0754  
Epoch 11/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0654 -  
val\_loss: 0.0657  
Epoch 12/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0658 -  
val\_loss: 0.0761  
Epoch 13/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0659 -  
val\_loss: 0.0725  
Epoch 14/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0657 -  
val\_loss: 0.0711  
Epoch 15/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0657 -  
val\_loss: 0.0703  
Epoch 16/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0658 -  
val\_loss: 0.0733  
Epoch 17/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0663 -  
val\_loss: 0.0803  
Epoch 18/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0661 -

```
val_loss: 0.0839
Epoch 19/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0659 -
val_loss: 0.0749
Epoch 20/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0650 -
val_loss: 0.0621
Epoch 21/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0654 -
val_loss: 0.0782
Epoch 22/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0657 -
val_loss: 0.0725
Epoch 23/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0651 -
val_loss: 0.0633
Epoch 24/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0654 -
val_loss: 0.0960
Epoch 25/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0646 -
val_loss: 0.0695
Epoch 26/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0647 -
val_loss: 0.0813
Epoch 27/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0653 -
val_loss: 0.0950
Epoch 28/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0658 -
val_loss: 0.0713
Epoch 29/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0642 -
val_loss: 0.0779
Epoch 30/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0650 -
val_loss: 0.0667
Epoch 31/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0646 -
val_loss: 0.0648
Epoch 32/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0648 -
val_loss: 0.0813
Epoch 33/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0652 -
val_loss: 0.0734
Epoch 34/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0649 -
```



```
val_loss: 0.0620
Epoch 35/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0649 -
val_loss: 0.0692
Epoch 36/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0648 -
val_loss: 0.0922
Epoch 37/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0649 -
val_loss: 0.0707
Epoch 38/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0648 -
val_loss: 0.0660
Epoch 39/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0644 -
val_loss: 0.0779
Epoch 40/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0641 -
val_loss: 0.0688
Epoch 41/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0647 -
val_loss: 0.0748
Epoch 42/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0651 -
val_loss: 0.0719
Epoch 43/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0646 -
val_loss: 0.0651
Epoch 44/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0645 -
val_loss: 0.0638
Epoch 45/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0646 -
val_loss: 0.0840
Epoch 46/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0646 -
val_loss: 0.0659
Epoch 47/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0644 -
val_loss: 0.0785
Epoch 48/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0647 -
val_loss: 0.0758
Epoch 49/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0643 -
val_loss: 0.0724
Epoch 50/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0644 -
```

val\_loss: 0.0696  
Epoch 51/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0645 -  
val\_loss: 0.0751  
Epoch 52/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0645 -  
val\_loss: 0.0777  
Epoch 53/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0645 -  
val\_loss: 0.0579  
Epoch 54/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0642 -  
val\_loss: 0.0730  
Epoch 55/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0643 -  
val\_loss: 0.0729  
Epoch 56/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0643 -  
val\_loss: 0.0599  
Epoch 57/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0645 -  
val\_loss: 0.0661  
Epoch 58/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0643 -  
val\_loss: 0.0649  
Epoch 59/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0645 -  
val\_loss: 0.0762  
Epoch 60/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0641 -  
val\_loss: 0.0634  
Epoch 61/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0639 -  
val\_loss: 0.0649  
Epoch 62/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0641 -  
val\_loss: 0.0636  
Epoch 63/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0638 -  
val\_loss: 0.0849  
Epoch 64/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0638 -  
val\_loss: 0.0658  
Epoch 65/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0643 -  
val\_loss: 0.0789  
Epoch 66/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0647 -

```
val_loss: 0.0846
Epoch 67/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0634 -
val_loss: 0.0661
Epoch 68/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0642 -
val_loss: 0.0784
Epoch 69/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0638 -
val_loss: 0.0753
Epoch 70/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0645 -
val_loss: 0.0755
Epoch 71/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0643 -
val_loss: 0.0540
Epoch 72/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0637 -
val_loss: 0.0709
Epoch 73/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0640 -
val_loss: 0.0779
Epoch 74/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0639 -
val_loss: 0.0666
Epoch 75/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0640 -
val_loss: 0.0778
Epoch 76/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0635 -
val_loss: 0.0688
Epoch 77/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0636 -
val_loss: 0.0704
Epoch 78/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0634 -
val_loss: 0.0636
Epoch 79/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0639 -
val_loss: 0.0781
Epoch 80/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0636 -
val_loss: 0.0579
Epoch 81/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0632 -
val_loss: 0.0871
Epoch 82/100
115092/115092 [=====] - 16s 143us/step - loss: 0.0635 -
```

val\_loss: 0.0635  
Epoch 83/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0647 -  
val\_loss: 0.0672  
Epoch 84/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0676 -  
val\_loss: 0.0718  
Epoch 85/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0683 -  
val\_loss: 0.0606  
Epoch 86/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0679 -  
val\_loss: 0.0653  
Epoch 87/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0680 -  
val\_loss: 0.0686  
Epoch 88/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0679 -  
val\_loss: 0.0797  
Epoch 89/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0679 -  
val\_loss: 0.0836  
Epoch 90/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0692 -  
val\_loss: 0.0804  
Epoch 91/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0675 -  
val\_loss: 0.0765  
Epoch 92/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0678 -  
val\_loss: 0.0776  
Epoch 93/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0680 -  
val\_loss: 0.0785  
Epoch 94/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0674 -  
val\_loss: 0.0651  
Epoch 95/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0677 -  
val\_loss: 0.0651  
Epoch 96/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0680 -  
val\_loss: 0.0665  
Epoch 97/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0681 -  
val\_loss: 0.0601  
Epoch 98/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0677 -

```
val_loss: 0.0711
Epoch 99/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0672 -
val_loss: 0.0821
Epoch 100/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0673 -
val_loss: 0.0752
```

```
[23]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[24]: Y_test = np.round(Y_test, 0)
```

```
[25]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))
```

```
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
```

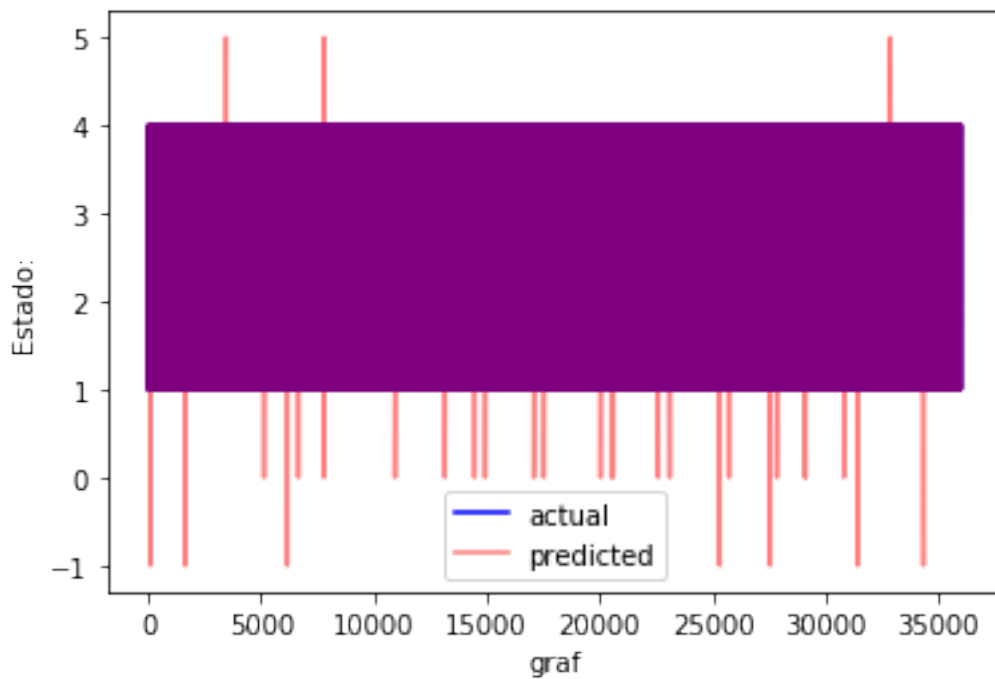
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[26]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9541467724414469

```
[27]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[28]: Y_val2 = np.array(Y_val.T)[0]  
Accu=Y_val2==Y_test  
accur=np.sum(Accu)  
accur/len(Y_val)
```

[28]: 0.9653293296633024

{}:

# Wrist\_elux5\_mae\_Adadel\_final

August 31, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```



```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```



```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```



```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0830 22:51:34.426502 17120 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 22:51:34.441463 17120 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 22:51:34.444489 17120 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 22:51:34.512310 17120 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0830 22:51:34.731726 17120 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 22:51:34.737670 17120 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is

deprecated. Please use `tf.compat.v1.assign` instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 20s 171us/step - loss: 0.5629 -  
val\_loss: 0.3969

Epoch 2/100

115092/115092 [=====] - 18s 157us/step - loss: 0.3315 -  
val\_loss: 0.3110

Epoch 3/100

115092/115092 [=====] - 18s 158us/step - loss: 0.2613 -  
val\_loss: 0.2899

Epoch 4/100

115092/115092 [=====] - 18s 159us/step - loss: 0.2206 -  
val\_loss: 0.2127

Epoch 5/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1829 -  
val\_loss: 0.1696

Epoch 6/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1569 -  
val\_loss: 0.1894

Epoch 7/100

115092/115092 [=====] - 18s 157us/step - loss: 0.1428 -  
val\_loss: 0.1326

Epoch 8/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1322 -  
val\_loss: 0.1323

Epoch 9/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1244 -  
val\_loss: 0.1215

Epoch 10/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1185 -  
val\_loss: 0.1247

Epoch 11/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1134 -  
val\_loss: 0.1225

Epoch 12/100

115092/115092 [=====] - 18s 157us/step - loss: 0.1086 -  
val\_loss: 0.1062

Epoch 13/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1059 -  
val\_loss: 0.0967

Epoch 14/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1022 -  
val\_loss: 0.1032

Epoch 15/100

115092/115092 [=====] - 18s 158us/step - loss: 0.0991 -

val\_loss: 0.1046  
Epoch 16/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0959 -  
val\_loss: 0.0932  
Epoch 17/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0943 -  
val\_loss: 0.1007  
Epoch 18/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0919 -  
val\_loss: 0.0844  
Epoch 19/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0899 -  
val\_loss: 0.0984  
Epoch 20/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0876 -  
val\_loss: 0.0970  
Epoch 21/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0869 -  
val\_loss: 0.0834  
Epoch 22/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0855 -  
val\_loss: 0.0897  
Epoch 23/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0836 -  
val\_loss: 0.0982  
Epoch 24/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0832 -  
val\_loss: 0.0945  
Epoch 25/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0822 -  
val\_loss: 0.0856  
Epoch 26/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0809 -  
val\_loss: 0.1015  
Epoch 27/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0804 -  
val\_loss: 0.0858  
Epoch 28/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0795 -  
val\_loss: 0.0951  
Epoch 29/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0787 -  
val\_loss: 0.0860  
Epoch 30/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0775 -  
val\_loss: 0.0863  
Epoch 31/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0769 -

```
val_loss: 0.0776
Epoch 32/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0760 -
val_loss: 0.0799
Epoch 33/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0749 -
val_loss: 0.0933
Epoch 34/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0743 -
val_loss: 0.0801
Epoch 35/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0741 -
val_loss: 0.0930
Epoch 36/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0728 -
val_loss: 0.0772
Epoch 37/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0726 -
val_loss: 0.0738
Epoch 38/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0719 -
val_loss: 0.0755
Epoch 39/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0716 -
val_loss: 0.0680
Epoch 40/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0708 -
val_loss: 0.0716
Epoch 41/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0701 -
val_loss: 0.0724
Epoch 42/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0696 -
val_loss: 0.0789
Epoch 43/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0698 -
val_loss: 0.0892
Epoch 44/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0691 -
val_loss: 0.0810
Epoch 45/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0693 -
val_loss: 0.0697
Epoch 46/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0686 -
val_loss: 0.0835
Epoch 47/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0678 -
```

val\_loss: 0.0854  
Epoch 48/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0676 -  
val\_loss: 0.0765  
Epoch 49/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0673 -  
val\_loss: 0.0762  
Epoch 50/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0669 -  
val\_loss: 0.0743  
Epoch 51/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0663 -  
val\_loss: 0.0709  
Epoch 52/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0663 -  
val\_loss: 0.0797  
Epoch 53/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0660 -  
val\_loss: 0.0837  
Epoch 54/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0656 -  
val\_loss: 0.0666  
Epoch 55/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0653 -  
val\_loss: 0.0606  
Epoch 56/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0649 -  
val\_loss: 0.0767  
Epoch 57/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0652 -  
val\_loss: 0.0636  
Epoch 58/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0651 -  
val\_loss: 0.0658  
Epoch 59/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0648 -  
val\_loss: 0.0853  
Epoch 60/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0644 -  
val\_loss: 0.0894  
Epoch 61/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0645 -  
val\_loss: 0.0799  
Epoch 62/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0644 -  
val\_loss: 0.0707  
Epoch 63/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0646 -

val\_loss: 0.0642  
Epoch 64/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0641 -  
val\_loss: 0.0676  
Epoch 65/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.0661  
Epoch 66/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.0724  
Epoch 67/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0639 -  
val\_loss: 0.0696  
Epoch 68/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.0721  
Epoch 69/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0626 -  
val\_loss: 0.0708  
Epoch 70/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0629 -  
val\_loss: 0.0707  
Epoch 71/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0628 -  
val\_loss: 0.0659  
Epoch 72/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0622 -  
val\_loss: 0.0653  
Epoch 73/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0617 -  
val\_loss: 0.0713  
Epoch 74/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0617 -  
val\_loss: 0.0676  
Epoch 75/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0620 -  
val\_loss: 0.0653  
Epoch 76/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0611 -  
val\_loss: 0.0642  
Epoch 77/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0619 -  
val\_loss: 0.0602  
Epoch 78/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0613 -  
val\_loss: 0.0712  
Epoch 79/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0609 -

val\_loss: 0.0685  
Epoch 80/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0618 -  
val\_loss: 0.0664  
Epoch 81/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0611 -  
val\_loss: 0.0594  
Epoch 82/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0601 -  
val\_loss: 0.0631  
Epoch 83/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0600 -  
val\_loss: 0.0553  
Epoch 84/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0591 -  
val\_loss: 0.0569  
Epoch 85/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0589 -  
val\_loss: 0.0620  
Epoch 86/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0586 -  
val\_loss: 0.0585  
Epoch 87/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0585 -  
val\_loss: 0.0600  
Epoch 88/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0579 -  
val\_loss: 0.0591  
Epoch 89/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0574 -  
val\_loss: 0.0576  
Epoch 90/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0565 -  
val\_loss: 0.0704  
Epoch 91/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0566 -  
val\_loss: 0.0640  
Epoch 92/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0570 -  
val\_loss: 0.0582  
Epoch 93/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0567 -  
val\_loss: 0.0584  
Epoch 94/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0570 -  
val\_loss: 0.0573  
Epoch 95/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0557 -

```
val_loss: 0.0597
Epoch 96/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0564 -
val_loss: 0.0705
Epoch 97/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0574 -
val_loss: 0.0580
Epoch 98/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0564 -
val_loss: 0.0592
Epoch 99/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0556 -
val_loss: 0.0544
Epoch 100/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0561 -
val_loss: 0.0568
```

```
[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 115092 samples, validate on 28773 samples

```
Epoch 1/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0569 -
val_loss: 0.0709
Epoch 2/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0566 -
val_loss: 0.0691
Epoch 3/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0558 -
val_loss: 0.0654
Epoch 4/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0561 -
val_loss: 0.0601
Epoch 5/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0569 -
val_loss: 0.0776
Epoch 6/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0554 -
val_loss: 0.0708
Epoch 7/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0545 -
val_loss: 0.0543
Epoch 8/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0552 -
```



val\_loss: 0.0540  
Epoch 9/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0559 -  
val\_loss: 0.0591  
Epoch 10/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0556 -  
val\_loss: 0.0504  
Epoch 11/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0559 -  
val\_loss: 0.0630  
Epoch 12/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0556 -  
val\_loss: 0.0540  
Epoch 13/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0553 -  
val\_loss: 0.0629  
Epoch 14/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0559 -  
val\_loss: 0.0680  
Epoch 15/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0555 -  
val\_loss: 0.0677  
Epoch 16/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0553 -  
val\_loss: 0.0539  
Epoch 17/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0556 -  
val\_loss: 0.0599  
Epoch 18/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0562 -  
val\_loss: 0.0547  
Epoch 19/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0556 -  
val\_loss: 0.0749  
Epoch 20/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0559 -  
val\_loss: 0.0737  
Epoch 21/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0555 -  
val\_loss: 0.0759  
Epoch 22/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0573 -  
val\_loss: 0.0695  
Epoch 23/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0574 -  
val\_loss: 0.0621  
Epoch 24/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0570 -

val\_loss: 0.0491  
Epoch 25/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0565 -  
val\_loss: 0.0705  
Epoch 26/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0571 -  
val\_loss: 0.0560  
Epoch 27/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0574 -  
val\_loss: 0.0605  
Epoch 28/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0575 -  
val\_loss: 0.0553  
Epoch 29/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0578 -  
val\_loss: 0.0779  
Epoch 30/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0583 -  
val\_loss: 0.0634  
Epoch 31/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0592 -  
val\_loss: 0.0540  
Epoch 32/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0591 -  
val\_loss: 0.0577  
Epoch 33/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0595 -  
val\_loss: 0.0611  
Epoch 34/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0580 -  
val\_loss: 0.0574  
Epoch 35/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0579 -  
val\_loss: 0.0625  
Epoch 36/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0582 -  
val\_loss: 0.0577  
Epoch 37/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0576 -  
val\_loss: 0.0534  
Epoch 38/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0591 -  
val\_loss: 0.0596  
Epoch 39/100  
115092/115092 [=====] - 18s 153us/step - loss: 0.0580 -  
val\_loss: 0.0701  
Epoch 40/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0596 -

val\_loss: 0.0536  
Epoch 41/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0589 -  
val\_loss: 0.0558  
Epoch 42/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0589 -  
val\_loss: 0.0620  
Epoch 43/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0585 -  
val\_loss: 0.0697  
Epoch 44/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0587 -  
val\_loss: 0.0554  
Epoch 45/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0591 -  
val\_loss: 0.0573  
Epoch 46/100  
115092/115092 [=====] - 20s 171us/step - loss: 0.0579 -  
val\_loss: 0.0597  
Epoch 47/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0581 -  
val\_loss: 0.0777  
Epoch 48/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0597 -  
val\_loss: 0.0685  
Epoch 49/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0585 -  
val\_loss: 0.0632  
Epoch 50/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0588 -  
val\_loss: 0.0586  
Epoch 51/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0596 -  
val\_loss: 0.0915  
Epoch 52/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0587 -  
val\_loss: 0.0656  
Epoch 53/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0599 -  
val\_loss: 0.0749  
Epoch 54/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0599 -  
val\_loss: 0.0656  
Epoch 55/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0592 -  
val\_loss: 0.0671  
Epoch 56/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0595 -

val\_loss: 0.0707  
Epoch 57/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0596 -  
val\_loss: 0.0692  
Epoch 58/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0602 -  
val\_loss: 0.0717  
Epoch 59/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0606 -  
val\_loss: 0.0563  
Epoch 60/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0649 -  
val\_loss: 0.0803  
Epoch 61/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0613 -  
val\_loss: 0.0759  
Epoch 62/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0615 -  
val\_loss: 0.0520  
Epoch 63/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0604 -  
val\_loss: 0.0754  
Epoch 64/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0618 -  
val\_loss: 0.0565  
Epoch 65/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0613 -  
val\_loss: 0.0574  
Epoch 66/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0621 -  
val\_loss: 0.0754  
Epoch 67/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0634 -  
val\_loss: 0.0723  
Epoch 68/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0628 -  
val\_loss: 0.0612  
Epoch 69/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0635 -  
val\_loss: 0.0680  
Epoch 70/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0626 -  
val\_loss: 0.0780  
Epoch 71/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0622 -  
val\_loss: 0.0535  
Epoch 72/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0636 -

val\_loss: 0.1095  
Epoch 73/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0646 -  
val\_loss: 0.0662  
Epoch 74/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.0753  
Epoch 75/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0638 -  
val\_loss: 0.0591  
Epoch 76/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0652 -  
val\_loss: 0.0593  
Epoch 77/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0643 -  
val\_loss: 0.0672  
Epoch 78/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0647 -  
val\_loss: 0.0684  
Epoch 79/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0661 -  
val\_loss: 0.0624  
Epoch 80/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0668 -  
val\_loss: 0.0630  
Epoch 81/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0670 -  
val\_loss: 0.0635  
Epoch 82/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0685 -  
val\_loss: 0.0704  
Epoch 83/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0679 -  
val\_loss: 0.0650  
Epoch 84/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0679 -  
val\_loss: 0.0724  
Epoch 85/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0685 -  
val\_loss: 0.0625  
Epoch 86/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0709 -  
val\_loss: 0.0824  
Epoch 87/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0710 -  
val\_loss: 0.0640  
Epoch 88/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0688 -

```

val_loss: 0.0977
Epoch 89/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0696 -
val_loss: 0.0748
Epoch 90/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0685 -
val_loss: 0.0641
Epoch 91/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0680 -
val_loss: 0.0624
Epoch 92/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0691 -
val_loss: 0.0696
Epoch 93/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0693 -
val_loss: 0.0590
Epoch 94/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0684 -
val_loss: 0.0657
Epoch 95/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0667 -
val_loss: 0.0588
Epoch 96/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0687 -
val_loss: 0.0709
Epoch 97/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0676 -
val_loss: 0.0742
Epoch 98/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0659 -
val_loss: 0.0608
Epoch 99/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0644 -
val_loss: 0.0690
Epoch 100/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0628 -
val_loss: 0.0744

```

```

[22]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 115092 samples, validate on 28773 samples
Epoch 1/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0622 -

```

```
val_loss: 0.0584
Epoch 2/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0623 -
val_loss: 0.0598
Epoch 3/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0614 -
val_loss: 0.0793
Epoch 4/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0621 -
val_loss: 0.0586
Epoch 5/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0597 -
val_loss: 0.0719
Epoch 6/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0609 -
val_loss: 0.0579
Epoch 7/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0606 -
val_loss: 0.0585
Epoch 8/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0610 -
val_loss: 0.0759
Epoch 9/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0609 -
val_loss: 0.0531
Epoch 10/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0601 -
val_loss: 0.0642
Epoch 11/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0605 -
val_loss: 0.0702
Epoch 12/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0619 -
val_loss: 0.0602
Epoch 13/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0616 -
val_loss: 0.0649
Epoch 14/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0617 -
val_loss: 0.0651
Epoch 15/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0609 -
val_loss: 0.0554
Epoch 16/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0618 -
val_loss: 0.0619
Epoch 17/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0604 -
```

```
val_loss: 0.0718
Epoch 18/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0613 -
val_loss: 0.0547
Epoch 19/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0612 -
val_loss: 0.0829
Epoch 20/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0610 -
val_loss: 0.0641
Epoch 21/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0613 -
val_loss: 0.0602
Epoch 22/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0613 -
val_loss: 0.0793
Epoch 23/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0610 -
val_loss: 0.0654
Epoch 24/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0610 -
val_loss: 0.0536
Epoch 25/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0612 -
val_loss: 0.0649
Epoch 26/100
115092/115092 [=====] - 18s 154us/step - loss: 0.0611 -
val_loss: 0.0678
Epoch 27/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0615 -
val_loss: 0.0720
Epoch 28/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0619 -
val_loss: 0.0651
Epoch 29/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0631 -
val_loss: 0.0916
Epoch 30/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0628 -
val_loss: 0.0565
Epoch 31/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0623 -
val_loss: 0.0706
Epoch 32/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0637 -
val_loss: 0.0776
Epoch 33/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0630 -
```



val\_loss: 0.0728  
Epoch 34/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0620 -  
val\_loss: 0.0669  
Epoch 35/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0627 -  
val\_loss: 0.0622  
Epoch 36/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0633 -  
val\_loss: 0.0769  
Epoch 37/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0643 -  
val\_loss: 0.0680  
Epoch 38/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0643 -  
val\_loss: 0.0722  
Epoch 39/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0656 -  
val\_loss: 0.0717  
Epoch 40/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0643 -  
val\_loss: 0.0761  
Epoch 41/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0657 -  
val\_loss: 0.0587  
Epoch 42/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0644 -  
val\_loss: 0.0707  
Epoch 43/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0630 -  
val\_loss: 0.0678  
Epoch 44/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0623 -  
val\_loss: 0.0615  
Epoch 45/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0617 -  
val\_loss: 0.0882  
Epoch 46/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0625 -  
val\_loss: 0.0797  
Epoch 47/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0623 -  
val\_loss: 0.0528  
Epoch 48/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0623 -  
val\_loss: 0.0647  
Epoch 49/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0628 -

val\_loss: 0.0685  
Epoch 50/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.0569  
Epoch 51/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0624 -  
val\_loss: 0.0644  
Epoch 52/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0634 -  
val\_loss: 0.0712  
Epoch 53/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.0781  
Epoch 54/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0626 -  
val\_loss: 0.0586  
Epoch 55/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0623 -  
val\_loss: 0.0685  
Epoch 56/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0627 -  
val\_loss: 0.0706  
Epoch 57/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0634 -  
val\_loss: 0.0557  
Epoch 58/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0628 -  
val\_loss: 0.0715  
Epoch 59/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0632 -  
val\_loss: 0.0631  
Epoch 60/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0629 -  
val\_loss: 0.0556  
Epoch 61/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0628 -  
val\_loss: 0.0673  
Epoch 62/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0622 -  
val\_loss: 0.0668  
Epoch 63/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0634 -  
val\_loss: 0.0490  
Epoch 64/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0633 -  
val\_loss: 0.0520  
Epoch 65/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0635 -

val\_loss: 0.0686  
Epoch 66/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0631 -  
val\_loss: 0.0618  
Epoch 67/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0624 -  
val\_loss: 0.0618  
Epoch 68/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0632 -  
val\_loss: 0.0662  
Epoch 69/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0639 -  
val\_loss: 0.1032  
Epoch 70/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0632 -  
val\_loss: 0.0737  
Epoch 71/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0633 -  
val\_loss: 0.0617  
Epoch 72/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0653 -  
val\_loss: 0.0673  
Epoch 73/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0632 -  
val\_loss: 0.0663  
Epoch 74/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0619 -  
val\_loss: 0.0771  
Epoch 75/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0638 -  
val\_loss: 0.0676  
Epoch 76/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0641 -  
val\_loss: 0.0677  
Epoch 77/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0653 -  
val\_loss: 0.0725  
Epoch 78/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0644 -  
val\_loss: 0.0919  
Epoch 79/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0637 -  
val\_loss: 0.0586  
Epoch 80/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0643 -  
val\_loss: 0.0725  
Epoch 81/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0639 -

val\_loss: 0.0594  
Epoch 82/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0647 -  
val\_loss: 0.0603  
Epoch 83/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0637 -  
val\_loss: 0.0787  
Epoch 84/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0647 -  
val\_loss: 0.0715  
Epoch 85/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0654 -  
val\_loss: 0.0559  
Epoch 86/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0662 -  
val\_loss: 0.0671  
Epoch 87/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0649 -  
val\_loss: 0.0600  
Epoch 88/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0666 -  
val\_loss: 0.0629  
Epoch 89/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0662 -  
val\_loss: 0.0666  
Epoch 90/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0653 -  
val\_loss: 0.0658  
Epoch 91/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0667 -  
val\_loss: 0.0631  
Epoch 92/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0674 -  
val\_loss: 0.0673  
Epoch 93/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0661 -  
val\_loss: 0.0660  
Epoch 94/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0652 -  
val\_loss: 0.0785  
Epoch 95/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0665 -  
val\_loss: 0.0691  
Epoch 96/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0676 -  
val\_loss: 0.0784  
Epoch 97/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0670 -

```

val_loss: 0.0623
Epoch 98/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0681 -
val_loss: 0.0660
Epoch 99/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0669 -
val_loss: 0.0861
Epoch 100/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0664 -
val_loss: 0.0569

```

```
[23]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[24]: Y_test = np.round(Y_test, 0)
```

```
[25]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:2.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 4., predicted:4.

```

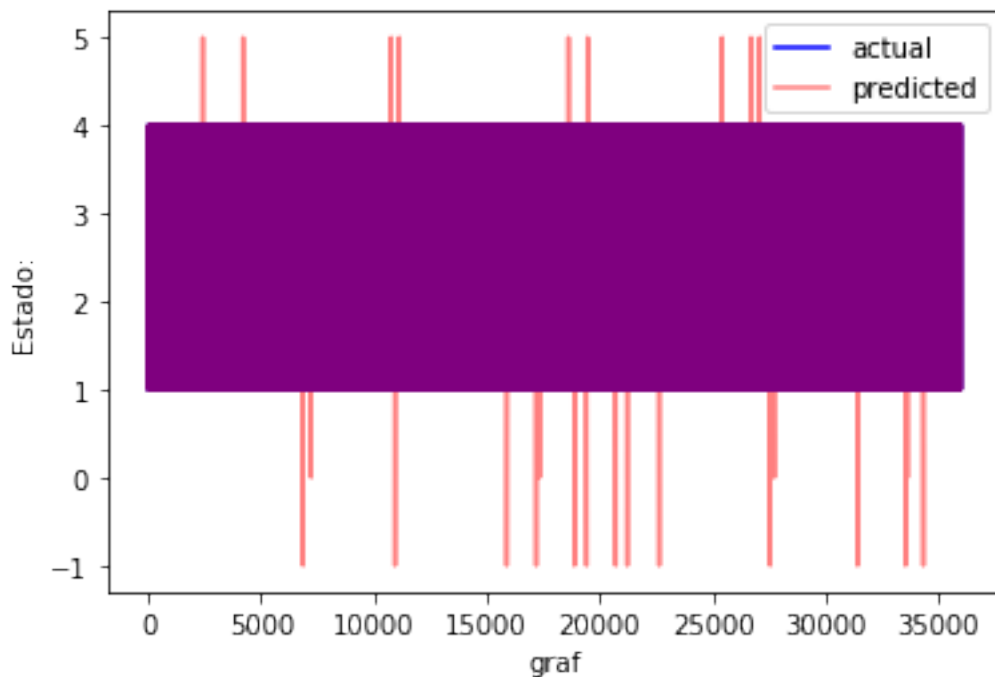
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[26]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9516759810555495

```
[27]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[28]: Y_val2 = np.array(Y_val.T)[0]  
Accu=Y_val2==Y_test  
accur=np.sum(Accu)
```

```
accur/len(Y_val)
```

```
[28]: 0.972836210971168
```

```
[ ]:
```

# Wrist\_elux7\_mae\_Adadel\_final

August 31, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```



```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```



```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```



```

Dense(60),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(30),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0831 00:46:19.774099 23100 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0831 00:46:19.787102 23100 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0831 00:46:19.792051 23100 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0831 00:46:19.878854 23100 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0831 00:46:20.109243 23100 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0831 00:46:20.114234 23100 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 23s 198us/step - loss: 0.5183 -  
val\_loss: 0.4381

Epoch 2/100

115092/115092 [=====] - 22s 191us/step - loss: 0.2869 -  
val\_loss: 0.2696

Epoch 3/100

115092/115092 [=====] - 22s 193us/step - loss: 0.2129 -  
val\_loss: 0.2185

Epoch 4/100

115092/115092 [=====] - 22s 193us/step - loss: 0.1772 -  
val\_loss: 0.1802

Epoch 5/100

115092/115092 [=====] - 22s 193us/step - loss: 0.1586 -  
val\_loss: 0.1495

Epoch 6/100

115092/115092 [=====] - 22s 193us/step - loss: 0.1457 -  
val\_loss: 0.1383

Epoch 7/100

115092/115092 [=====] - 22s 192us/step - loss: 0.1347 -  
val\_loss: 0.1748

Epoch 8/100

115092/115092 [=====] - 22s 193us/step - loss: 0.1256 -  
val\_loss: 0.1191

Epoch 9/100

115092/115092 [=====] - 22s 192us/step - loss: 0.1188 -  
val\_loss: 0.1282

Epoch 10/100

115092/115092 [=====] - 22s 191us/step - loss: 0.1119 -  
val\_loss: 0.1088

Epoch 11/100

115092/115092 [=====] - 22s 193us/step - loss: 0.1081 -  
val\_loss: 0.1141

Epoch 12/100

115092/115092 [=====] - 22s 192us/step - loss: 0.1041 -  
val\_loss: 0.1042

Epoch 13/100

115092/115092 [=====] - 22s 192us/step - loss: 0.1008 -  
val\_loss: 0.0996

Epoch 14/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0977 -  
val\_loss: 0.0960  
Epoch 15/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0960 -  
val\_loss: 0.0977  
Epoch 16/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0918 -  
val\_loss: 0.0951  
Epoch 17/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0898 -  
val\_loss: 0.0944  
Epoch 18/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0875 -  
val\_loss: 0.0898  
Epoch 19/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0858 -  
val\_loss: 0.0973  
Epoch 20/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0844 -  
val\_loss: 0.0989  
Epoch 21/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0832 -  
val\_loss: 0.0805  
Epoch 22/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0802 -  
val\_loss: 0.0866  
Epoch 23/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0801 -  
val\_loss: 0.1035  
Epoch 24/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0784 -  
val\_loss: 0.0833  
Epoch 25/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0776 -  
val\_loss: 0.0740  
Epoch 26/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0758 -  
val\_loss: 0.0776  
Epoch 27/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0750 -  
val\_loss: 0.0778  
Epoch 28/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0740 -  
val\_loss: 0.0714  
Epoch 29/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0734 -  
val\_loss: 0.0677  
Epoch 30/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0722 -  
val\_loss: 0.0755  
Epoch 31/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0724 -  
val\_loss: 0.0715  
Epoch 32/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0721 -  
val\_loss: 0.0683  
Epoch 33/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0707 -  
val\_loss: 0.0714  
Epoch 34/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0699 -  
val\_loss: 0.0687  
Epoch 35/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0697 -  
val\_loss: 0.0747  
Epoch 36/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0696 -  
val\_loss: 0.0877  
Epoch 37/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0674 -  
val\_loss: 0.0756  
Epoch 38/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0673 -  
val\_loss: 0.0876  
Epoch 39/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0675 -  
val\_loss: 0.0631  
Epoch 40/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0667 -  
val\_loss: 0.0614  
Epoch 41/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0668 -  
val\_loss: 0.0824  
Epoch 42/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0649 -  
val\_loss: 0.0661  
Epoch 43/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0654 -  
val\_loss: 0.0787  
Epoch 44/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0649 -  
val\_loss: 0.0639  
Epoch 45/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0654 -  
val\_loss: 0.0677  
Epoch 46/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0634 -  
val\_loss: 0.0656  
Epoch 47/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0645 -  
val\_loss: 0.0629  
Epoch 48/100  
115092/115092 [=====] - 22s 195us/step - loss: 0.0635 -  
val\_loss: 0.0674  
Epoch 49/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0628 -  
val\_loss: 0.0792  
Epoch 50/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0626 -  
val\_loss: 0.0760  
Epoch 51/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0636 -  
val\_loss: 0.0686  
Epoch 52/100  
115092/115092 [=====] - 23s 201us/step - loss: 0.0628 -  
val\_loss: 0.0622  
Epoch 53/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0622 -  
val\_loss: 0.0691  
Epoch 54/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0620 -  
val\_loss: 0.0633  
Epoch 55/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0619 -  
val\_loss: 0.0662  
Epoch 56/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0619 -  
val\_loss: 0.0612  
Epoch 57/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0622 -  
val\_loss: 0.0691  
Epoch 58/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0613 -  
val\_loss: 0.0628  
Epoch 59/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0611 -  
val\_loss: 0.0692  
Epoch 60/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0606 -  
val\_loss: 0.0506  
Epoch 61/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0590 -  
val\_loss: 0.0532  
Epoch 62/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0593 -  
val\_loss: 0.0498  
Epoch 63/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0577 -  
val\_loss: 0.0592  
Epoch 64/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0583 -  
val\_loss: 0.0627  
Epoch 65/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0577 -  
val\_loss: 0.0554  
Epoch 66/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0579 -  
val\_loss: 0.0701  
Epoch 67/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0578 -  
val\_loss: 0.0495  
Epoch 68/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0568 -  
val\_loss: 0.0721  
Epoch 69/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0570 -  
val\_loss: 0.0638  
Epoch 70/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0564 -  
val\_loss: 0.0488  
Epoch 71/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0551 -  
val\_loss: 0.0616  
Epoch 72/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0550 -  
val\_loss: 0.0628  
Epoch 73/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0546 -  
val\_loss: 0.0740  
Epoch 74/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0552 -  
val\_loss: 0.0514  
Epoch 75/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0547 -  
val\_loss: 0.0717  
Epoch 76/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0549 -  
val\_loss: 0.0581  
Epoch 77/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0542 -  
val\_loss: 0.0584  
Epoch 78/100

115092/115092 [=====] - 22s 190us/step - loss: 0.0540 -  
val\_loss: 0.0552  
Epoch 79/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0539 -  
val\_loss: 0.0490  
Epoch 80/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0536 -  
val\_loss: 0.0548  
Epoch 81/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0554 -  
val\_loss: 0.0814  
Epoch 82/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0531 -  
val\_loss: 0.0466  
Epoch 83/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0523 -  
val\_loss: 0.0554  
Epoch 84/100  
115092/115092 [=====] - 22s 195us/step - loss: 0.0523 -  
val\_loss: 0.0667  
Epoch 85/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0530 -  
val\_loss: 0.0490  
Epoch 86/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0527 -  
val\_loss: 0.0430  
Epoch 87/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0518 -  
val\_loss: 0.0628  
Epoch 88/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0519 -  
val\_loss: 0.0573  
Epoch 89/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0515 -  
val\_loss: 0.0787  
Epoch 90/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0523 -  
val\_loss: 0.0501  
Epoch 91/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0537 -  
val\_loss: 0.0658  
Epoch 92/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0535 -  
val\_loss: 0.0506  
Epoch 93/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0533 -  
val\_loss: 0.0442  
Epoch 94/100

```

115092/115092 [=====] - 22s 192us/step - loss: 0.0526 -
val_loss: 0.0538
Epoch 95/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0524 -
val_loss: 0.0548
Epoch 96/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0525 -
val_loss: 0.0408
Epoch 97/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0534 -
val_loss: 0.0519
Epoch 98/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0531 -
val_loss: 0.0427
Epoch 99/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0533 -
val_loss: 0.0569
Epoch 100/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0538 -
val_loss: 0.0492

```

```

[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 115092 samples, validate on 28773 samples
Epoch 1/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0540 -
val_loss: 0.0414
Epoch 2/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0531 -
val_loss: 0.0520
Epoch 3/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0537 -
val_loss: 0.0562
Epoch 4/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0521 -
val_loss: 0.0743
Epoch 5/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0519 -
val_loss: 0.0530
Epoch 6/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0511 -
val_loss: 0.0559
Epoch 7/100

```



115092/115092 [=====] - 22s 191us/step - loss: 0.0516 -  
val\_loss: 0.0486  
Epoch 8/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0521 -  
val\_loss: 0.0679  
Epoch 9/100  
115092/115092 [=====] - 22s 195us/step - loss: 0.0520 -  
val\_loss: 0.0599  
Epoch 10/100  
115092/115092 [=====] - 22s 195us/step - loss: 0.0529 -  
val\_loss: 0.0803  
Epoch 11/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0526 -  
val\_loss: 0.0646  
Epoch 12/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0520 -  
val\_loss: 0.0553  
Epoch 13/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0538 -  
val\_loss: 0.0447  
Epoch 14/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0529 -  
val\_loss: 0.0504  
Epoch 15/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0536 -  
val\_loss: 0.0406  
Epoch 16/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0543 -  
val\_loss: 0.0481  
Epoch 17/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0530 -  
val\_loss: 0.0551  
Epoch 18/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0537 -  
val\_loss: 0.0534  
Epoch 19/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0525 -  
val\_loss: 0.0501  
Epoch 20/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0537 -  
val\_loss: 0.0705  
Epoch 21/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0533 -  
val\_loss: 0.0525  
Epoch 22/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0534 -  
val\_loss: 0.0500  
Epoch 23/100

115092/115092 [=====] - 22s 193us/step - loss: 0.0543 -  
val\_loss: 0.0533  
Epoch 24/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0551 -  
val\_loss: 0.0579  
Epoch 25/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0547 -  
val\_loss: 0.0514  
Epoch 26/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0583 -  
val\_loss: 0.0657  
Epoch 27/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0567 -  
val\_loss: 0.0763  
Epoch 28/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0555 -  
val\_loss: 0.0633  
Epoch 29/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0592 -  
val\_loss: 0.0685  
Epoch 30/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0620 -  
val\_loss: 0.0708  
Epoch 31/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0623 -  
val\_loss: 0.0806  
Epoch 32/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0597 -  
val\_loss: 0.0523  
Epoch 33/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0613 -  
val\_loss: 0.0626  
Epoch 34/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0606 -  
val\_loss: 0.0625  
Epoch 35/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0620 -  
val\_loss: 0.0602  
Epoch 36/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0633 -  
val\_loss: 0.0739  
Epoch 37/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0627 -  
val\_loss: 0.0572  
Epoch 38/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0671 -  
val\_loss: 0.0733  
Epoch 39/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0677 -  
val\_loss: 0.0644  
Epoch 40/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0664 -  
val\_loss: 0.0594  
Epoch 41/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0663 -  
val\_loss: 0.0612  
Epoch 42/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0658 -  
val\_loss: 0.0685  
Epoch 43/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0662 -  
val\_loss: 0.0749  
Epoch 44/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0642 -  
val\_loss: 0.0772  
Epoch 45/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0657 -  
val\_loss: 0.0909  
Epoch 46/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0667 -  
val\_loss: 0.0570  
Epoch 47/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0663 -  
val\_loss: 0.0519  
Epoch 48/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0649 -  
val\_loss: 0.0745  
Epoch 49/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0650 -  
val\_loss: 0.0917  
Epoch 50/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0690 -  
val\_loss: 0.0578  
Epoch 51/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0782 -  
val\_loss: 0.0890  
Epoch 52/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0779 -  
val\_loss: 0.0705  
Epoch 53/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0802 -  
val\_loss: 0.0758  
Epoch 54/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0837 -  
val\_loss: 0.0879  
Epoch 55/100

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115092/115092 [=====] - 22s 192us/step - loss: 0.0916 -
val_loss: 0.0964
Epoch 56/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0896 -
val_loss: 0.1102
Epoch 57/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0786 -
val_loss: 0.0844
Epoch 58/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0796 -
val_loss: 0.0861
Epoch 59/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0768 -
val_loss: 0.0698
Epoch 60/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0770 -
val_loss: 0.0848
Epoch 61/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0760 -
val_loss: 0.0728
Epoch 62/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0763 -
val_loss: 0.0796
Epoch 63/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0790 -
val_loss: 0.1093
Epoch 64/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0752 -
val_loss: 0.0744
Epoch 65/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0770 -
val_loss: 0.0781
Epoch 66/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0787 -
val_loss: 0.0919
Epoch 67/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0787 -
val_loss: 0.0853
Epoch 68/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0801 -
val_loss: 0.0589
Epoch 69/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0775 -
val_loss: 0.0626
Epoch 70/100
115092/115092 [=====] - 22s 188us/step - loss: 0.0797 -
val_loss: 0.0960
Epoch 71/100

```

115092/115092 [=====] - 22s 192us/step - loss: 0.0807 -  
val\_loss: 0.0732  
Epoch 72/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0812 -  
val\_loss: 0.0786  
Epoch 73/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0779 -  
val\_loss: 0.0965  
Epoch 74/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0822 -  
val\_loss: 0.1047  
Epoch 75/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0813 -  
val\_loss: 0.0824  
Epoch 76/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0827 -  
val\_loss: 0.1222  
Epoch 77/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0830 -  
val\_loss: 0.0840  
Epoch 78/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0862 -  
val\_loss: 0.0817  
Epoch 79/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0866 -  
val\_loss: 0.1006  
Epoch 80/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0817 -  
val\_loss: 0.0875  
Epoch 81/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0796 -  
val\_loss: 0.0893  
Epoch 82/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0791 -  
val\_loss: 0.0991  
Epoch 83/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0782 -  
val\_loss: 0.1013  
Epoch 84/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0803 -  
val\_loss: 0.0949  
Epoch 85/100  
115092/115092 [=====] - 22s 195us/step - loss: 0.0810 -  
val\_loss: 0.0896  
Epoch 86/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0804 -  
val\_loss: 0.0693  
Epoch 87/100

```

115092/115092 [=====] - 22s 188us/step - loss: 0.0765 -
val_loss: 0.0856
Epoch 88/100
115092/115092 [=====] - 22s 188us/step - loss: 0.0773 -
val_loss: 0.0886
Epoch 89/100
115092/115092 [=====] - 22s 187us/step - loss: 0.0747 -
val_loss: 0.0846
Epoch 90/100
115092/115092 [=====] - 22s 188us/step - loss: 0.0751 -
val_loss: 0.0798
Epoch 91/100
115092/115092 [=====] - 22s 188us/step - loss: 0.0761 -
val_loss: 0.0589
Epoch 92/100
115092/115092 [=====] - 22s 188us/step - loss: 0.0771 -
val_loss: 0.0972
Epoch 93/100
115092/115092 [=====] - 22s 188us/step - loss: 0.0752 -
val_loss: 0.0732
Epoch 94/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0740 -
val_loss: 0.0742
Epoch 95/100
115092/115092 [=====] - 23s 201us/step - loss: 0.0724 -
val_loss: 0.0756
Epoch 96/100
115092/115092 [=====] - 23s 196us/step - loss: 0.0730 -
val_loss: 0.0868
Epoch 97/100
115092/115092 [=====] - 24s 205us/step - loss: 0.0719 -
val_loss: 0.0725
Epoch 98/100
115092/115092 [=====] - 24s 206us/step - loss: 0.0732 -
val_loss: 0.0841
Epoch 99/100
115092/115092 [=====] - 23s 203us/step - loss: 0.0751 -
val_loss: 0.0688
Epoch 100/100
115092/115092 [=====] - 23s 202us/step - loss: 0.0760 -
val_loss: 0.0699

```

```

[22]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 22s 195us/step - loss: 0.0727 -  
val\_loss: 0.0812

Epoch 2/100

115092/115092 [=====] - 22s 195us/step - loss: 0.0737 -  
val\_loss: 0.1181

Epoch 3/100

115092/115092 [=====] - 22s 194us/step - loss: 0.0764 -  
val\_loss: 0.0860

Epoch 4/100

115092/115092 [=====] - 22s 194us/step - loss: 0.0739 -  
val\_loss: 0.0678

Epoch 5/100

115092/115092 [=====] - 22s 195us/step - loss: 0.0739 -  
val\_loss: 0.0711

Epoch 6/100

115092/115092 [=====] - 23s 199us/step - loss: 0.0722 -  
val\_loss: 0.0813

Epoch 7/100

115092/115092 [=====] - 23s 200us/step - loss: 0.0719 -  
val\_loss: 0.0804

Epoch 8/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0720 -  
val\_loss: 0.0655

Epoch 9/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0742 -  
val\_loss: 0.0601

Epoch 10/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0737 -  
val\_loss: 0.0818

Epoch 11/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0756 -  
val\_loss: 0.0926

Epoch 12/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0758 -  
val\_loss: 0.0714

Epoch 13/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0713 -  
val\_loss: 0.0701

Epoch 14/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0693 -  
val\_loss: 0.0711

Epoch 15/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0687 -  
val\_loss: 0.0642

Epoch 16/100

115092/115092 [=====] - 23s 196us/step - loss: 0.0703 -

val\_loss: 0.0780  
Epoch 17/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0701 -  
val\_loss: 0.0735  
Epoch 18/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0695 -  
val\_loss: 0.0585  
Epoch 19/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0717 -  
val\_loss: 0.0697  
Epoch 20/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0707 -  
val\_loss: 0.0789  
Epoch 21/100  
115092/115092 [=====] - 22s 195us/step - loss: 0.0733 -  
val\_loss: 0.1511  
Epoch 22/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0721 -  
val\_loss: 0.0790  
Epoch 23/100  
115092/115092 [=====] - 23s 200us/step - loss: 0.0709 -  
val\_loss: 0.0829  
Epoch 24/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0707 -  
val\_loss: 0.0685  
Epoch 25/100  
115092/115092 [=====] - 23s 200us/step - loss: 0.0716 -  
val\_loss: 0.0736  
Epoch 26/100  
115092/115092 [=====] - 23s 200us/step - loss: 0.0721 -  
val\_loss: 0.0740  
Epoch 27/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0748 -  
val\_loss: 0.0728  
Epoch 28/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0707 -  
val\_loss: 0.0929  
Epoch 29/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0733 -  
val\_loss: 0.0890  
Epoch 30/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0752 -  
val\_loss: 0.0850  
Epoch 31/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0710 -  
val\_loss: 0.0595  
Epoch 32/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0707 -



val\_loss: 0.0747  
Epoch 33/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0728 -  
val\_loss: 0.0675  
Epoch 34/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0719 -  
val\_loss: 0.0697  
Epoch 35/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0740 -  
val\_loss: 0.0795  
Epoch 36/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0710 -  
val\_loss: 0.0683  
Epoch 37/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0731 -  
val\_loss: 0.0781  
Epoch 38/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0745 -  
val\_loss: 0.0718  
Epoch 39/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0734 -  
val\_loss: 0.0787  
Epoch 40/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0752 -  
val\_loss: 0.0794  
Epoch 41/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0722 -  
val\_loss: 0.0714  
Epoch 42/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0721 -  
val\_loss: 0.0701  
Epoch 43/100  
115092/115092 [=====] - 23s 200us/step - loss: 0.0740 -  
val\_loss: 0.0860  
Epoch 44/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0772 -  
val\_loss: 0.0869  
Epoch 45/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0796 -  
val\_loss: 0.0860  
Epoch 46/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0786 -  
val\_loss: 0.0884  
Epoch 47/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0796 -  
val\_loss: 0.0814  
Epoch 48/100  
115092/115092 [=====] - 23s 200us/step - loss: 0.0785 -

```

val_loss: 0.0787
Epoch 49/100
115092/115092 [=====] - 23s 201us/step - loss: 0.0803 -
val_loss: 0.0678
Epoch 50/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0808 -
val_loss: 0.0814
Epoch 51/100
115092/115092 [=====] - 23s 201us/step - loss: 0.0829 -
val_loss: 0.1045
Epoch 52/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0829 -
val_loss: 0.0662
Epoch 53/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0835 -
val_loss: 0.0787
Epoch 54/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0785 -
val_loss: 0.0783
Epoch 55/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0816 -
val_loss: 0.0749
Epoch 56/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0838 -
val_loss: 0.0772
Epoch 57/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0857 -
val_loss: 0.0802
Epoch 58/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0831 -
val_loss: 0.0699
Epoch 59/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0870 -
val_loss: 0.1185
Epoch 60/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0892 -
val_loss: 0.0802
Epoch 61/100
115092/115092 [=====] - 23s 202us/step - loss: 0.0927 -
val_loss: 0.1162
Epoch 62/100
115092/115092 [=====] - 23s 201us/step - loss: 0.0927 -
val_loss: 0.0962
Epoch 63/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0884 -
val_loss: 0.0918
Epoch 64/100
115092/115092 [=====] - 23s 201us/step - loss: 0.0964 -

```

```

val_loss: 0.0854
Epoch 65/100
115092/115092 [=====] - 23s 199us/step - loss: 0.1056 -
val_loss: 0.1364
Epoch 66/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0972 -
val_loss: 0.0928
Epoch 67/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0973 -
val_loss: 0.1081
Epoch 68/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0907 -
val_loss: 0.0814
Epoch 69/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0923 -
val_loss: 0.0876
Epoch 70/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0964 -
val_loss: 0.1051
Epoch 71/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0923 -
val_loss: 0.0969
Epoch 72/100
115092/115092 [=====] - 23s 200us/step - loss: 0.1034 -
val_loss: 0.1105
Epoch 73/100
115092/115092 [=====] - 23s 198us/step - loss: 0.1003 -
val_loss: 0.0949
Epoch 74/100
115092/115092 [=====] - 23s 199us/step - loss: 0.1005 -
val_loss: 0.1198
Epoch 75/100
115092/115092 [=====] - 23s 197us/step - loss: 0.1024 -
val_loss: 0.1012
Epoch 76/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0997 -
val_loss: 0.0986
Epoch 77/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0978 -
val_loss: 0.0970
Epoch 78/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0920 -
val_loss: 0.1229
Epoch 79/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0928 -
val_loss: 0.0985
Epoch 80/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0922 -

```

```

val_loss: 0.0995
Epoch 81/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0944 -
val_loss: 0.1065
Epoch 82/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0926 -
val_loss: 0.0971
Epoch 83/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0893 -
val_loss: 0.0885
Epoch 84/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0881 -
val_loss: 0.0918
Epoch 85/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0884 -
val_loss: 0.0824
Epoch 86/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0887 -
val_loss: 0.0928
Epoch 87/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0911 -
val_loss: 0.0817
Epoch 88/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0887 -
val_loss: 0.0821
Epoch 89/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0865 -
val_loss: 0.0840
Epoch 90/100
115092/115092 [=====] - 23s 201us/step - loss: 0.0858 -
val_loss: 0.0842
Epoch 91/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0874 -
val_loss: 0.1015
Epoch 92/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0904 -
val_loss: 0.0797
Epoch 93/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0868 -
val_loss: 0.0750
Epoch 94/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0852 -
val_loss: 0.0682
Epoch 95/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0821 -
val_loss: 0.0874
Epoch 96/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0892 -

```

```

val_loss: 0.0916
Epoch 97/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0858 -
val_loss: 0.1160
Epoch 98/100
115092/115092 [=====] - 23s 200us/step - loss: 0.0886 -
val_loss: 0.0850
Epoch 99/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0847 -
val_loss: 0.0831
Epoch 100/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0887 -
val_loss: 0.0837

```

```
[23]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[24]: Y_test = np.round(Y_test, 0)
```

```
[25]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:2.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.

```

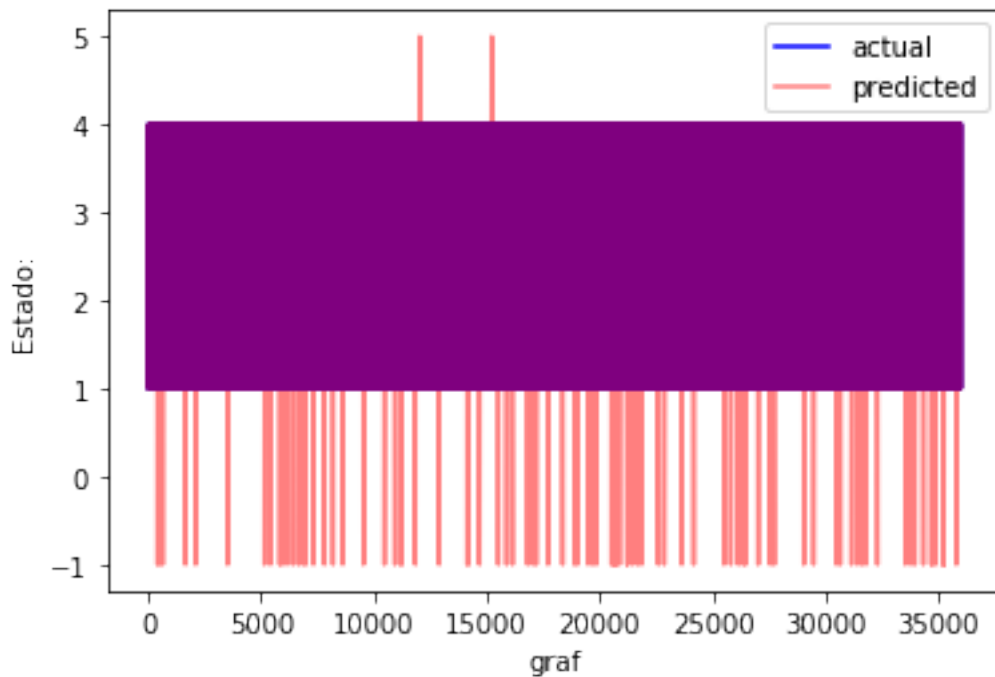
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[26]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9156114264749748

```
[27]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[28]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[28]: 0.9513164845552868
```

```
[:]
```

# Wrist\_elux4\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```



```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```



```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

        D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```



```

    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0830 02:57:15.235106 19500 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 02:57:15.248070 19500 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 02:57:15.252061 19500 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 02:57:15.303957 19500 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0830 02:57:15.474464 19500 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 02:57:15.479451 19500 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100  
115092/115092 [=====] - 18s 153us/step - loss: 0.5981 -  
val\_loss: 0.4853

Epoch 2/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.3578 -  
val\_loss: 0.3916

Epoch 3/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.2837 -  
val\_loss: 0.2953

Epoch 4/100  
115092/115092 [=====] - 17s 143us/step - loss: 0.2476 -  
val\_loss: 0.2450

Epoch 5/100  
115092/115092 [=====] - 17s 143us/step - loss: 0.2249 -  
val\_loss: 0.2368

Epoch 6/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.2082 -  
val\_loss: 0.2215

Epoch 7/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1959 -  
val\_loss: 0.2067

Epoch 8/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1851 -  
val\_loss: 0.2045

Epoch 9/100  
115092/115092 [=====] - 17s 143us/step - loss: 0.1767 -  
val\_loss: 0.1896

Epoch 10/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1685 -  
val\_loss: 0.1614

Epoch 11/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1611 -  
val\_loss: 0.1587

Epoch 12/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1553 -  
val\_loss: 0.1551

Epoch 13/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1491 -  
val\_loss: 0.1609

Epoch 14/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1442 -  
val\_loss: 0.1488

Epoch 15/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1403 -  
val\_loss: 0.1376

Epoch 16/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1367 -

val\_loss: 0.1417  
Epoch 17/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.1333 -  
val\_loss: 0.1326  
Epoch 18/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1302 -  
val\_loss: 0.1405  
Epoch 19/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1280 -  
val\_loss: 0.1306  
Epoch 20/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1257 -  
val\_loss: 0.1420  
Epoch 21/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1232 -  
val\_loss: 0.1345  
Epoch 22/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1212 -  
val\_loss: 0.1275  
Epoch 23/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1195 -  
val\_loss: 0.1238  
Epoch 24/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1181 -  
val\_loss: 0.1179  
Epoch 25/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1161 -  
val\_loss: 0.1359  
Epoch 26/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1146 -  
val\_loss: 0.1151  
Epoch 27/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1133 -  
val\_loss: 0.1248  
Epoch 28/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1118 -  
val\_loss: 0.1161  
Epoch 29/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1108 -  
val\_loss: 0.1091  
Epoch 30/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1091 -  
val\_loss: 0.1273  
Epoch 31/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1082 -  
val\_loss: 0.1074  
Epoch 32/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1073 -

val\_loss: 0.1139  
Epoch 33/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.1061 -  
val\_loss: 0.1155  
Epoch 34/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.1054 -  
val\_loss: 0.1239  
Epoch 35/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1044 -  
val\_loss: 0.1176  
Epoch 36/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1034 -  
val\_loss: 0.1070  
Epoch 37/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.1029 -  
val\_loss: 0.1007  
Epoch 38/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.1019 -  
val\_loss: 0.1068  
Epoch 39/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.1012 -  
val\_loss: 0.1040  
Epoch 40/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0999 -  
val\_loss: 0.1152  
Epoch 41/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0994 -  
val\_loss: 0.1103  
Epoch 42/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0988 -  
val\_loss: 0.0938  
Epoch 43/100  
115092/115092 [=====] - 16s 143us/step - loss: 0.0977 -  
val\_loss: 0.1051  
Epoch 44/100  
115092/115092 [=====] - 17s 144us/step - loss: 0.0966 -  
val\_loss: 0.0984  
Epoch 45/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0968 -  
val\_loss: 0.0995  
Epoch 46/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0966 -  
val\_loss: 0.1114  
Epoch 47/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0954 -  
val\_loss: 0.0865  
Epoch 48/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0949 -

```
val_loss: 0.1311
Epoch 49/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0944 -
val_loss: 0.0965
Epoch 50/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0948 -
val_loss: 0.1125
Epoch 51/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0939 -
val_loss: 0.0943
Epoch 52/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0936 -
val_loss: 0.1040
Epoch 53/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0928 -
val_loss: 0.0948
Epoch 54/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0929 -
val_loss: 0.1133
Epoch 55/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0924 -
val_loss: 0.1039
Epoch 56/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0919 -
val_loss: 0.0919
Epoch 57/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0913 -
val_loss: 0.0947
Epoch 58/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0913 -
val_loss: 0.0878
Epoch 59/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0908 -
val_loss: 0.0959
Epoch 60/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0906 -
val_loss: 0.0934
Epoch 61/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0907 -
val_loss: 0.0970
Epoch 62/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0897 -
val_loss: 0.0790
Epoch 63/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0893 -
val_loss: 0.0900
Epoch 64/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0890 -
```

```
val_loss: 0.0902
Epoch 65/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0893 -
val_loss: 0.0993
Epoch 66/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0890 -
val_loss: 0.0909
Epoch 67/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0879 -
val_loss: 0.0962
Epoch 68/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0879 -
val_loss: 0.0826
Epoch 69/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0878 -
val_loss: 0.0959
Epoch 70/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0867 -
val_loss: 0.0899
Epoch 71/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0870 -
val_loss: 0.0879
Epoch 72/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0869 -
val_loss: 0.0857
Epoch 73/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0864 -
val_loss: 0.0885
Epoch 74/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0859 -
val_loss: 0.0884
Epoch 75/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0860 -
val_loss: 0.0903
Epoch 76/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0854 -
val_loss: 0.0837
Epoch 77/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0852 -
val_loss: 0.0872
Epoch 78/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0852 -
val_loss: 0.0799
Epoch 79/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0851 -
val_loss: 0.0975
Epoch 80/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0846 -
```

val\_loss: 0.0803  
Epoch 81/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0840 -  
val\_loss: 0.0840  
Epoch 82/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0843 -  
val\_loss: 0.0860  
Epoch 83/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0837 -  
val\_loss: 0.0811  
Epoch 84/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0830 -  
val\_loss: 0.0721  
Epoch 85/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0840 -  
val\_loss: 0.0874  
Epoch 86/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0833 -  
val\_loss: 0.0930  
Epoch 87/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0836 -  
val\_loss: 0.0794  
Epoch 88/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0833 -  
val\_loss: 0.0780  
Epoch 89/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0826 -  
val\_loss: 0.0867  
Epoch 90/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0826 -  
val\_loss: 0.0909  
Epoch 91/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0823 -  
val\_loss: 0.0825  
Epoch 92/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0823 -  
val\_loss: 0.0823  
Epoch 93/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0817 -  
val\_loss: 0.0848  
Epoch 94/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0812 -  
val\_loss: 0.0904  
Epoch 95/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0807 -  
val\_loss: 0.0983  
Epoch 96/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0815 -

```
val_loss: 0.0928
Epoch 97/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0802 -
val_loss: 0.0954
Epoch 98/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0806 -
val_loss: 0.0882
Epoch 99/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0802 -
val_loss: 0.0773
Epoch 100/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0801 -
val_loss: 0.0824
```

```
[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 115092 samples, validate on 28773 samples

```
Epoch 1/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0797 -
val_loss: 0.0837
Epoch 2/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0796 -
val_loss: 0.0805
Epoch 3/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0796 -
val_loss: 0.0796
Epoch 4/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0800 -
val_loss: 0.0793
Epoch 5/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0799 -
val_loss: 0.0932
Epoch 6/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0795 -
val_loss: 0.0765
Epoch 7/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0796 -
val_loss: 0.0906
Epoch 8/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0791 -
val_loss: 0.0793
Epoch 9/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0791 -
```



```
val_loss: 0.0794
Epoch 10/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0790 -
val_loss: 0.0821
Epoch 11/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0793 -
val_loss: 0.0758
Epoch 12/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0787 -
val_loss: 0.0963
Epoch 13/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0787 -
val_loss: 0.0784
Epoch 14/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0788 -
val_loss: 0.0819
Epoch 15/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0788 -
val_loss: 0.0764
Epoch 16/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0781 -
val_loss: 0.0880
Epoch 17/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0778 -
val_loss: 0.0879
Epoch 18/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0783 -
val_loss: 0.0751
Epoch 19/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0778 -
val_loss: 0.0687
Epoch 20/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0776 -
val_loss: 0.0806
Epoch 21/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0780 -
val_loss: 0.0817
Epoch 22/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0775 -
val_loss: 0.0864
Epoch 23/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0772 -
val_loss: 0.0793
Epoch 24/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0778 -
val_loss: 0.0832
Epoch 25/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0772 -
```

val\_loss: 0.0813  
Epoch 26/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0767 -  
val\_loss: 0.0736  
Epoch 27/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0772 -  
val\_loss: 0.0860  
Epoch 28/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0771 -  
val\_loss: 0.0801  
Epoch 29/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0770 -  
val\_loss: 0.0991  
Epoch 30/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0771 -  
val\_loss: 0.1036  
Epoch 31/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0761 -  
val\_loss: 0.0950  
Epoch 32/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0762 -  
val\_loss: 0.1001  
Epoch 33/100  
115092/115092 [=====] - 16s 142us/step - loss: 0.0765 -  
val\_loss: 0.0761  
Epoch 34/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0761 -  
val\_loss: 0.0809  
Epoch 35/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0761 -  
val\_loss: 0.0677  
Epoch 36/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0764 -  
val\_loss: 0.0716  
Epoch 37/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0764 -  
val\_loss: 0.0765  
Epoch 38/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0764 -  
val\_loss: 0.0763  
Epoch 39/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0766 -  
val\_loss: 0.0829  
Epoch 40/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0757 -  
val\_loss: 0.0925  
Epoch 41/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0760 -

val\_loss: 0.0829  
Epoch 42/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0758 -  
val\_loss: 0.1000  
Epoch 43/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0759 -  
val\_loss: 0.0802  
Epoch 44/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0755 -  
val\_loss: 0.0799  
Epoch 45/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0759 -  
val\_loss: 0.0824  
Epoch 46/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0760 -  
val\_loss: 0.0730  
Epoch 47/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0749 -  
val\_loss: 0.0848  
Epoch 48/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0756 -  
val\_loss: 0.0853  
Epoch 49/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0745 -  
val\_loss: 0.0825  
Epoch 50/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0743 -  
val\_loss: 0.0824  
Epoch 51/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0746 -  
val\_loss: 0.0699  
Epoch 52/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0749 -  
val\_loss: 0.0866  
Epoch 53/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0743 -  
val\_loss: 0.0974  
Epoch 54/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0740 -  
val\_loss: 0.0912  
Epoch 55/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0748 -  
val\_loss: 0.0906  
Epoch 56/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0750 -  
val\_loss: 0.0716  
Epoch 57/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0749 -

val\_loss: 0.0729  
Epoch 58/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0747 -  
val\_loss: 0.0753  
Epoch 59/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0746 -  
val\_loss: 0.0700  
Epoch 60/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0737 -  
val\_loss: 0.0751  
Epoch 61/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0737 -  
val\_loss: 0.1002  
Epoch 62/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0742 -  
val\_loss: 0.0688  
Epoch 63/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0740 -  
val\_loss: 0.0772  
Epoch 64/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0736 -  
val\_loss: 0.0728  
Epoch 65/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0741 -  
val\_loss: 0.0880  
Epoch 66/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0738 -  
val\_loss: 0.0909  
Epoch 67/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0732 -  
val\_loss: 0.0800  
Epoch 68/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0728 -  
val\_loss: 0.0775  
Epoch 69/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0732 -  
val\_loss: 0.0679  
Epoch 70/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0729 -  
val\_loss: 0.0850  
Epoch 71/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0728 -  
val\_loss: 0.0708  
Epoch 72/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0725 -  
val\_loss: 0.0747  
Epoch 73/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0738 -

val\_loss: 0.0854  
Epoch 74/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0728 -  
val\_loss: 0.0832  
Epoch 75/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0736 -  
val\_loss: 0.0875  
Epoch 76/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0729 -  
val\_loss: 0.0771  
Epoch 77/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0725 -  
val\_loss: 0.0878  
Epoch 78/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0728 -  
val\_loss: 0.0902  
Epoch 79/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0725 -  
val\_loss: 0.0839  
Epoch 80/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0728 -  
val\_loss: 0.0644  
Epoch 81/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0729 -  
val\_loss: 0.0902  
Epoch 82/100  
115092/115092 [=====] - 16s 139us/step - loss: 0.0728 -  
val\_loss: 0.0809  
Epoch 83/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0730 -  
val\_loss: 0.0822  
Epoch 84/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0726 -  
val\_loss: 0.1080  
Epoch 85/100  
115092/115092 [=====] - 16s 140us/step - loss: 0.0721 -  
val\_loss: 0.0805  
Epoch 86/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0723 -  
val\_loss: 0.0691  
Epoch 87/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0723 -  
val\_loss: 0.0856  
Epoch 88/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0722 -  
val\_loss: 0.0666  
Epoch 89/100  
115092/115092 [=====] - 16s 141us/step - loss: 0.0726 -

```

val_loss: 0.0805
Epoch 90/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0720 -
val_loss: 0.0878
Epoch 91/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0720 -
val_loss: 0.0819
Epoch 92/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0716 -
val_loss: 0.1019
Epoch 93/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0716 -
val_loss: 0.0771
Epoch 94/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0720 -
val_loss: 0.0651
Epoch 95/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0714 -
val_loss: 0.0921
Epoch 96/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0714 -
val_loss: 0.0632
Epoch 97/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0712 -
val_loss: 0.0749
Epoch 98/100
115092/115092 [=====] - 16s 140us/step - loss: 0.0712 -
val_loss: 0.0757
Epoch 99/100
115092/115092 [=====] - 16s 141us/step - loss: 0.0711 -
val_loss: 0.0767
Epoch 100/100
115092/115092 [=====] - 16s 142us/step - loss: 0.0712 -
val_loss: 0.0709

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))

```

Estado: 1., predicted:1.

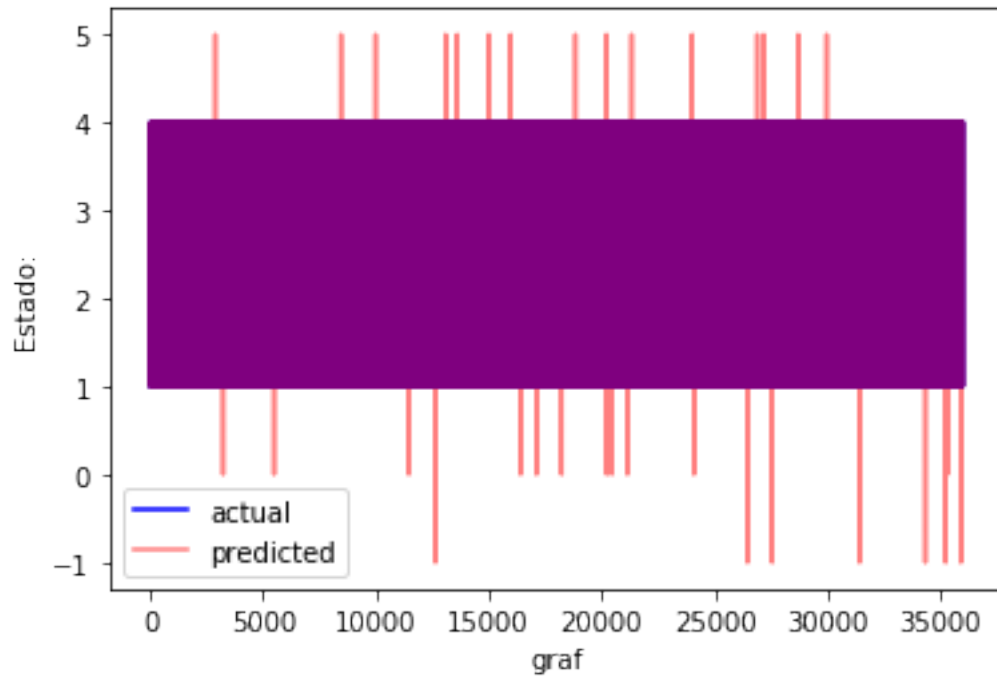
```
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:4.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

0.9563134630940406

```
[26]: plt.plot((Y_val),
              color="b", label="actual")
      plt.plot((Y_test),
              color="r", alpha=0.5, label="predicted")
      plt.xlabel("graf")
      plt.ylabel("Estado:")
      plt.legend(loc="best")
      plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[27]: 0.9746156198737732
```

```
[:]
```



# Wrist\_elux5\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```



```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```



```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0830 03:54:14.022293 2160 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 03:54:14.035257 2160 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 03:54:14.038250 2160 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 03:54:14.099122 2160 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0830 03:54:14.282597 2160 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 03:54:14.287618 2160 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is

deprecated. Please use `tf.compat.v1.assign` instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 18s 159us/step - loss: 0.5602 -  
val\_loss: 0.3840

Epoch 2/100

115092/115092 [=====] - 17s 148us/step - loss: 0.3263 -  
val\_loss: 0.3050

Epoch 3/100

115092/115092 [=====] - 17s 148us/step - loss: 0.2474 -  
val\_loss: 0.2530

Epoch 4/100

115092/115092 [=====] - 17s 147us/step - loss: 0.2056 -  
val\_loss: 0.1918

Epoch 5/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1809 -  
val\_loss: 0.1983

Epoch 6/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1629 -  
val\_loss: 0.1572

Epoch 7/100

115092/115092 [=====] - 17s 147us/step - loss: 0.1488 -  
val\_loss: 0.1333

Epoch 8/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1381 -  
val\_loss: 0.1644

Epoch 9/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1294 -  
val\_loss: 0.1237

Epoch 10/100

115092/115092 [=====] - 17s 147us/step - loss: 0.1212 -  
val\_loss: 0.1229

Epoch 11/100

115092/115092 [=====] - 17s 147us/step - loss: 0.1151 -  
val\_loss: 0.1237

Epoch 12/100

115092/115092 [=====] - 17s 147us/step - loss: 0.1108 -  
val\_loss: 0.1039

Epoch 13/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1070 -  
val\_loss: 0.1179

Epoch 14/100

115092/115092 [=====] - 17s 147us/step - loss: 0.1043 -  
val\_loss: 0.1132

Epoch 15/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1016 -

```
val_loss: 0.1195
Epoch 16/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0992 -
val_loss: 0.0958
Epoch 17/100
115092/115092 [=====] - 17s 147us/step - loss: 0.0967 -
val_loss: 0.1008
Epoch 18/100
115092/115092 [=====] - 17s 147us/step - loss: 0.0940 -
val_loss: 0.0958
Epoch 19/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0922 -
val_loss: 0.0937
Epoch 20/100
115092/115092 [=====] - 17s 147us/step - loss: 0.0906 -
val_loss: 0.0863
Epoch 21/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0891 -
val_loss: 0.0955
Epoch 22/100
115092/115092 [=====] - 17s 150us/step - loss: 0.0866 -
val_loss: 0.0945
Epoch 23/100
115092/115092 [=====] - 17s 149us/step - loss: 0.0851 -
val_loss: 0.0992
Epoch 24/100
115092/115092 [=====] - 17s 150us/step - loss: 0.0842 -
val_loss: 0.0842
Epoch 25/100
115092/115092 [=====] - 17s 151us/step - loss: 0.0832 -
val_loss: 0.0779
Epoch 26/100
115092/115092 [=====] - 17s 150us/step - loss: 0.0820 -
val_loss: 0.0835
Epoch 27/100
115092/115092 [=====] - 17s 150us/step - loss: 0.0802 -
val_loss: 0.0794
Epoch 28/100
115092/115092 [=====] - 17s 150us/step - loss: 0.0796 -
val_loss: 0.0862
Epoch 29/100
115092/115092 [=====] - 17s 149us/step - loss: 0.0783 -
val_loss: 0.0811
Epoch 30/100
115092/115092 [=====] - 17s 151us/step - loss: 0.0773 -
val_loss: 0.0861
Epoch 31/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0765 -
```

val\_loss: 0.0766  
Epoch 32/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0753 -  
val\_loss: 0.0825  
Epoch 33/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0750 -  
val\_loss: 0.0814  
Epoch 34/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0742 -  
val\_loss: 0.0780  
Epoch 35/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0739 -  
val\_loss: 0.0733  
Epoch 36/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0728 -  
val\_loss: 0.0835  
Epoch 37/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0719 -  
val\_loss: 0.0794  
Epoch 38/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0716 -  
val\_loss: 0.0684  
Epoch 39/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0705 -  
val\_loss: 0.0664  
Epoch 40/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0699 -  
val\_loss: 0.0733  
Epoch 41/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0695 -  
val\_loss: 0.0664  
Epoch 42/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0684 -  
val\_loss: 0.0692  
Epoch 43/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0679 -  
val\_loss: 0.0770  
Epoch 44/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0678 -  
val\_loss: 0.0744  
Epoch 45/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0662 -  
val\_loss: 0.0679  
Epoch 46/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0665 -  
val\_loss: 0.0746  
Epoch 47/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0657 -

val\_loss: 0.0679  
Epoch 48/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0658 -  
val\_loss: 0.0716  
Epoch 49/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0645 -  
val\_loss: 0.0652  
Epoch 50/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0645 -  
val\_loss: 0.0657  
Epoch 51/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0636 -  
val\_loss: 0.0739  
Epoch 52/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0631 -  
val\_loss: 0.0647  
Epoch 53/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0630 -  
val\_loss: 0.0574  
Epoch 54/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0614 -  
val\_loss: 0.0680  
Epoch 55/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0623 -  
val\_loss: 0.0770  
Epoch 56/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0619 -  
val\_loss: 0.0688  
Epoch 57/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0612 -  
val\_loss: 0.0705  
Epoch 58/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0607 -  
val\_loss: 0.0710  
Epoch 59/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0609 -  
val\_loss: 0.0608  
Epoch 60/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0602 -  
val\_loss: 0.0642  
Epoch 61/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0597 -  
val\_loss: 0.0708  
Epoch 62/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0596 -  
val\_loss: 0.0682  
Epoch 63/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0597 -

val\_loss: 0.0752  
Epoch 64/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0593 -  
val\_loss: 0.0508  
Epoch 65/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0591 -  
val\_loss: 0.0642  
Epoch 66/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0591 -  
val\_loss: 0.0578  
Epoch 67/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0586 -  
val\_loss: 0.0770  
Epoch 68/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0590 -  
val\_loss: 0.0637  
Epoch 69/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0594 -  
val\_loss: 0.0693  
Epoch 70/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0589 -  
val\_loss: 0.0557  
Epoch 71/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0590 -  
val\_loss: 0.0630  
Epoch 72/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0589 -  
val\_loss: 0.0676  
Epoch 73/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0586 -  
val\_loss: 0.0659  
Epoch 74/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0587 -  
val\_loss: 0.0720  
Epoch 75/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0583 -  
val\_loss: 0.0552  
Epoch 76/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0581 -  
val\_loss: 0.0598  
Epoch 77/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0591 -  
val\_loss: 0.0625  
Epoch 78/100  
115092/115092 [=====] - 18s 154us/step - loss: 0.0583 -  
val\_loss: 0.0569  
Epoch 79/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0585 -

val\_loss: 0.0590  
Epoch 80/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0579 -  
val\_loss: 0.0606  
Epoch 81/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0588 -  
val\_loss: 0.0603  
Epoch 82/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0579 -  
val\_loss: 0.0524  
Epoch 83/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0581 -  
val\_loss: 0.0503  
Epoch 84/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0589 -  
val\_loss: 0.0539  
Epoch 85/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0592 -  
val\_loss: 0.0807  
Epoch 86/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0588 -  
val\_loss: 0.0827  
Epoch 87/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0587 -  
val\_loss: 0.0531  
Epoch 88/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0584 -  
val\_loss: 0.0628  
Epoch 89/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0586 -  
val\_loss: 0.0596  
Epoch 90/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0585 -  
val\_loss: 0.0838  
Epoch 91/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0611 -  
val\_loss: 0.0542  
Epoch 92/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0589 -  
val\_loss: 0.0629  
Epoch 93/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0582 -  
val\_loss: 0.0521  
Epoch 94/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0581 -  
val\_loss: 0.0612  
Epoch 95/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0577 -



```
val_loss: 0.0614
Epoch 96/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0580 -
val_loss: 0.0480
Epoch 97/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0568 -
val_loss: 0.0571
Epoch 98/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0567 -
val_loss: 0.0641
Epoch 99/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0566 -
val_loss: 0.0664
Epoch 100/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0568 -
val_loss: 0.0740
```

```
[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 115092 samples, validate on 28773 samples

```
Epoch 1/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0565 -
val_loss: 0.0680
Epoch 2/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0565 -
val_loss: 0.0575
Epoch 3/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0559 -
val_loss: 0.0643
Epoch 4/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0560 -
val_loss: 0.0527
Epoch 5/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0563 -
val_loss: 0.0554
Epoch 6/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0568 -
val_loss: 0.0583
Epoch 7/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0564 -
val_loss: 0.0547
Epoch 8/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0566 -
```

```
val_loss: 0.0531
Epoch 9/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0563 -
val_loss: 0.0563
Epoch 10/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0561 -
val_loss: 0.0626
Epoch 11/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0563 -
val_loss: 0.0681
Epoch 12/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0553 -
val_loss: 0.0688
Epoch 13/100
115092/115092 [=====] - 18s 154us/step - loss: 0.0563 -
val_loss: 0.0758
Epoch 14/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0559 -
val_loss: 0.0578
Epoch 15/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0555 -
val_loss: 0.0578
Epoch 16/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0560 -
val_loss: 0.0690
Epoch 17/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0556 -
val_loss: 0.0574
Epoch 18/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0557 -
val_loss: 0.0524
Epoch 19/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0548 -
val_loss: 0.0586
Epoch 20/100
115092/115092 [=====] - 18s 153us/step - loss: 0.0545 -
val_loss: 0.0523
Epoch 21/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0542 -
val_loss: 0.0524
Epoch 22/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0544 -
val_loss: 0.0478
Epoch 23/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0549 -
val_loss: 0.0727
Epoch 24/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0542 -
```

```
val_loss: 0.0519
Epoch 25/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0532 -
val_loss: 0.0471
Epoch 26/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0532 -
val_loss: 0.0558
Epoch 27/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0536 -
val_loss: 0.0575
Epoch 28/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0528 -
val_loss: 0.0562
Epoch 29/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0535 -
val_loss: 0.0565
Epoch 30/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0531 -
val_loss: 0.0539
Epoch 31/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0536 -
val_loss: 0.0456
Epoch 32/100
115092/115092 [=====] - 18s 154us/step - loss: 0.0537 -
val_loss: 0.0623
Epoch 33/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0534 -
val_loss: 0.0597
Epoch 34/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0530 -
val_loss: 0.0563
Epoch 35/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0521 -
val_loss: 0.0543
Epoch 36/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0526 -
val_loss: 0.0552
Epoch 37/100
115092/115092 [=====] - 18s 154us/step - loss: 0.0513 -
val_loss: 0.0542
Epoch 38/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0516 -
val_loss: 0.0495
Epoch 39/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0516 -
val_loss: 0.0596
Epoch 40/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0515 -
```

val\_loss: 0.0639  
Epoch 41/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0529 -  
val\_loss: 0.0657  
Epoch 42/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0523 -  
val\_loss: 0.0691  
Epoch 43/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0513 -  
val\_loss: 0.0578  
Epoch 44/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0529 -  
val\_loss: 0.0604  
Epoch 45/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0532 -  
val\_loss: 0.0531  
Epoch 46/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0526 -  
val\_loss: 0.0546  
Epoch 47/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0522 -  
val\_loss: 0.0504  
Epoch 48/100  
115092/115092 [=====] - 18s 155us/step - loss: 0.0532 -  
val\_loss: 0.0509  
Epoch 49/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0529 -  
val\_loss: 0.0514  
Epoch 50/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0535 -  
val\_loss: 0.0684  
Epoch 51/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0538 -  
val\_loss: 0.0458  
Epoch 52/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0540 -  
val\_loss: 0.0534  
Epoch 53/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0542 -  
val\_loss: 0.0659  
Epoch 54/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0543 -  
val\_loss: 0.0577  
Epoch 55/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0543 -  
val\_loss: 0.0458  
Epoch 56/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0550 -

val\_loss: 0.0544  
Epoch 57/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0554 -  
val\_loss: 0.0469  
Epoch 58/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0548 -  
val\_loss: 0.0557  
Epoch 59/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0552 -  
val\_loss: 0.0582  
Epoch 60/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0550 -  
val\_loss: 0.0472  
Epoch 61/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0564 -  
val\_loss: 0.0575  
Epoch 62/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0567 -  
val\_loss: 0.0543  
Epoch 63/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0555 -  
val\_loss: 0.0552  
Epoch 64/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0571 -  
val\_loss: 0.0553  
Epoch 65/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0561 -  
val\_loss: 0.0582  
Epoch 66/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0575 -  
val\_loss: 0.0684  
Epoch 67/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0578 -  
val\_loss: 0.0560  
Epoch 68/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0578 -  
val\_loss: 0.0629  
Epoch 69/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0589 -  
val\_loss: 0.0807  
Epoch 70/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0585 -  
val\_loss: 0.0635  
Epoch 71/100  
115092/115092 [=====] - 18s 157us/step - loss: 0.0585 -  
val\_loss: 0.0523  
Epoch 72/100  
115092/115092 [=====] - 18s 156us/step - loss: 0.0599 -

```
val_loss: 0.0562
Epoch 73/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0588 -
val_loss: 0.0645
Epoch 74/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0598 -
val_loss: 0.0562
Epoch 75/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0595 -
val_loss: 0.0623
Epoch 76/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0605 -
val_loss: 0.0698
Epoch 77/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0603 -
val_loss: 0.0646
Epoch 78/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0612 -
val_loss: 0.0666
Epoch 79/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0610 -
val_loss: 0.0628
Epoch 80/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0623 -
val_loss: 0.0603
Epoch 81/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0622 -
val_loss: 0.0658
Epoch 82/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0619 -
val_loss: 0.0685
Epoch 83/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0651 -
val_loss: 0.0595
Epoch 84/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0645 -
val_loss: 0.0588
Epoch 85/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0646 -
val_loss: 0.0637
Epoch 86/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0621 -
val_loss: 0.0624
Epoch 87/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0617 -
val_loss: 0.0700
Epoch 88/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0623 -
```

```

val_loss: 0.0793
Epoch 89/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0633 -
val_loss: 0.0640
Epoch 90/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0634 -
val_loss: 0.0619
Epoch 91/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0619 -
val_loss: 0.0783
Epoch 92/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0630 -
val_loss: 0.0699
Epoch 93/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0632 -
val_loss: 0.0626
Epoch 94/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0624 -
val_loss: 0.0636
Epoch 95/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0624 -
val_loss: 0.0585
Epoch 96/100
115092/115092 [=====] - 18s 155us/step - loss: 0.0627 -
val_loss: 0.0878
Epoch 97/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0620 -
val_loss: 0.0707
Epoch 98/100
115092/115092 [=====] - 18s 157us/step - loss: 0.0615 -
val_loss: 0.0537
Epoch 99/100
115092/115092 [=====] - 18s 156us/step - loss: 0.0627 -
val_loss: 0.0623
Epoch 100/100
115092/115092 [=====] - 18s 154us/step - loss: 0.0624 -
val_loss: 0.0573

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
```

```
print("Estado: "+ np.array2string(label) + ", predicted:" + np.  
↪array2string(prediction))
```

```
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 4., predicted:4.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:2.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

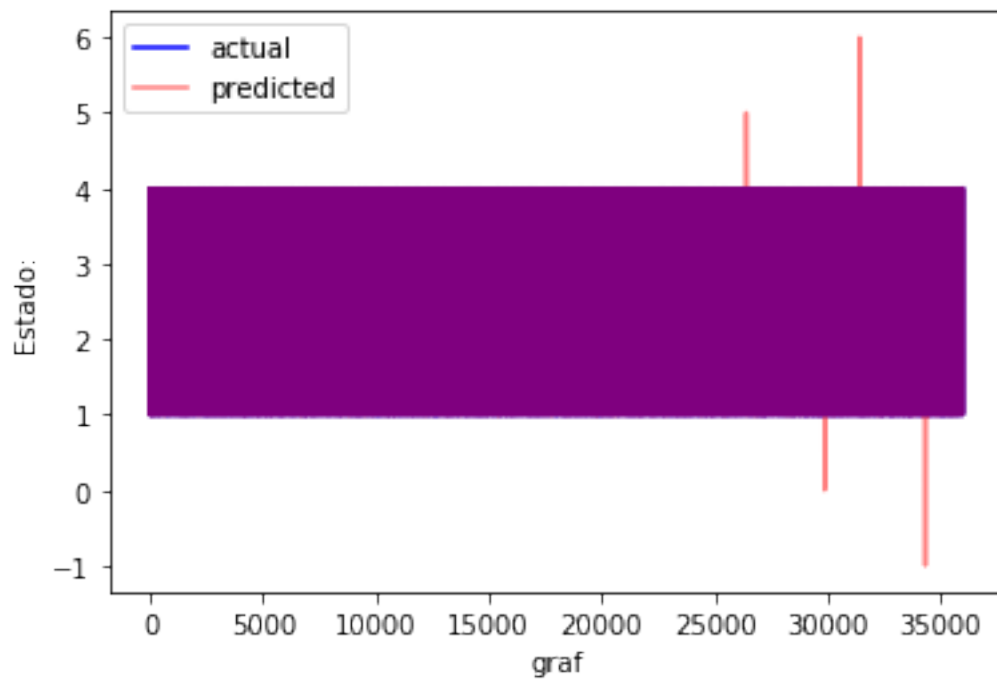
```
[25]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9529768306439741

```
[26]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")
```



```
plt.legend(loc="best")  
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]  
Accu=Y_val2==Y_test  
accur=np.sum(Accu)  
accur/len(Y_val)
```

```
[27]: 0.9722523424250007
```

```
[:]
```

# Wrist\_elux7\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```



```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```



```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

Dense(60),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(30),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0830 05:14:49.241491 18176 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 05:14:49.253420 18176 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 05:14:49.257409 18176 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 05:14:49.350161 18176 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0830 05:14:49.582539 18176 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 05:14:49.587561 18176 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 23s 202us/step - loss: 0.5122 -  
val\_loss: 0.3439

Epoch 2/100

115092/115092 [=====] - 22s 191us/step - loss: 0.2748 -  
val\_loss: 0.2154

Epoch 3/100

115092/115092 [=====] - 22s 188us/step - loss: 0.2046 -  
val\_loss: 0.1900

Epoch 4/100

115092/115092 [=====] - 22s 189us/step - loss: 0.1662 -  
val\_loss: 0.1848

Epoch 5/100

115092/115092 [=====] - 22s 191us/step - loss: 0.1427 -  
val\_loss: 0.1321

Epoch 6/100

115092/115092 [=====] - 22s 192us/step - loss: 0.1279 -  
val\_loss: 0.1200

Epoch 7/100

115092/115092 [=====] - 22s 191us/step - loss: 0.1178 -  
val\_loss: 0.1525

Epoch 8/100

115092/115092 [=====] - 22s 192us/step - loss: 0.1104 -  
val\_loss: 0.1150

Epoch 9/100

115092/115092 [=====] - 22s 190us/step - loss: 0.1053 -  
val\_loss: 0.1538

Epoch 10/100

115092/115092 [=====] - 22s 190us/step - loss: 0.1007 -  
val\_loss: 0.0962

Epoch 11/100

115092/115092 [=====] - 22s 191us/step - loss: 0.0966 -  
val\_loss: 0.1025

Epoch 12/100

115092/115092 [=====] - 22s 191us/step - loss: 0.0937 -  
val\_loss: 0.0922

Epoch 13/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0917 -  
val\_loss: 0.1028

Epoch 14/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0882 -  
val\_loss: 0.0791  
Epoch 15/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0873 -  
val\_loss: 0.0865  
Epoch 16/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0846 -  
val\_loss: 0.0852  
Epoch 17/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0819 -  
val\_loss: 0.0801  
Epoch 18/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0823 -  
val\_loss: 0.0733  
Epoch 19/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0803 -  
val\_loss: 0.0948  
Epoch 20/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0785 -  
val\_loss: 0.0756  
Epoch 21/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0778 -  
val\_loss: 0.0694  
Epoch 22/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0749 -  
val\_loss: 0.0786  
Epoch 23/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0730 -  
val\_loss: 0.0805  
Epoch 24/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0722 -  
val\_loss: 0.0727  
Epoch 25/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0708 -  
val\_loss: 0.0732  
Epoch 26/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0703 -  
val\_loss: 0.0680  
Epoch 27/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0692 -  
val\_loss: 0.0843  
Epoch 28/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0682 -  
val\_loss: 0.0700  
Epoch 29/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0675 -  
val\_loss: 0.0639  
Epoch 30/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0672 -  
val\_loss: 0.0802  
Epoch 31/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0671 -  
val\_loss: 0.0650  
Epoch 32/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0655 -  
val\_loss: 0.0764  
Epoch 33/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0662 -  
val\_loss: 0.0678  
Epoch 34/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0662 -  
val\_loss: 0.0671  
Epoch 35/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0652 -  
val\_loss: 0.0736  
Epoch 36/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0639 -  
val\_loss: 0.0715  
Epoch 37/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0641 -  
val\_loss: 0.0744  
Epoch 38/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0630 -  
val\_loss: 0.0803  
Epoch 39/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0628 -  
val\_loss: 0.0777  
Epoch 40/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0628 -  
val\_loss: 0.0691  
Epoch 41/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0618 -  
val\_loss: 0.0874  
Epoch 42/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0610 -  
val\_loss: 0.0557  
Epoch 43/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0605 -  
val\_loss: 0.0603  
Epoch 44/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0613 -  
val\_loss: 0.0653  
Epoch 45/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0599 -  
val\_loss: 0.0741  
Epoch 46/100

115092/115092 [=====] - 22s 193us/step - loss: 0.0604 -  
val\_loss: 0.0599  
Epoch 47/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0590 -  
val\_loss: 0.0632  
Epoch 48/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0600 -  
val\_loss: 0.0571  
Epoch 49/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0587 -  
val\_loss: 0.0716  
Epoch 50/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0601 -  
val\_loss: 0.0570  
Epoch 51/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0590 -  
val\_loss: 0.0614  
Epoch 52/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0587 -  
val\_loss: 0.0561  
Epoch 53/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0589 -  
val\_loss: 0.0693  
Epoch 54/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0577 -  
val\_loss: 0.0624  
Epoch 55/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0573 -  
val\_loss: 0.0656  
Epoch 56/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0577 -  
val\_loss: 0.0634  
Epoch 57/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0582 -  
val\_loss: 0.0544  
Epoch 58/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0585 -  
val\_loss: 0.0712  
Epoch 59/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0571 -  
val\_loss: 0.0646  
Epoch 60/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0576 -  
val\_loss: 0.0605  
Epoch 61/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0579 -  
val\_loss: 0.0641  
Epoch 62/100

115092/115092 [=====] - 22s 189us/step - loss: 0.0572 -  
val\_loss: 0.0665  
Epoch 63/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0574 -  
val\_loss: 0.0521  
Epoch 64/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0574 -  
val\_loss: 0.0800  
Epoch 65/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0565 -  
val\_loss: 0.0603  
Epoch 66/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0564 -  
val\_loss: 0.0506  
Epoch 67/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0552 -  
val\_loss: 0.0655  
Epoch 68/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0564 -  
val\_loss: 0.0620  
Epoch 69/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0561 -  
val\_loss: 0.0497  
Epoch 70/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0563 -  
val\_loss: 0.0559  
Epoch 71/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0555 -  
val\_loss: 0.0557  
Epoch 72/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0570 -  
val\_loss: 0.0674  
Epoch 73/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0565 -  
val\_loss: 0.0678  
Epoch 74/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0572 -  
val\_loss: 0.0485  
Epoch 75/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0563 -  
val\_loss: 0.0541  
Epoch 76/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0556 -  
val\_loss: 0.0630  
Epoch 77/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0551 -  
val\_loss: 0.0515  
Epoch 78/100



115092/115092 [=====] - 22s 188us/step - loss: 0.0537 -  
val\_loss: 0.0618  
Epoch 79/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0552 -  
val\_loss: 0.0550  
Epoch 80/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0559 -  
val\_loss: 0.0823  
Epoch 81/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0549 -  
val\_loss: 0.0551  
Epoch 82/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0557 -  
val\_loss: 0.0585  
Epoch 83/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0553 -  
val\_loss: 0.0603  
Epoch 84/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0538 -  
val\_loss: 0.0525  
Epoch 85/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0542 -  
val\_loss: 0.0553  
Epoch 86/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0538 -  
val\_loss: 0.0684  
Epoch 87/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0543 -  
val\_loss: 0.0602  
Epoch 88/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0545 -  
val\_loss: 0.0699  
Epoch 89/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0536 -  
val\_loss: 0.0539  
Epoch 90/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0535 -  
val\_loss: 0.0604  
Epoch 91/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0539 -  
val\_loss: 0.0556  
Epoch 92/100  
115092/115092 [=====] - 22s 187us/step - loss: 0.0521 -  
val\_loss: 0.0605  
Epoch 93/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0539 -  
val\_loss: 0.0733  
Epoch 94/100

```

115092/115092 [=====] - 22s 188us/step - loss: 0.0544 -
val_loss: 0.0562
Epoch 95/100
115092/115092 [=====] - 22s 187us/step - loss: 0.0527 -
val_loss: 0.0596
Epoch 96/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0543 -
val_loss: 0.0471
Epoch 97/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0530 -
val_loss: 0.0613
Epoch 98/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0531 -
val_loss: 0.0451
Epoch 99/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0525 -
val_loss: 0.0527
Epoch 100/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0524 -
val_loss: 0.0579

```

```

[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 115092 samples, validate on 28773 samples
Epoch 1/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0532 -
val_loss: 0.0545
Epoch 2/100
115092/115092 [=====] - 22s 195us/step - loss: 0.0520 -
val_loss: 0.0481
Epoch 3/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0535 -
val_loss: 0.0554
Epoch 4/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0526 -
val_loss: 0.0483
Epoch 5/100
115092/115092 [=====] - 22s 193us/step - loss: 0.0524 -
val_loss: 0.0850
Epoch 6/100
115092/115092 [=====] - 22s 192us/step - loss: 0.0519 -
val_loss: 0.0532
Epoch 7/100

```

115092/115092 [=====] - 22s 193us/step - loss: 0.0518 -  
val\_loss: 0.0584  
Epoch 8/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0530 -  
val\_loss: 0.0617  
Epoch 9/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0537 -  
val\_loss: 0.0578  
Epoch 10/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0529 -  
val\_loss: 0.0478  
Epoch 11/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0536 -  
val\_loss: 0.0550  
Epoch 12/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0519 -  
val\_loss: 0.0536  
Epoch 13/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0549 -  
val\_loss: 0.0505  
Epoch 14/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0534 -  
val\_loss: 0.0582  
Epoch 15/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0530 -  
val\_loss: 0.0547  
Epoch 16/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0535 -  
val\_loss: 0.0683  
Epoch 17/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0536 -  
val\_loss: 0.0536  
Epoch 18/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0544 -  
val\_loss: 0.0621  
Epoch 19/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0572 -  
val\_loss: 0.0762  
Epoch 20/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0533 -  
val\_loss: 0.0754  
Epoch 21/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0525 -  
val\_loss: 0.0673  
Epoch 22/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0541 -  
val\_loss: 0.0479  
Epoch 23/100

115092/115092 [=====] - 22s 192us/step - loss: 0.0534 -  
val\_loss: 0.0596  
Epoch 24/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0547 -  
val\_loss: 0.0544  
Epoch 25/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0555 -  
val\_loss: 0.0598  
Epoch 26/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0561 -  
val\_loss: 0.0525  
Epoch 27/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0543 -  
val\_loss: 0.0626  
Epoch 28/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0549 -  
val\_loss: 0.0595  
Epoch 29/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0545 -  
val\_loss: 0.0535  
Epoch 30/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0557 -  
val\_loss: 0.0547  
Epoch 31/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0558 -  
val\_loss: 0.0535  
Epoch 32/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0560 -  
val\_loss: 0.0496  
Epoch 33/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0557 -  
val\_loss: 0.0606  
Epoch 34/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0563 -  
val\_loss: 0.0480  
Epoch 35/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0563 -  
val\_loss: 0.0556  
Epoch 36/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0551 -  
val\_loss: 0.0608  
Epoch 37/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0570 -  
val\_loss: 0.0544  
Epoch 38/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0566 -  
val\_loss: 0.0592  
Epoch 39/100

115092/115092 [=====] - 22s 193us/step - loss: 0.0581 -  
val\_loss: 0.0585  
Epoch 40/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0579 -  
val\_loss: 0.0672  
Epoch 41/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0583 -  
val\_loss: 0.0603  
Epoch 42/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0598 -  
val\_loss: 0.0579  
Epoch 43/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0574 -  
val\_loss: 0.0502  
Epoch 44/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0589 -  
val\_loss: 0.0623  
Epoch 45/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0607 -  
val\_loss: 0.0509  
Epoch 46/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0600 -  
val\_loss: 0.0751  
Epoch 47/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0611 -  
val\_loss: 0.0525  
Epoch 48/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0606 -  
val\_loss: 0.0675  
Epoch 49/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0626 -  
val\_loss: 0.0588  
Epoch 50/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0646 -  
val\_loss: 0.0640  
Epoch 51/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0662 -  
val\_loss: 0.0703  
Epoch 52/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0650 -  
val\_loss: 0.0725  
Epoch 53/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0627 -  
val\_loss: 0.0709  
Epoch 54/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0637 -  
val\_loss: 0.0587  
Epoch 55/100

115092/115092 [=====] - 22s 193us/step - loss: 0.0639 -  
val\_loss: 0.0523  
Epoch 56/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0624 -  
val\_loss: 0.0635  
Epoch 57/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0603 -  
val\_loss: 0.0542  
Epoch 58/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0600 -  
val\_loss: 0.0534  
Epoch 59/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0614 -  
val\_loss: 0.0624  
Epoch 60/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0589 -  
val\_loss: 0.0615  
Epoch 61/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0609 -  
val\_loss: 0.0756  
Epoch 62/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0627 -  
val\_loss: 0.0837  
Epoch 63/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0604 -  
val\_loss: 0.0702  
Epoch 64/100  
115092/115092 [=====] - 22s 194us/step - loss: 0.0601 -  
val\_loss: 0.0566  
Epoch 65/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0604 -  
val\_loss: 0.0750  
Epoch 66/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0604 -  
val\_loss: 0.0726  
Epoch 67/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0610 -  
val\_loss: 0.0601  
Epoch 68/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0626 -  
val\_loss: 0.0865  
Epoch 69/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0613 -  
val\_loss: 0.0710  
Epoch 70/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0636 -  
val\_loss: 0.0581  
Epoch 71/100

115092/115092 [=====] - 22s 189us/step - loss: 0.0610 -  
val\_loss: 0.0733  
Epoch 72/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0608 -  
val\_loss: 0.0683  
Epoch 73/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0608 -  
val\_loss: 0.0612  
Epoch 74/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0615 -  
val\_loss: 0.0547  
Epoch 75/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0620 -  
val\_loss: 0.0683  
Epoch 76/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0640 -  
val\_loss: 0.0535  
Epoch 77/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0628 -  
val\_loss: 0.0631  
Epoch 78/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0633 -  
val\_loss: 0.0658  
Epoch 79/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0642 -  
val\_loss: 0.0629  
Epoch 80/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0645 -  
val\_loss: 0.0692  
Epoch 81/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0673 -  
val\_loss: 0.0617  
Epoch 82/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0636 -  
val\_loss: 0.0592  
Epoch 83/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0651 -  
val\_loss: 0.0693  
Epoch 84/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0688 -  
val\_loss: 0.0576  
Epoch 85/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0667 -  
val\_loss: 0.0672  
Epoch 86/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0659 -  
val\_loss: 0.0589  
Epoch 87/100

```
115092/115092 [=====] - 22s 191us/step - loss: 0.0675 -  
val_loss: 0.0562  
Epoch 88/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0672 -  
val_loss: 0.0515  
Epoch 89/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0699 -  
val_loss: 0.0720  
Epoch 90/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0689 -  
val_loss: 0.0605  
Epoch 91/100  
115092/115092 [=====] - 22s 189us/step - loss: 0.0662 -  
val_loss: 0.0653  
Epoch 92/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0654 -  
val_loss: 0.0574  
Epoch 93/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0675 -  
val_loss: 0.0791  
Epoch 94/100  
115092/115092 [=====] - 22s 190us/step - loss: 0.0648 -  
val_loss: 0.0865  
Epoch 95/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0676 -  
val_loss: 0.0643  
Epoch 96/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0660 -  
val_loss: 0.0679  
Epoch 97/100  
115092/115092 [=====] - 22s 191us/step - loss: 0.0743 -  
val_loss: 0.0790  
Epoch 98/100  
115092/115092 [=====] - 22s 188us/step - loss: 0.0694 -  
val_loss: 0.0648  
Epoch 99/100  
115092/115092 [=====] - 22s 192us/step - loss: 0.0689 -  
val_loss: 0.0656  
Epoch 100/100  
115092/115092 [=====] - 22s 193us/step - loss: 0.0681 -  
val_loss: 0.0645
```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test =np.round(Y_test, 0)
```



```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))
```

```
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:3.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

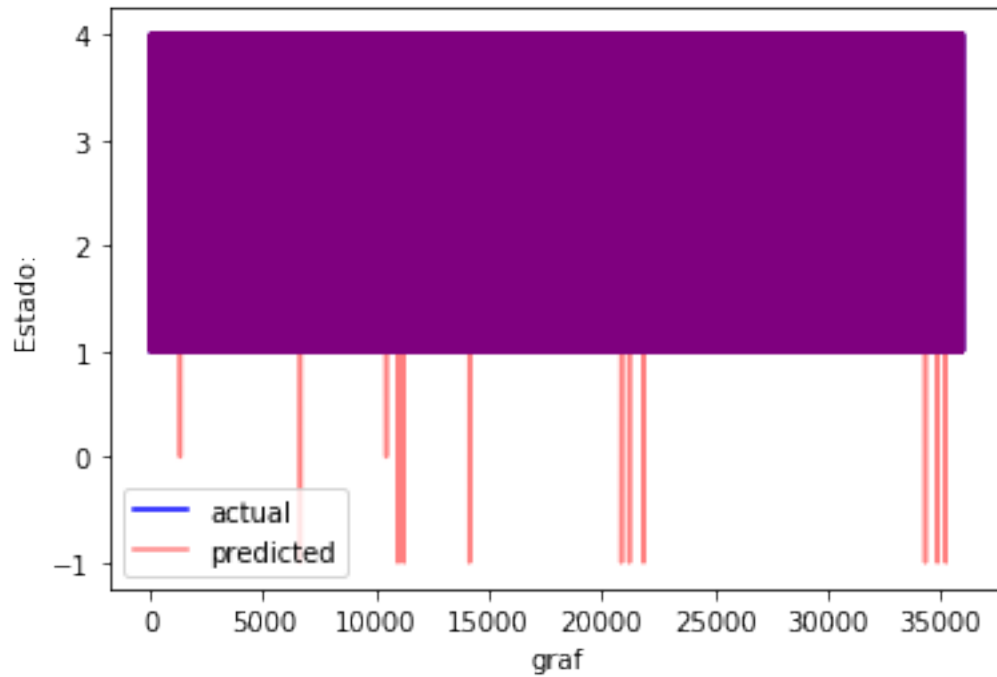
Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
        r2 = r2_score(Y_test, Y_val)
        print (r2)
```

0.9381804505653084

```
[26]: plt.plot((Y_val),
        color="b", label="actual")
```

```
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[27]: 0.9675257875274558
```

```
[ ]:
```

# Wrist\_elux4\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```



```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```



```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```

[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT

```

Dividimos en los conjuntos de validación y entrenamiento:

```

[18]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```

[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```
Dense(60),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')
```

WARNING: Logging before flag parsing goes to stderr.  
W0830 01:06:52.774749 7756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 01:06:52.807661 7756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 01:06:52.818632 7756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 01:06:52.884494 7756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```
[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

W0830 01:06:53.077977 7756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 01:06:53.082966 7756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 21s 183us/step - loss: 0.5862 -  
val\_loss: 0.4021

Epoch 2/100

115092/115092 [=====] - 18s 155us/step - loss: 0.3596 -  
val\_loss: 0.3465

Epoch 3/100

115092/115092 [=====] - 17s 147us/step - loss: 0.2868 -  
val\_loss: 0.3225

Epoch 4/100

115092/115092 [=====] - 17s 147us/step - loss: 0.2499 -  
val\_loss: 0.2759

Epoch 5/100

115092/115092 [=====] - 17s 148us/step - loss: 0.2254 -  
val\_loss: 0.2536

Epoch 6/100

115092/115092 [=====] - 17s 148us/step - loss: 0.2070 -  
val\_loss: 0.1961

Epoch 7/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1929 -  
val\_loss: 0.2113

Epoch 8/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1796 -  
val\_loss: 0.2095

Epoch 9/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1695 -  
val\_loss: 0.1752

Epoch 10/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1601 -  
val\_loss: 0.1568

Epoch 11/100

115092/115092 [=====] - 17s 149us/step - loss: 0.1529 -  
val\_loss: 0.1502

Epoch 12/100

115092/115092 [=====] - 17s 149us/step - loss: 0.1466 -  
val\_loss: 0.1469

Epoch 13/100

115092/115092 [=====] - 17s 148us/step - loss: 0.1413 -  
val\_loss: 0.1252

Epoch 14/100

115092/115092 [=====] - 18s 153us/step - loss: 0.1367 -  
val\_loss: 0.1482

Epoch 15/100

115092/115092 [=====] - 17s 150us/step - loss: 0.1338 -  
val\_loss: 0.1427

Epoch 16/100

115092/115092 [=====] - 17s 149us/step - loss: 0.1296 -

val\_loss: 0.1588  
Epoch 17/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1276 -  
val\_loss: 0.1366  
Epoch 18/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1250 -  
val\_loss: 0.1260  
Epoch 19/100  
115092/115092 [=====] - 17s 151us/step - loss: 0.1227 -  
val\_loss: 0.1468  
Epoch 20/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1205 -  
val\_loss: 0.1227  
Epoch 21/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1185 -  
val\_loss: 0.1260  
Epoch 22/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1161 -  
val\_loss: 0.1305  
Epoch 23/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1148 -  
val\_loss: 0.1211  
Epoch 24/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1139 -  
val\_loss: 0.1313  
Epoch 25/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1122 -  
val\_loss: 0.1108  
Epoch 26/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.1110 -  
val\_loss: 0.1108  
Epoch 27/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1100 -  
val\_loss: 0.1108  
Epoch 28/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.1086 -  
val\_loss: 0.1142  
Epoch 29/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1072 -  
val\_loss: 0.1465  
Epoch 30/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1064 -  
val\_loss: 0.1096  
Epoch 31/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1053 -  
val\_loss: 0.1178  
Epoch 32/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1040 -

val\_loss: 0.0990  
Epoch 33/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.1032 -  
val\_loss: 0.1156  
Epoch 34/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.1023 -  
val\_loss: 0.0990  
Epoch 35/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1015 -  
val\_loss: 0.0971  
Epoch 36/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.1012 -  
val\_loss: 0.1137  
Epoch 37/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0993 -  
val\_loss: 0.1133  
Epoch 38/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0990 -  
val\_loss: 0.1094  
Epoch 39/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0986 -  
val\_loss: 0.1000  
Epoch 40/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0974 -  
val\_loss: 0.1145  
Epoch 41/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0969 -  
val\_loss: 0.1011  
Epoch 42/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0963 -  
val\_loss: 0.1060  
Epoch 43/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0959 -  
val\_loss: 0.1003  
Epoch 44/100  
115092/115092 [=====] - 17s 151us/step - loss: 0.0950 -  
val\_loss: 0.1066  
Epoch 45/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0945 -  
val\_loss: 0.1013  
Epoch 46/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0944 -  
val\_loss: 0.0835  
Epoch 47/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0939 -  
val\_loss: 0.0896  
Epoch 48/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0931 -

val\_loss: 0.1029  
Epoch 49/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0926 -  
val\_loss: 0.1196  
Epoch 50/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0918 -  
val\_loss: 0.1167  
Epoch 51/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0918 -  
val\_loss: 0.0908  
Epoch 52/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0914 -  
val\_loss: 0.0938  
Epoch 53/100  
115092/115092 [=====] - 17s 152us/step - loss: 0.0908 -  
val\_loss: 0.0905  
Epoch 54/100  
115092/115092 [=====] - 20s 175us/step - loss: 0.0900 -  
val\_loss: 0.1008  
Epoch 55/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0896 -  
val\_loss: 0.0925  
Epoch 56/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0893 -  
val\_loss: 0.0999  
Epoch 57/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0885 -  
val\_loss: 0.0815  
Epoch 58/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0883 -  
val\_loss: 0.1069  
Epoch 59/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0878 -  
val\_loss: 0.0933  
Epoch 60/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0868 -  
val\_loss: 0.1227  
Epoch 61/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0867 -  
val\_loss: 0.0857  
Epoch 62/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0862 -  
val\_loss: 0.0850  
Epoch 63/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0859 -  
val\_loss: 0.0819  
Epoch 64/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0856 -



val\_loss: 0.0947  
Epoch 65/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0853 -  
val\_loss: 0.1076  
Epoch 66/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0846 -  
val\_loss: 0.0860  
Epoch 67/100  
115092/115092 [=====] - 17s 151us/step - loss: 0.0850 -  
val\_loss: 0.0909  
Epoch 68/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0844 -  
val\_loss: 0.0914  
Epoch 69/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0839 -  
val\_loss: 0.0854  
Epoch 70/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0835 -  
val\_loss: 0.0901  
Epoch 71/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0831 -  
val\_loss: 0.0873  
Epoch 72/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0832 -  
val\_loss: 0.0963  
Epoch 73/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0830 -  
val\_loss: 0.1037  
Epoch 74/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0819 -  
val\_loss: 0.0915  
Epoch 75/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0817 -  
val\_loss: 0.0795  
Epoch 76/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0816 -  
val\_loss: 0.0881  
Epoch 77/100  
115092/115092 [=====] - 17s 147us/step - loss: 0.0812 -  
val\_loss: 0.0832  
Epoch 78/100  
115092/115092 [=====] - 17s 147us/step - loss: 0.0807 -  
val\_loss: 0.0861  
Epoch 79/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0806 -  
val\_loss: 0.0933  
Epoch 80/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0806 -

val\_loss: 0.0850  
Epoch 81/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0803 -  
val\_loss: 0.0948  
Epoch 82/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0804 -  
val\_loss: 0.0903  
Epoch 83/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0799 -  
val\_loss: 0.0749  
Epoch 84/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0796 -  
val\_loss: 0.0957  
Epoch 85/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0798 -  
val\_loss: 0.0790  
Epoch 86/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0791 -  
val\_loss: 0.1069  
Epoch 87/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0793 -  
val\_loss: 0.0775  
Epoch 88/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0787 -  
val\_loss: 0.0836  
Epoch 89/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0785 -  
val\_loss: 0.0891  
Epoch 90/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0788 -  
val\_loss: 0.0826  
Epoch 91/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0784 -  
val\_loss: 0.0873  
Epoch 92/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0787 -  
val\_loss: 0.0875  
Epoch 93/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0784 -  
val\_loss: 0.0909  
Epoch 94/100  
115092/115092 [=====] - 17s 148us/step - loss: 0.0777 -  
val\_loss: 0.0890  
Epoch 95/100  
115092/115092 [=====] - 17s 149us/step - loss: 0.0782 -  
val\_loss: 0.0807  
Epoch 96/100  
115092/115092 [=====] - 17s 150us/step - loss: 0.0781 -

```

val_loss: 0.0908
Epoch 97/100
115092/115092 [=====] - 17s 149us/step - loss: 0.0778 -
val_loss: 0.0915
Epoch 98/100
115092/115092 [=====] - 17s 149us/step - loss: 0.0776 -
val_loss: 0.1007
Epoch 99/100
115092/115092 [=====] - 17s 147us/step - loss: 0.0774 -
val_loss: 0.1024
Epoch 100/100
115092/115092 [=====] - 17s 148us/step - loss: 0.0774 -
val_loss: 0.0976

```

```
[21]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[22]: Y_test = np.round(Y_test, 0)
```

```
[23]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:2.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.

```

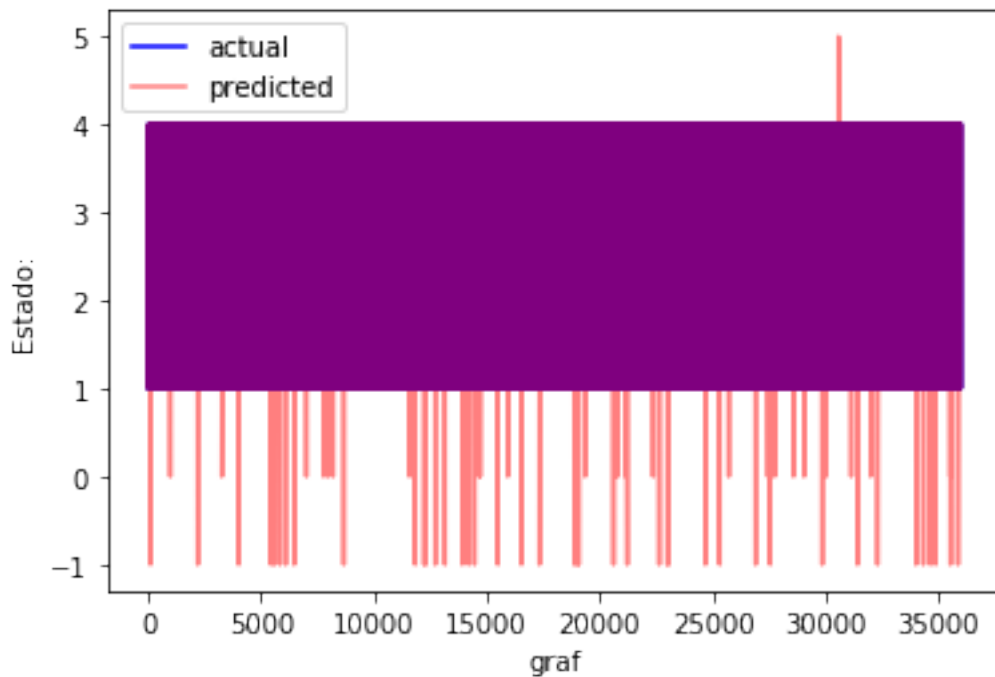
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[24]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9473311782077163

```
[25]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[26]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[26]: 0.9611310367837184
```

```
[:]
```

# Wrist\_elux5\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```



```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```



```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0830 01:41:06.452198 12492 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 01:41:06.471148 12492 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 01:41:06.475136 12492 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 01:41:06.558912 12492 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0830 01:41:06.767384 12492 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 01:41:06.774366 12492 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is

deprecated. Please use `tf.compat.v1.assign` instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 21s 179us/step - loss: 0.5560 -  
val\_loss: 0.4178

Epoch 2/100

115092/115092 [=====] - 19s 164us/step - loss: 0.3313 -  
val\_loss: 0.2706

Epoch 3/100

115092/115092 [=====] - 19s 164us/step - loss: 0.2469 -  
val\_loss: 0.2499

Epoch 4/100

115092/115092 [=====] - 19s 165us/step - loss: 0.2044 -  
val\_loss: 0.1897

Epoch 5/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1794 -  
val\_loss: 0.1732

Epoch 6/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1604 -  
val\_loss: 0.1548

Epoch 7/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1475 -  
val\_loss: 0.2112

Epoch 8/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1375 -  
val\_loss: 0.1244

Epoch 9/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1285 -  
val\_loss: 0.1504

Epoch 10/100

115092/115092 [=====] - 19s 165us/step - loss: 0.1210 -  
val\_loss: 0.1193

Epoch 11/100

115092/115092 [=====] - 19s 165us/step - loss: 0.1160 -  
val\_loss: 0.1149

Epoch 12/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1117 -  
val\_loss: 0.1154

Epoch 13/100

115092/115092 [=====] - 19s 164us/step - loss: 0.1069 -  
val\_loss: 0.1104

Epoch 14/100

115092/115092 [=====] - 19s 163us/step - loss: 0.1036 -  
val\_loss: 0.1029

Epoch 15/100

115092/115092 [=====] - 19s 163us/step - loss: 0.1002 -



```
val_loss: 0.1002
Epoch 16/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0973 -
val_loss: 0.0874
Epoch 17/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0938 -
val_loss: 0.0958
Epoch 18/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0918 -
val_loss: 0.0982
Epoch 19/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0904 -
val_loss: 0.0804
Epoch 20/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0886 -
val_loss: 0.0869
Epoch 21/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0865 -
val_loss: 0.0827
Epoch 22/100
115092/115092 [=====] - 19s 162us/step - loss: 0.0856 -
val_loss: 0.0877
Epoch 23/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0840 -
val_loss: 0.0811
Epoch 24/100
115092/115092 [=====] - 20s 170us/step - loss: 0.0821 -
val_loss: 0.1282
Epoch 25/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0813 -
val_loss: 0.0782
Epoch 26/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0799 -
val_loss: 0.0844
Epoch 27/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0790 -
val_loss: 0.0739
Epoch 28/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0786 -
val_loss: 0.0681
Epoch 29/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0771 -
val_loss: 0.0756
Epoch 30/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0757 -
val_loss: 0.0819
Epoch 31/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0752 -
```

val\_loss: 0.0748  
Epoch 32/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0751 -  
val\_loss: 0.0723  
Epoch 33/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0737 -  
val\_loss: 0.0867  
Epoch 34/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0732 -  
val\_loss: 0.0839  
Epoch 35/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0729 -  
val\_loss: 0.0635  
Epoch 36/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0716 -  
val\_loss: 0.0828  
Epoch 37/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0714 -  
val\_loss: 0.0651  
Epoch 38/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0705 -  
val\_loss: 0.0706  
Epoch 39/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0707 -  
val\_loss: 0.0710  
Epoch 40/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0702 -  
val\_loss: 0.0735  
Epoch 41/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0697 -  
val\_loss: 0.0904  
Epoch 42/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0691 -  
val\_loss: 0.0767  
Epoch 43/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0688 -  
val\_loss: 0.0743  
Epoch 44/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0686 -  
val\_loss: 0.0737  
Epoch 45/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0677 -  
val\_loss: 0.0701  
Epoch 46/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0674 -  
val\_loss: 0.0750  
Epoch 47/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0670 -

```
val_loss: 0.0716
Epoch 48/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0664 -
val_loss: 0.0711
Epoch 49/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0668 -
val_loss: 0.0657
Epoch 50/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0665 -
val_loss: 0.0575
Epoch 51/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0658 -
val_loss: 0.0614
Epoch 52/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0657 -
val_loss: 0.0692
Epoch 53/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0652 -
val_loss: 0.0780
Epoch 54/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0653 -
val_loss: 0.0635
Epoch 55/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0649 -
val_loss: 0.0652
Epoch 56/100
115092/115092 [=====] - 19s 162us/step - loss: 0.0650 -
val_loss: 0.0647
Epoch 57/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0639 -
val_loss: 0.0560
Epoch 58/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0643 -
val_loss: 0.0762
Epoch 59/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0640 -
val_loss: 0.0663
Epoch 60/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0642 -
val_loss: 0.0737
Epoch 61/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0637 -
val_loss: 0.0631
Epoch 62/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0635 -
val_loss: 0.0688
Epoch 63/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0639 -
```

```
val_loss: 0.0587
Epoch 64/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0636 -
val_loss: 0.0880
Epoch 65/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0633 -
val_loss: 0.0694
Epoch 66/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0626 -
val_loss: 0.0649
Epoch 67/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0614 -
val_loss: 0.0575
Epoch 68/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0616 -
val_loss: 0.0732
Epoch 69/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0609 -
val_loss: 0.0618
Epoch 70/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0607 -
val_loss: 0.0683
Epoch 71/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0597 -
val_loss: 0.0589
Epoch 72/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0603 -
val_loss: 0.0558
Epoch 73/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0600 -
val_loss: 0.0524
Epoch 74/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0595 -
val_loss: 0.0702
Epoch 75/100
115092/115092 [=====] - 19s 162us/step - loss: 0.0592 -
val_loss: 0.0552
Epoch 76/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0590 -
val_loss: 0.0615
Epoch 77/100
115092/115092 [=====] - 19s 161us/step - loss: 0.0586 -
val_loss: 0.0658
Epoch 78/100
115092/115092 [=====] - 19s 161us/step - loss: 0.0591 -
val_loss: 0.0642
Epoch 79/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0585 -
```

```
val_loss: 0.0590
Epoch 80/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0587 -
val_loss: 0.0645
Epoch 81/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0591 -
val_loss: 0.0674
Epoch 82/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0582 -
val_loss: 0.0656
Epoch 83/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0579 -
val_loss: 0.0537
Epoch 84/100
115092/115092 [=====] - 19s 162us/step - loss: 0.0579 -
val_loss: 0.0541
Epoch 85/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0574 -
val_loss: 0.0829
Epoch 86/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0579 -
val_loss: 0.0504
Epoch 87/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0570 -
val_loss: 0.0548
Epoch 88/100
115092/115092 [=====] - 19s 162us/step - loss: 0.0573 -
val_loss: 0.0635
Epoch 89/100
115092/115092 [=====] - 19s 161us/step - loss: 0.0566 -
val_loss: 0.0611
Epoch 90/100
115092/115092 [=====] - 19s 161us/step - loss: 0.0567 -
val_loss: 0.0595
Epoch 91/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0571 -
val_loss: 0.0559
Epoch 92/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0564 -
val_loss: 0.0583
Epoch 93/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0570 -
val_loss: 0.0638
Epoch 94/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0561 -
val_loss: 0.0629
Epoch 95/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0567 -
```

```

val_loss: 0.0570
Epoch 96/100
115092/115092 [=====] - 21s 182us/step - loss: 0.0563 -
val_loss: 0.0494
Epoch 97/100
115092/115092 [=====] - 19s 167us/step - loss: 0.0565 -
val_loss: 0.0563
Epoch 98/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0558 -
val_loss: 0.0606
Epoch 99/100
115092/115092 [=====] - 19s 164us/step - loss: 0.0555 -
val_loss: 0.0532
Epoch 100/100
115092/115092 [=====] - 19s 167us/step - loss: 0.0558 -
val_loss: 0.0521

```

```
[21]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[22]: Y_test = np.round(Y_test, 0)
```

```
[23]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.

```

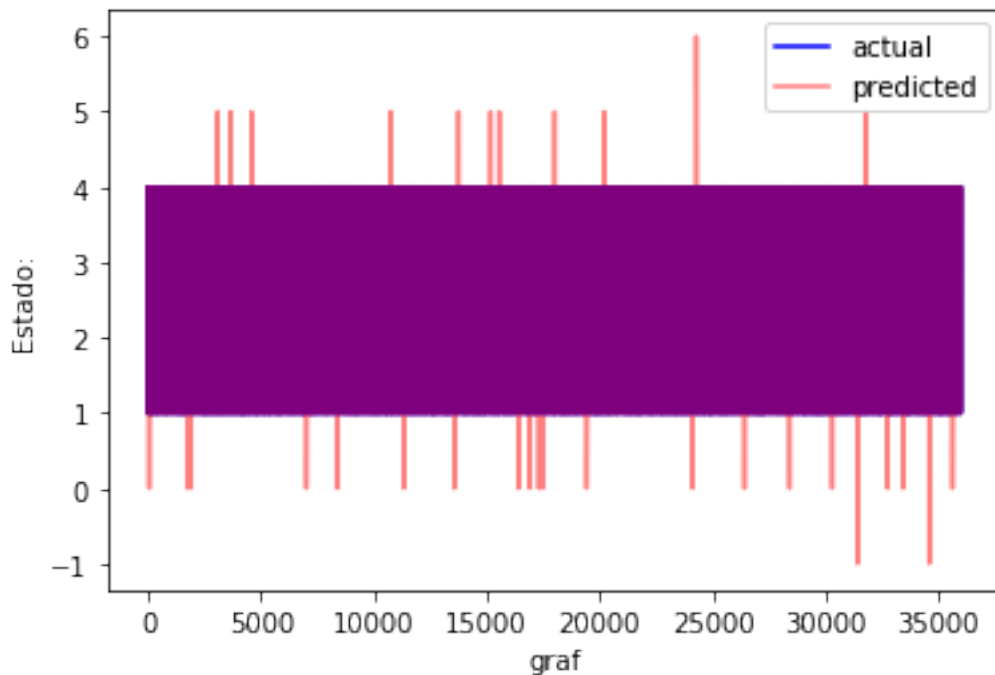
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[24]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9632204478987918

```
[25]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[26]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[26]: 0.9761447993994495
```

```
[:]
```



# Wrist\_elux7\_mae\_Adadel\_final

August 30, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```



```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```



```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

Dense(60),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(30),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0830 02:17:23.968223 6340 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0830 02:17:23.981184 6340 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0830 02:17:23.984184 6340 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0830 02:17:24.078895 6340 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0830 02:17:24.318292 6340 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0830 02:17:24.324240 6340 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 23s 203us/step - loss: 0.5144 -  
val\_loss: 0.4035

Epoch 2/100

115092/115092 [=====] - 23s 196us/step - loss: 0.2823 -  
val\_loss: 0.2418

Epoch 3/100

115092/115092 [=====] - 23s 197us/step - loss: 0.2173 -  
val\_loss: 0.1953

Epoch 4/100

115092/115092 [=====] - 23s 197us/step - loss: 0.1869 -  
val\_loss: 0.1814

Epoch 5/100

115092/115092 [=====] - 23s 198us/step - loss: 0.1686 -  
val\_loss: 0.1688

Epoch 6/100

115092/115092 [=====] - 23s 196us/step - loss: 0.1575 -  
val\_loss: 0.1683

Epoch 7/100

115092/115092 [=====] - 23s 198us/step - loss: 0.1468 -  
val\_loss: 0.1328

Epoch 8/100

115092/115092 [=====] - 23s 196us/step - loss: 0.1427 -  
val\_loss: 0.1350

Epoch 9/100

115092/115092 [=====] - 23s 197us/step - loss: 0.1364 -  
val\_loss: 0.1455

Epoch 10/100

115092/115092 [=====] - 23s 196us/step - loss: 0.1324 -  
val\_loss: 0.1454

Epoch 11/100

115092/115092 [=====] - 23s 197us/step - loss: 0.1285 -  
val\_loss: 0.1273

Epoch 12/100

115092/115092 [=====] - 23s 197us/step - loss: 0.1258 -  
val\_loss: 0.1417

Epoch 13/100

115092/115092 [=====] - 23s 197us/step - loss: 0.1229 -  
val\_loss: 0.1282

Epoch 14/100

115092/115092 [=====] - 23s 196us/step - loss: 0.1226 -  
val\_loss: 0.1154  
Epoch 15/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.1056 -  
val\_loss: 0.1073  
Epoch 16/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0948 -  
val\_loss: 0.1141  
Epoch 17/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0921 -  
val\_loss: 0.0848  
Epoch 18/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0911 -  
val\_loss: 0.0927  
Epoch 19/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0881 -  
val\_loss: 0.1075  
Epoch 20/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0863 -  
val\_loss: 0.0938  
Epoch 21/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0840 -  
val\_loss: 0.0953  
Epoch 22/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0833 -  
val\_loss: 0.0850  
Epoch 23/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0818 -  
val\_loss: 0.1343  
Epoch 24/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0814 -  
val\_loss: 0.0835  
Epoch 25/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0796 -  
val\_loss: 0.0820  
Epoch 26/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0771 -  
val\_loss: 0.0750  
Epoch 27/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0764 -  
val\_loss: 0.0780  
Epoch 28/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0741 -  
val\_loss: 0.0680  
Epoch 29/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0745 -  
val\_loss: 0.0795  
Epoch 30/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0724 -  
val\_loss: 0.0751  
Epoch 31/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0721 -  
val\_loss: 0.0768  
Epoch 32/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0717 -  
val\_loss: 0.0634  
Epoch 33/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0707 -  
val\_loss: 0.0780  
Epoch 34/100  
115092/115092 [=====] - 23s 196us/step - loss: 0.0705 -  
val\_loss: 0.0776  
Epoch 35/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0688 -  
val\_loss: 0.0810  
Epoch 36/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0682 -  
val\_loss: 0.0772  
Epoch 37/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0688 -  
val\_loss: 0.0897  
Epoch 38/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0678 -  
val\_loss: 0.0644  
Epoch 39/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0675 -  
val\_loss: 0.0636  
Epoch 40/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0661 -  
val\_loss: 0.0653  
Epoch 41/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0668 -  
val\_loss: 0.0645  
Epoch 42/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0661 -  
val\_loss: 0.0787  
Epoch 43/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0656 -  
val\_loss: 0.0733  
Epoch 44/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0642 -  
val\_loss: 0.0654  
Epoch 45/100  
115092/115092 [=====] - 23s 201us/step - loss: 0.0649 -  
val\_loss: 0.0593  
Epoch 46/100

115092/115092 [=====] - 23s 197us/step - loss: 0.0626 -  
val\_loss: 0.0760  
Epoch 47/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0623 -  
val\_loss: 0.0654  
Epoch 48/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0624 -  
val\_loss: 0.0688  
Epoch 49/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0629 -  
val\_loss: 0.0658  
Epoch 50/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0616 -  
val\_loss: 0.0669  
Epoch 51/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0614 -  
val\_loss: 0.0697  
Epoch 52/100  
115092/115092 [=====] - 23s 203us/step - loss: 0.0614 -  
val\_loss: 0.0535  
Epoch 53/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0607 -  
val\_loss: 0.0578  
Epoch 54/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0602 -  
val\_loss: 0.0674  
Epoch 55/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0605 -  
val\_loss: 0.0615  
Epoch 56/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0595 -  
val\_loss: 0.0685  
Epoch 57/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0593 -  
val\_loss: 0.0560  
Epoch 58/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0587 -  
val\_loss: 0.0689  
Epoch 59/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0588 -  
val\_loss: 0.0681  
Epoch 60/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0594 -  
val\_loss: 0.0607  
Epoch 61/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0588 -  
val\_loss: 0.0688  
Epoch 62/100

115092/115092 [=====] - 23s 199us/step - loss: 0.0579 -  
val\_loss: 0.0540  
Epoch 63/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0577 -  
val\_loss: 0.0540  
Epoch 64/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0582 -  
val\_loss: 0.1376  
Epoch 65/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0583 -  
val\_loss: 0.0680  
Epoch 66/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0570 -  
val\_loss: 0.0755  
Epoch 67/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0566 -  
val\_loss: 0.0639  
Epoch 68/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0563 -  
val\_loss: 0.0585  
Epoch 69/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0557 -  
val\_loss: 0.0691  
Epoch 70/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0566 -  
val\_loss: 0.0715  
Epoch 71/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0559 -  
val\_loss: 0.0617  
Epoch 72/100  
115092/115092 [=====] - 23s 199us/step - loss: 0.0555 -  
val\_loss: 0.0523  
Epoch 73/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0556 -  
val\_loss: 0.0834  
Epoch 74/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0566 -  
val\_loss: 0.0519  
Epoch 75/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0551 -  
val\_loss: 0.0591  
Epoch 76/100  
115092/115092 [=====] - 23s 198us/step - loss: 0.0556 -  
val\_loss: 0.0571  
Epoch 77/100  
115092/115092 [=====] - 23s 197us/step - loss: 0.0533 -  
val\_loss: 0.0579  
Epoch 78/100

```

115092/115092 [=====] - 23s 197us/step - loss: 0.0555 -
val_loss: 0.0559
Epoch 79/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0540 -
val_loss: 0.0587
Epoch 80/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0540 -
val_loss: 0.0550
Epoch 81/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0532 -
val_loss: 0.0598
Epoch 82/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0533 -
val_loss: 0.0654
Epoch 83/100
115092/115092 [=====] - 23s 196us/step - loss: 0.0535 -
val_loss: 0.0527
Epoch 84/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0519 -
val_loss: 0.0453
Epoch 85/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0527 -
val_loss: 0.0621
Epoch 86/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0518 -
val_loss: 0.0567
Epoch 87/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0525 -
val_loss: 0.0447
Epoch 88/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0511 -
val_loss: 0.0560
Epoch 89/100
115092/115092 [=====] - 23s 196us/step - loss: 0.0524 -
val_loss: 0.0545
Epoch 90/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0515 -
val_loss: 0.0630
Epoch 91/100
115092/115092 [=====] - 23s 199us/step - loss: 0.0518 -
val_loss: 0.0635
Epoch 92/100
115092/115092 [=====] - 23s 198us/step - loss: 0.0505 -
val_loss: 0.0579
Epoch 93/100
115092/115092 [=====] - 22s 190us/step - loss: 0.0511 -
val_loss: 0.0539
Epoch 94/100

```



```

115092/115092 [=====] - 22s 191us/step - loss: 0.0515 -
val_loss: 0.0457
Epoch 95/100
115092/115092 [=====] - 23s 197us/step - loss: 0.0518 -
val_loss: 0.0516
Epoch 96/100
115092/115092 [=====] - 21s 186us/step - loss: 0.0495 -
val_loss: 0.0511
Epoch 97/100
115092/115092 [=====] - 21s 186us/step - loss: 0.0512 -
val_loss: 0.0580
Epoch 98/100
115092/115092 [=====] - 22s 191us/step - loss: 0.0500 -
val_loss: 0.0704
Epoch 99/100
115092/115092 [=====] - 22s 190us/step - loss: 0.0502 -
val_loss: 0.0618
Epoch 100/100
115092/115092 [=====] - 22s 190us/step - loss: 0.0511 -
val_loss: 0.0520

```

```
[21]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[22]: Y_test = np.round(Y_test, 0)
```

```
[23]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.

```

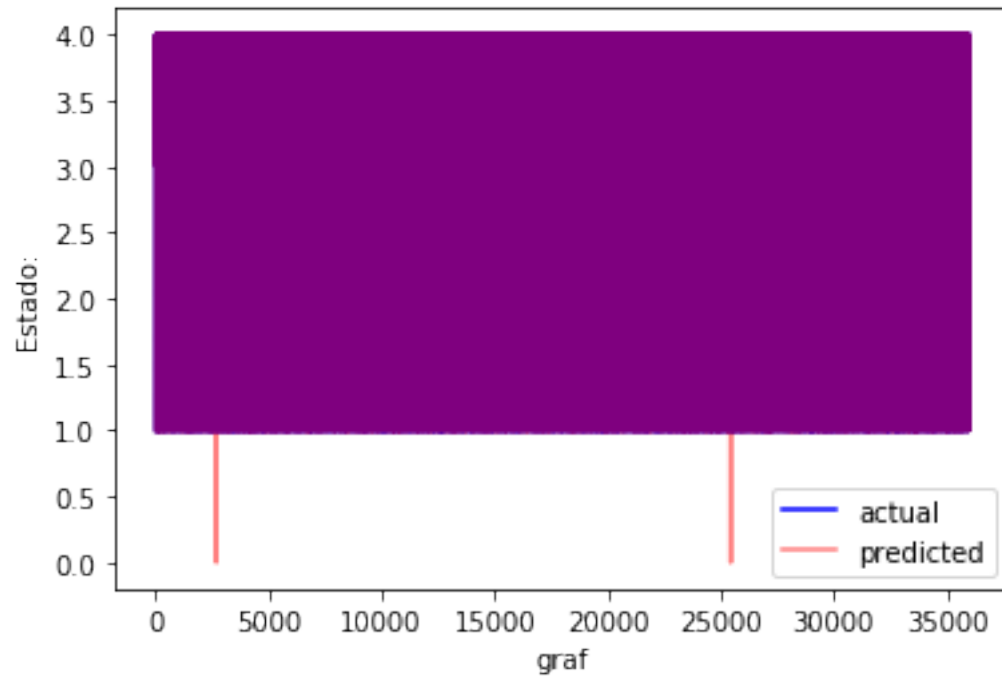
```
Estado: 1., predicted:1.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[24]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9557391972854581

```
[25]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[26]: Y_val2 = np.array(Y_val.T)[0]  
Accu=Y_val2==Y_test  
accur=np.sum(Accu)  
accur/len(Y_val)
```

```
[26]: 0.9726415881224456
```

```
[:]
```

# Wrist\_seluelux5\_mae\_Adadel\_final

September 3, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```



```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```



```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```

[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT
3

```

Dividimos en los conjuntos de validación y entrenamiento:

```

[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```

[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),

```

```

    Activation('selu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('selu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.

W0903 03:28:41.603379 13956 deprecation\_wrapper.py:119] From C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0903 03:28:41.636319 13956 deprecation\_wrapper.py:119] From C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.

W0903 03:28:41.647271 13956 deprecation\_wrapper.py:119] From C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is deprecated. Please use tf.random.uniform instead.

W0903 03:28:41.686223 13956 deprecation.py:323] From C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\backend\tensorflow\_backend.py:3217: add\_dispatch\_support.<locals>.wrapper (from tensorflow.python.ops.array\_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where

W0903 03:28:41.735028 13956 deprecation\_wrapper.py:119] From C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790: The name tf.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0903 03:28:42.005303 13956 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0903 03:28:42.012285 13956 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 24s 206us/step - loss: 0.5585 -  
val\_loss: 0.3931

Epoch 2/100

115092/115092 [=====] - 20s 176us/step - loss: 0.3358 -  
val\_loss: 0.2913

Epoch 3/100

115092/115092 [=====] - 21s 178us/step - loss: 0.2545 -  
val\_loss: 0.2299

Epoch 4/100

115092/115092 [=====] - 21s 181us/step - loss: 0.2128 -  
val\_loss: 0.1831

Epoch 5/100

115092/115092 [=====] - 20s 176us/step - loss: 0.1832 -  
val\_loss: 0.2128

Epoch 6/100

115092/115092 [=====] - 20s 176us/step - loss: 0.1635 -  
val\_loss: 0.1689

Epoch 7/100

115092/115092 [=====] - 20s 177us/step - loss: 0.1488 -  
val\_loss: 0.1398

Epoch 8/100

115092/115092 [=====] - 20s 177us/step - loss: 0.1387 -  
val\_loss: 0.1428

Epoch 9/100

115092/115092 [=====] - 20s 176us/step - loss: 0.1312 -  
val\_loss: 0.1190

Epoch 10/100

115092/115092 [=====] - 20s 177us/step - loss: 0.1249 -  
val\_loss: 0.1288

Epoch 11/100

115092/115092 [=====] - 21s 179us/step - loss: 0.1186 -  
val\_loss: 0.1248

Epoch 12/100

115092/115092 [=====] - 20s 176us/step - loss: 0.1133 -  
val\_loss: 0.1568

Epoch 13/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.1096 -  
val\_loss: 0.1081  
Epoch 14/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.1061 -  
val\_loss: 0.1116  
Epoch 15/100  
115092/115092 [=====] - 20s 178us/step - loss: 0.1030 -  
val\_loss: 0.0952  
Epoch 16/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.1000 -  
val\_loss: 0.1047  
Epoch 17/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.0974 -  
val\_loss: 0.0994  
Epoch 18/100  
115092/115092 [=====] - 20s 178us/step - loss: 0.0953 -  
val\_loss: 0.0945  
Epoch 19/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.0927 -  
val\_loss: 0.0956  
Epoch 20/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.0907 -  
val\_loss: 0.0908  
Epoch 21/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.0885 -  
val\_loss: 0.0780  
Epoch 22/100  
115092/115092 [=====] - 21s 178us/step - loss: 0.0871 -  
val\_loss: 0.1046  
Epoch 23/100  
115092/115092 [=====] - 21s 180us/step - loss: 0.0855 -  
val\_loss: 0.1073  
Epoch 24/100  
115092/115092 [=====] - 20s 177us/step - loss: 0.0846 -  
val\_loss: 0.0787  
Epoch 25/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0829 -  
val\_loss: 0.0831  
Epoch 26/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0820 -  
val\_loss: 0.0725  
Epoch 27/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0808 -  
val\_loss: 0.0814  
Epoch 28/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0799 -  
val\_loss: 0.0941

Epoch 29/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0783 -  
val\_loss: 0.0840  
Epoch 30/100  
115092/115092 [=====] - 20s 171us/step - loss: 0.0775 -  
val\_loss: 0.0806  
Epoch 31/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0755 -  
val\_loss: 0.0740  
Epoch 32/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0751 -  
val\_loss: 0.0965  
Epoch 33/100  
115092/115092 [=====] - 20s 171us/step - loss: 0.0749 -  
val\_loss: 0.0769  
Epoch 34/100  
115092/115092 [=====] - 20s 176us/step - loss: 0.0739 -  
val\_loss: 0.0854  
Epoch 35/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0734 -  
val\_loss: 0.0844  
Epoch 36/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0721 -  
val\_loss: 0.0771  
Epoch 37/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0718 -  
val\_loss: 0.0739  
Epoch 38/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0712 -  
val\_loss: 0.0832  
Epoch 39/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0706 -  
val\_loss: 0.0770  
Epoch 40/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0704 -  
val\_loss: 0.0743  
Epoch 41/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0697 -  
val\_loss: 0.0682  
Epoch 42/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0689 -  
val\_loss: 0.0761  
Epoch 43/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0685 -  
val\_loss: 0.0673  
Epoch 44/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0686 -  
val\_loss: 0.0724



Epoch 45/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0676 -  
val\_loss: 0.0622  
Epoch 46/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0682 -  
val\_loss: 0.0652  
Epoch 47/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0678 -  
val\_loss: 0.0658  
Epoch 48/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0675 -  
val\_loss: 0.0628  
Epoch 49/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0669 -  
val\_loss: 0.0779  
Epoch 50/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0670 -  
val\_loss: 0.0985  
Epoch 51/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0668 -  
val\_loss: 0.0773  
Epoch 52/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0662 -  
val\_loss: 0.0691  
Epoch 53/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0658 -  
val\_loss: 0.0549  
Epoch 54/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0658 -  
val\_loss: 0.0582  
Epoch 55/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0653 -  
val\_loss: 0.0704  
Epoch 56/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0648 -  
val\_loss: 0.0822  
Epoch 57/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0649 -  
val\_loss: 0.0690  
Epoch 58/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0637 -  
val\_loss: 0.0802  
Epoch 59/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0643 -  
val\_loss: 0.0846  
Epoch 60/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0635 -  
val\_loss: 0.0911

Epoch 61/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0633 -  
val\_loss: 0.0627  
Epoch 62/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0625 -  
val\_loss: 0.0806  
Epoch 63/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0623 -  
val\_loss: 0.0678  
Epoch 64/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0618 -  
val\_loss: 0.0642  
Epoch 65/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0622 -  
val\_loss: 0.0596  
Epoch 66/100  
115092/115092 [=====] - 20s 173us/step - loss: 0.0608 -  
val\_loss: 0.0556  
Epoch 67/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0609 -  
val\_loss: 0.0968  
Epoch 68/100  
115092/115092 [=====] - 20s 173us/step - loss: 0.0607 -  
val\_loss: 0.0510  
Epoch 69/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0602 -  
val\_loss: 0.0750  
Epoch 70/100  
115092/115092 [=====] - 20s 175us/step - loss: 0.0597 -  
val\_loss: 0.0637  
Epoch 71/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0593 -  
val\_loss: 0.1047  
Epoch 72/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0593 -  
val\_loss: 0.0752  
Epoch 73/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0594 -  
val\_loss: 0.0665  
Epoch 74/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0587 -  
val\_loss: 0.0570  
Epoch 75/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0585 -  
val\_loss: 0.0547  
Epoch 76/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0588 -  
val\_loss: 0.0824

Epoch 77/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0585 -  
val\_loss: 0.0595  
Epoch 78/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0585 -  
val\_loss: 0.0566  
Epoch 79/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0583 -  
val\_loss: 0.0546  
Epoch 80/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0577 -  
val\_loss: 0.0561  
Epoch 81/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0578 -  
val\_loss: 0.0616  
Epoch 82/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0575 -  
val\_loss: 0.0681  
Epoch 83/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0576 -  
val\_loss: 0.0812  
Epoch 84/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0577 -  
val\_loss: 0.0773  
Epoch 85/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0581 -  
val\_loss: 0.0526  
Epoch 86/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0566 -  
val\_loss: 0.0608  
Epoch 87/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0569 -  
val\_loss: 0.0643  
Epoch 88/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0577 -  
val\_loss: 0.0560  
Epoch 89/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0572 -  
val\_loss: 0.0669  
Epoch 90/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0570 -  
val\_loss: 0.0662  
Epoch 91/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0570 -  
val\_loss: 0.0689  
Epoch 92/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0563 -  
val\_loss: 0.0537

```

Epoch 93/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0566 -
val_loss: 0.0752
Epoch 94/100
115092/115092 [=====] - 20s 171us/step - loss: 0.0576 -
val_loss: 0.0725
Epoch 95/100
115092/115092 [=====] - 20s 170us/step - loss: 0.0573 -
val_loss: 0.0652
Epoch 96/100
115092/115092 [=====] - 21s 181us/step - loss: 0.0563 -
val_loss: 0.0614
Epoch 97/100
115092/115092 [=====] - 20s 178us/step - loss: 0.0572 -
val_loss: 0.0579
Epoch 98/100
115092/115092 [=====] - 20s 170us/step - loss: 0.0567 -
val_loss: 0.0595
Epoch 99/100
115092/115092 [=====] - 19s 166us/step - loss: 0.0567 -
val_loss: 0.0560
Epoch 100/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0564 -
val_loss: 0.0620

```

```

[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

Train on 115092 samples, validate on 28773 samples

```

Epoch 1/100
115092/115092 [=====] - 19s 167us/step - loss: 0.0576 -
val_loss: 0.0536
Epoch 2/100
115092/115092 [=====] - 19s 165us/step - loss: 0.0580 -
val_loss: 0.0571
Epoch 3/100
115092/115092 [=====] - 19s 163us/step - loss: 0.0576 -
val_loss: 0.0580
Epoch 4/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0570 -
val_loss: 0.0694
Epoch 5/100
115092/115092 [=====] - 20s 176us/step - loss: 0.0568 -
val_loss: 0.0517

```

Epoch 6/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0575 -  
val\_loss: 0.0556  
Epoch 7/100  
115092/115092 [=====] - 20s 178us/step - loss: 0.0582 -  
val\_loss: 0.0745  
Epoch 8/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0585 -  
val\_loss: 0.0694  
Epoch 9/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0584 -  
val\_loss: 0.0840  
Epoch 10/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0592 -  
val\_loss: 0.0656  
Epoch 11/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0591 -  
val\_loss: 0.0564  
Epoch 12/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0593 -  
val\_loss: 0.0526  
Epoch 13/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0596 -  
val\_loss: 0.0633  
Epoch 14/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0590 -  
val\_loss: 0.0770  
Epoch 15/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0609 -  
val\_loss: 0.0773  
Epoch 16/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0596 -  
val\_loss: 0.0585  
Epoch 17/100  
115092/115092 [=====] - 20s 169us/step - loss: 0.0606 -  
val\_loss: 0.0545  
Epoch 18/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0598 -  
val\_loss: 0.0803  
Epoch 19/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0605 -  
val\_loss: 0.0716  
Epoch 20/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0597 -  
val\_loss: 0.0577  
Epoch 21/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0594 -  
val\_loss: 0.0714

Epoch 22/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0598 -  
val\_loss: 0.0571  
Epoch 23/100  
115092/115092 [=====] - 20s 171us/step - loss: 0.0599 -  
val\_loss: 0.0770  
Epoch 24/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0596 -  
val\_loss: 0.0605  
Epoch 25/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0596 -  
val\_loss: 0.0611  
Epoch 26/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0597 -  
val\_loss: 0.0854  
Epoch 27/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0597 -  
val\_loss: 0.0715  
Epoch 28/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0586 -  
val\_loss: 0.0634  
Epoch 29/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0577 -  
val\_loss: 0.0508  
Epoch 30/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0568 -  
val\_loss: 0.0734  
Epoch 31/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0570 -  
val\_loss: 0.0531  
Epoch 32/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0569 -  
val\_loss: 0.0577  
Epoch 33/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0567 -  
val\_loss: 0.0583  
Epoch 34/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0561 -  
val\_loss: 0.0630  
Epoch 35/100  
115092/115092 [=====] - 20s 173us/step - loss: 0.0558 -  
val\_loss: 0.0518  
Epoch 36/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0561 -  
val\_loss: 0.0729  
Epoch 37/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0563 -  
val\_loss: 0.0564

Epoch 38/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0550 -  
val\_loss: 0.0648  
Epoch 39/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0561 -  
val\_loss: 0.0534  
Epoch 40/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0555 -  
val\_loss: 0.0655  
Epoch 41/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0551 -  
val\_loss: 0.0541  
Epoch 42/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0558 -  
val\_loss: 0.0538  
Epoch 43/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0565 -  
val\_loss: 0.0546  
Epoch 44/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0558 -  
val\_loss: 0.0565  
Epoch 45/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0561 -  
val\_loss: 0.0593  
Epoch 46/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0565 -  
val\_loss: 0.0510  
Epoch 47/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0560 -  
val\_loss: 0.0534  
Epoch 48/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0558 -  
val\_loss: 0.0512  
Epoch 49/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0553 -  
val\_loss: 0.0652  
Epoch 50/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0552 -  
val\_loss: 0.0693  
Epoch 51/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0546 -  
val\_loss: 0.0643  
Epoch 52/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0560 -  
val\_loss: 0.0505  
Epoch 53/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0550 -  
val\_loss: 0.0620

Epoch 54/100  
115092/115092 [=====] - 20s 173us/step - loss: 0.0561 -  
val\_loss: 0.0579  
Epoch 55/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0560 -  
val\_loss: 0.0567  
Epoch 56/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0566 -  
val\_loss: 0.0616  
Epoch 57/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0566 -  
val\_loss: 0.0540  
Epoch 58/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0572 -  
val\_loss: 0.0736  
Epoch 59/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0568 -  
val\_loss: 0.0618  
Epoch 60/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0566 -  
val\_loss: 0.0618  
Epoch 61/100  
115092/115092 [=====] - 19s 165us/step - loss: 0.0569 -  
val\_loss: 0.0540  
Epoch 62/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0574 -  
val\_loss: 0.0660  
Epoch 63/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0554 -  
val\_loss: 0.0735  
Epoch 64/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0584 -  
val\_loss: 0.0520  
Epoch 65/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0568 -  
val\_loss: 0.0588  
Epoch 66/100  
115092/115092 [=====] - 20s 173us/step - loss: 0.0564 -  
val\_loss: 0.0562  
Epoch 67/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0571 -  
val\_loss: 0.0644  
Epoch 68/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0570 -  
val\_loss: 0.0654  
Epoch 69/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0560 -  
val\_loss: 0.0840



Epoch 70/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.0555 -  
val\_loss: 0.0614  
Epoch 71/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.0566 -  
val\_loss: 0.0678  
Epoch 72/100  
115092/115092 [=====] - 20s 172us/step - loss: 0.0563 -  
val\_loss: 0.0644  
Epoch 73/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0579 -  
val\_loss: 0.0670  
Epoch 74/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0563 -  
val\_loss: 0.0671  
Epoch 75/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0567 -  
val\_loss: 0.0639  
Epoch 76/100  
115092/115092 [=====] - 19s 167us/step - loss: 0.0562 -  
val\_loss: 0.0562  
Epoch 77/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0569 -  
val\_loss: 0.0661  
Epoch 78/100  
115092/115092 [=====] - 19s 166us/step - loss: 0.0571 -  
val\_loss: 0.0631  
Epoch 79/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0568 -  
val\_loss: 0.0490  
Epoch 80/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0567 -  
val\_loss: 0.0542  
Epoch 81/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0564 -  
val\_loss: 0.0586  
Epoch 82/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0564 -  
val\_loss: 0.0623  
Epoch 83/100  
115092/115092 [=====] - 19s 168us/step - loss: 0.0563 -  
val\_loss: 0.0889  
Epoch 84/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.0559 -  
val\_loss: 0.0608  
Epoch 85/100  
115092/115092 [=====] - 20s 170us/step - loss: 0.0565 -  
val\_loss: 0.0787

```
Epoch 86/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0569 -
val_loss: 0.0522
Epoch 87/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0560 -
val_loss: 0.0676
Epoch 88/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0566 -
val_loss: 0.0757
Epoch 89/100
115092/115092 [=====] - 20s 170us/step - loss: 0.0566 -
val_loss: 0.0536
Epoch 90/100
115092/115092 [=====] - 20s 171us/step - loss: 0.0569 -
val_loss: 0.0655
Epoch 91/100
115092/115092 [=====] - 20s 175us/step - loss: 0.0557 -
val_loss: 0.0641
Epoch 92/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0561 -
val_loss: 0.0596
Epoch 93/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0560 -
val_loss: 0.0563
Epoch 94/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0568 -
val_loss: 0.0588
Epoch 95/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0568 -
val_loss: 0.0620
Epoch 96/100
115092/115092 [=====] - 19s 168us/step - loss: 0.0567 -
val_loss: 0.0696
Epoch 97/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0575 -
val_loss: 0.0672
Epoch 98/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0578 -
val_loss: 0.0558
Epoch 99/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0585 -
val_loss: 0.0671
Epoch 100/100
115092/115092 [=====] - 19s 169us/step - loss: 0.0574 -
val_loss: 0.0526
```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

```
[24]: for i in range(30):  
      YA= np.squeeze(np.asarray(Y_val))  
      label = YA[i]  
      prediction = Y_test[i]  
      print("Estado: "+ np.array2string(label) + ", predicted:" + np.  
      →array2string(prediction))
```

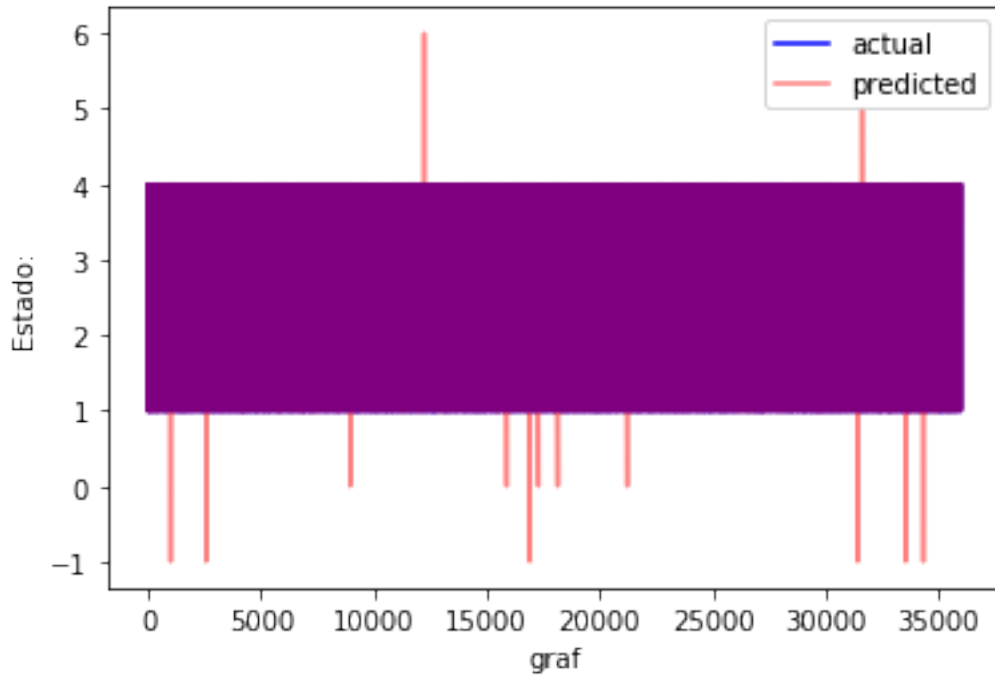
```
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 4., predicted:4.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score  
      r2 = r2_score(Y_test, Y_val)  
      print (r2)
```

```
0.9600521866248108
```

```
[26]: plt.plot((Y_val),
             color="b", label="actual")
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

[27]: 0.977840798509745

[ ]:

# Wrist\_seluelux5\_mae\_Adadel\_final

August 31, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```



```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```



```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```

[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT

```

Dividimos en los conjuntos de validación y entrenamiento:

```

[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```

[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('selu'),

```

```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('selu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0829 22:04:57.830875 31448 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0829 22:04:57.864757 31448 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0829 22:04:57.877796 31448 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0829 22:04:57.919682 31448 deprecation.py:323] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:3217:  
add\_dispatch\_support.<locals>.wrapper (from tensorflow.python.ops.array\_ops) is  
deprecated and will be removed in a future version.

Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where

W0829 22:04:57.966590 31448 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      →validation_split=0.2)

```

W0829 22:04:58.267327 31448 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-

packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is deprecated. Please use tf.compat.v1.assign\_add instead.

W0829 22:04:58.274302 31448 deprecation\_wrapper.py:119] From C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is deprecated. Please use tf.compat.v1.assign instead.

Train on 84868 samples, validate on 21218 samples

Epoch 1/100  
84868/84868 [=====] - 19s 226us/step - loss: 0.4211 - val\_loss: 0.2801  
Epoch 2/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.2503 - val\_loss: 0.2200  
Epoch 3/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.1915 - val\_loss: 0.1721  
Epoch 4/100  
84868/84868 [=====] - 15s 181us/step - loss: 0.1607 - val\_loss: 0.1665  
Epoch 5/100  
84868/84868 [=====] - 15s 182us/step - loss: 0.1422 - val\_loss: 0.1556  
Epoch 6/100  
84868/84868 [=====] - 16s 183us/step - loss: 0.1306 - val\_loss: 0.1213  
Epoch 7/100  
84868/84868 [=====] - 15s 183us/step - loss: 0.1214 - val\_loss: 0.1268  
Epoch 8/100  
84868/84868 [=====] - 15s 182us/step - loss: 0.1145 - val\_loss: 0.1465  
Epoch 9/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.1098 - val\_loss: 0.1213  
Epoch 10/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.1053 - val\_loss: 0.0991  
Epoch 11/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.1011 - val\_loss: 0.0942  
Epoch 12/100  
84868/84868 [=====] - 16s 183us/step - loss: 0.0975 - val\_loss: 0.0972  
Epoch 13/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0949 -

```
val_loss: 0.0974
Epoch 14/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0906 -
val_loss: 0.0905
Epoch 15/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0871 -
val_loss: 0.0932
Epoch 16/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0838 -
val_loss: 0.0904
Epoch 17/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0821 -
val_loss: 0.0878
Epoch 18/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0802 -
val_loss: 0.0864
Epoch 19/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0788 -
val_loss: 0.0744
Epoch 20/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0773 -
val_loss: 0.0749
Epoch 21/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0763 -
val_loss: 0.0766
Epoch 22/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0755 -
val_loss: 0.0909
Epoch 23/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0738 -
val_loss: 0.0965
Epoch 24/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0735 -
val_loss: 0.0708
Epoch 25/100
84868/84868 [=====] - 16s 194us/step - loss: 0.0725 -
val_loss: 0.0931
Epoch 26/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0721 -
val_loss: 0.0745
Epoch 27/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0712 -
val_loss: 0.0804
Epoch 28/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0704 -
val_loss: 0.0848
Epoch 29/100
84868/84868 [=====] - 17s 201us/step - loss: 0.0701 -
```



```
val_loss: 0.0759
Epoch 30/100
84868/84868 [=====] - 17s 202us/step - loss: 0.0688 -
val_loss: 0.0822
Epoch 31/100
84868/84868 [=====] - 17s 197us/step - loss: 0.0683 -
val_loss: 0.0838
Epoch 32/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0683 -
val_loss: 0.0711
Epoch 33/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0673 -
val_loss: 0.0656
Epoch 34/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0662 -
val_loss: 0.0696
Epoch 35/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0656 -
val_loss: 0.0721
Epoch 36/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0656 -
val_loss: 0.0727
Epoch 37/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0653 -
val_loss: 0.0670
Epoch 38/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0648 -
val_loss: 0.0641
Epoch 39/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0643 -
val_loss: 0.0733
Epoch 40/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0650 -
val_loss: 0.0751
Epoch 41/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0634 -
val_loss: 0.0679
Epoch 42/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0642 -
val_loss: 0.0637
Epoch 43/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0629 -
val_loss: 0.0569
Epoch 44/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0628 -
val_loss: 0.0741
Epoch 45/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0614 -
```

val\_loss: 0.0679  
Epoch 46/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.0603 -  
val\_loss: 0.0712  
Epoch 47/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.0599 -  
val\_loss: 0.0719  
Epoch 48/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.0601 -  
val\_loss: 0.0641  
Epoch 49/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.0599 -  
val\_loss: 0.0622  
Epoch 50/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0600 -  
val\_loss: 0.0609  
Epoch 51/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0597 -  
val\_loss: 0.0662  
Epoch 52/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0589 -  
val\_loss: 0.0688  
Epoch 53/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0586 -  
val\_loss: 0.0713  
Epoch 54/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0584 -  
val\_loss: 0.0667  
Epoch 55/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.0586 -  
val\_loss: 0.0684  
Epoch 56/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0585 -  
val\_loss: 0.0613  
Epoch 57/100  
84868/84868 [=====] - 15s 180us/step - loss: 0.0585 -  
val\_loss: 0.0592  
Epoch 58/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0583 -  
val\_loss: 0.0610  
Epoch 59/100  
84868/84868 [=====] - 15s 181us/step - loss: 0.0580 -  
val\_loss: 0.0726  
Epoch 60/100  
84868/84868 [=====] - 15s 181us/step - loss: 0.0579 -  
val\_loss: 0.0688  
Epoch 61/100  
84868/84868 [=====] - 15s 182us/step - loss: 0.0573 -

```
val_loss: 0.0678
Epoch 62/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0575 -
val_loss: 0.0666
Epoch 63/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0574 -
val_loss: 0.0581
Epoch 64/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0572 -
val_loss: 0.0635
Epoch 65/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0566 -
val_loss: 0.0629
Epoch 66/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0553 -
val_loss: 0.0671
Epoch 67/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0555 -
val_loss: 0.0630
Epoch 68/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0555 -
val_loss: 0.0679
Epoch 69/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0550 -
val_loss: 0.0587
Epoch 70/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0548 -
val_loss: 0.0623
Epoch 71/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0542 -
val_loss: 0.0580
Epoch 72/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0538 -
val_loss: 0.0576
Epoch 73/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0542 -
val_loss: 0.0624
Epoch 74/100
84868/84868 [=====] - 16s 183us/step - loss: 0.0552 -
val_loss: 0.0587
Epoch 75/100
84868/84868 [=====] - 16s 185us/step - loss: 0.0545 -
val_loss: 0.0665
Epoch 76/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0537 -
val_loss: 0.0596
Epoch 77/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0534 -
```

```
val_loss: 0.0645
Epoch 78/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0531 -
val_loss: 0.0656
Epoch 79/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0536 -
val_loss: 0.0608
Epoch 80/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0531 -
val_loss: 0.0562
Epoch 81/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0521 -
val_loss: 0.0528
Epoch 82/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0519 -
val_loss: 0.0565
Epoch 83/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0521 -
val_loss: 0.0623
Epoch 84/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0517 -
val_loss: 0.0563
Epoch 85/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0515 -
val_loss: 0.0529
Epoch 86/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0512 -
val_loss: 0.0569
Epoch 87/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0517 -
val_loss: 0.0501
Epoch 88/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0514 -
val_loss: 0.0513
Epoch 89/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0515 -
val_loss: 0.0541
Epoch 90/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0521 -
val_loss: 0.0521
Epoch 91/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0500 -
val_loss: 0.0545
Epoch 92/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0509 -
val_loss: 0.0550
Epoch 93/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0503 -
```

```

val_loss: 0.0641
Epoch 94/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0502 -
val_loss: 0.0533
Epoch 95/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0504 -
val_loss: 0.0571
Epoch 96/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0504 -
val_loss: 0.0568
Epoch 97/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0499 -
val_loss: 0.0535
Epoch 98/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0497 -
val_loss: 0.0546
Epoch 99/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0493 -
val_loss: 0.0554
Epoch 100/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0505 -
val_loss: 0.0557

```

```

[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 84868 samples, validate on 21218 samples
Epoch 1/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0502 -
val_loss: 0.0488
Epoch 2/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0501 -
val_loss: 0.0592
Epoch 3/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0505 -
val_loss: 0.0683
Epoch 4/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0502 -
val_loss: 0.0499
Epoch 5/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0499 -
val_loss: 0.0507
Epoch 6/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0498 -

```

```
val_loss: 0.0511
Epoch 7/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0497 -
val_loss: 0.0567
Epoch 8/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0498 -
val_loss: 0.0636
Epoch 9/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0499 -
val_loss: 0.0536
Epoch 10/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0497 -
val_loss: 0.0548
Epoch 11/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0494 -
val_loss: 0.0592
Epoch 12/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0494 -
val_loss: 0.0524
Epoch 13/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0495 -
val_loss: 0.0558
Epoch 14/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0490 -
val_loss: 0.0609
Epoch 15/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0498 -
val_loss: 0.0530
Epoch 16/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0494 -
val_loss: 0.0537
Epoch 17/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0499 -
val_loss: 0.0532
Epoch 18/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0492 -
val_loss: 0.0723
Epoch 19/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0490 -
val_loss: 0.0436
Epoch 20/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0491 -
val_loss: 0.0481
Epoch 21/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0494 -
val_loss: 0.0627
Epoch 22/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0498 -
```

```
val_loss: 0.0519
Epoch 23/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0492 -
val_loss: 0.0558
Epoch 24/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0493 -
val_loss: 0.0677
Epoch 25/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0493 -
val_loss: 0.0616
Epoch 26/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0487 -
val_loss: 0.0505
Epoch 27/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0488 -
val_loss: 0.0456
Epoch 28/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0480 -
val_loss: 0.0520
Epoch 29/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0494 -
val_loss: 0.0493
Epoch 30/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0491 -
val_loss: 0.0537
Epoch 31/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0483 -
val_loss: 0.0490
Epoch 32/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0484 -
val_loss: 0.0590
Epoch 33/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0487 -
val_loss: 0.0478
Epoch 34/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0481 -
val_loss: 0.0560
Epoch 35/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0491 -
val_loss: 0.0517
Epoch 36/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0486 -
val_loss: 0.0596
Epoch 37/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0493 -
val_loss: 0.0563
Epoch 38/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0514 -
```

```
val_loss: 0.0549
Epoch 39/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0495 -
val_loss: 0.0500
Epoch 40/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0498 -
val_loss: 0.0663
Epoch 41/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0496 -
val_loss: 0.0492
Epoch 42/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0503 -
val_loss: 0.0482
Epoch 43/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0498 -
val_loss: 0.0587
Epoch 44/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0501 -
val_loss: 0.0526
Epoch 45/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0501 -
val_loss: 0.0501
Epoch 46/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0495 -
val_loss: 0.0530
Epoch 47/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0490 -
val_loss: 0.0547
Epoch 48/100
84868/84868 [=====] - 15s 180us/step - loss: 0.0506 -
val_loss: 0.0506
Epoch 49/100
84868/84868 [=====] - 16s 194us/step - loss: 0.0505 -
val_loss: 0.0635
Epoch 50/100
84868/84868 [=====] - 17s 202us/step - loss: 0.0493 -
val_loss: 0.0573
Epoch 51/100
84868/84868 [=====] - 17s 204us/step - loss: 0.0494 -
val_loss: 0.0599
Epoch 52/100
84868/84868 [=====] - 17s 199us/step - loss: 0.0487 -
val_loss: 0.0494
Epoch 53/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0498 -
val_loss: 0.0555
Epoch 54/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0497 -
```



val\_loss: 0.0590  
Epoch 55/100  
84868/84868 [=====] - 18s 213us/step - loss: 0.0500 -  
val\_loss: 0.0700  
Epoch 56/100  
84868/84868 [=====] - 17s 200us/step - loss: 0.0490 -  
val\_loss: 0.0461  
Epoch 57/100  
84868/84868 [=====] - 17s 197us/step - loss: 0.0484 -  
val\_loss: 0.0514  
Epoch 58/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0495 -  
val\_loss: 0.0478  
Epoch 59/100  
84868/84868 [=====] - 17s 194us/step - loss: 0.0480 -  
val\_loss: 0.0623  
Epoch 60/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0487 -  
val\_loss: 0.0507  
Epoch 61/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0496 -  
val\_loss: 0.0473  
Epoch 62/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0499 -  
val\_loss: 0.0506  
Epoch 63/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0486 -  
val\_loss: 0.0775  
Epoch 64/100  
84868/84868 [=====] - 17s 194us/step - loss: 0.0492 -  
val\_loss: 0.0496  
Epoch 65/100  
84868/84868 [=====] - 17s 196us/step - loss: 0.0500 -  
val\_loss: 0.0784  
Epoch 66/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0499 -  
val\_loss: 0.0471  
Epoch 67/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0507 -  
val\_loss: 0.0640  
Epoch 68/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0504 -  
val\_loss: 0.0477  
Epoch 69/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0489 -  
val\_loss: 0.0475  
Epoch 70/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0497 -

val\_loss: 0.0464  
Epoch 71/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0492 -  
val\_loss: 0.0540  
Epoch 72/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0492 -  
val\_loss: 0.0508  
Epoch 73/100  
84868/84868 [=====] - 17s 204us/step - loss: 0.0484 -  
val\_loss: 0.0615  
Epoch 74/100  
84868/84868 [=====] - 17s 197us/step - loss: 0.0484 -  
val\_loss: 0.0530  
Epoch 75/100  
84868/84868 [=====] - 18s 207us/step - loss: 0.0489 -  
val\_loss: 0.0501  
Epoch 76/100  
84868/84868 [=====] - 18s 217us/step - loss: 0.0487 -  
val\_loss: 0.0450  
Epoch 77/100  
84868/84868 [=====] - 17s 205us/step - loss: 0.0485 -  
val\_loss: 0.0718  
Epoch 78/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0483 -  
val\_loss: 0.0485  
Epoch 79/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0486 -  
val\_loss: 0.0527  
Epoch 80/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0484 -  
val\_loss: 0.0411  
Epoch 81/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0480 -  
val\_loss: 0.0442  
Epoch 82/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0485 -  
val\_loss: 0.0562  
Epoch 83/100  
84868/84868 [=====] - 15s 178us/step - loss: 0.0489 -  
val\_loss: 0.0515  
Epoch 84/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0484 -  
val\_loss: 0.0468  
Epoch 85/100  
84868/84868 [=====] - 15s 178us/step - loss: 0.0495 -  
val\_loss: 0.0463  
Epoch 86/100  
84868/84868 [=====] - 15s 179us/step - loss: 0.0479 -

```

val_loss: 0.0468
Epoch 87/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0473 -
val_loss: 0.0567
Epoch 88/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0478 -
val_loss: 0.0476
Epoch 89/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0486 -
val_loss: 0.0487
Epoch 90/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0488 -
val_loss: 0.0542
Epoch 91/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0470 -
val_loss: 0.0468
Epoch 92/100
84868/84868 [=====] - 15s 177us/step - loss: 0.0482 -
val_loss: 0.0465
Epoch 93/100
84868/84868 [=====] - 15s 176us/step - loss: 0.0480 -
val_loss: 0.0530
Epoch 94/100
84868/84868 [=====] - 15s 177us/step - loss: 0.0478 -
val_loss: 0.0469
Epoch 95/100
84868/84868 [=====] - 15s 177us/step - loss: 0.0494 -
val_loss: 0.0491
Epoch 96/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0484 -
val_loss: 0.0552
Epoch 97/100
84868/84868 [=====] - 15s 179us/step - loss: 0.0487 -
val_loss: 0.0633
Epoch 98/100
84868/84868 [=====] - 15s 177us/step - loss: 0.0484 -
val_loss: 0.0442
Epoch 99/100
84868/84868 [=====] - 15s 177us/step - loss: 0.0468 -
val_loss: 0.0426
Epoch 100/100
84868/84868 [=====] - 15s 178us/step - loss: 0.0481 -
val_loss: 0.0552

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))
```

```
Estado: 3., predicted:3.
Estado: 1., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

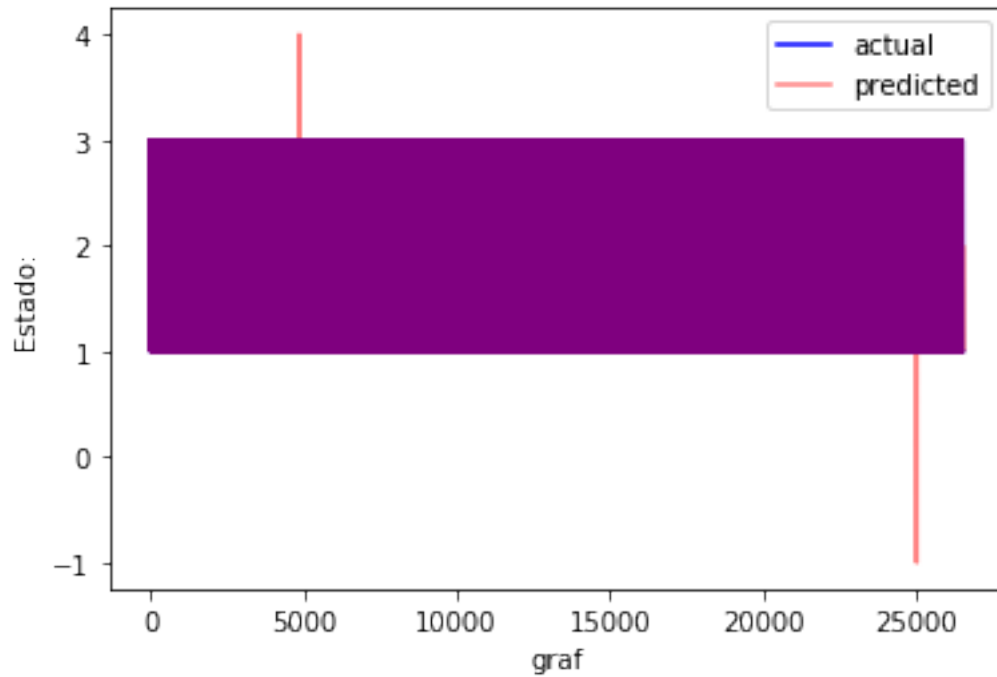
Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
        r2 = r2_score(Y_test, Y_val)
        print (r2)
```

0.8923511571157836

```
[26]: plt.plot((Y_val),
        color="b", label="actual")
```

```
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[27]: 0.9690822713219214
```

```
[ ]:
```

# TFM\_wrist\_elux4\_mae\_Adadel\_final

August 21, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```



```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```



```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[23]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

Entrenamos la red:

```

[24]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

Train on 84868 samples, validate on 21218 samples

```

Epoch 1/100
84868/84868 [=====] - 15s 181us/step - loss: 0.4074 -
val_loss: 0.2950
Epoch 2/100
84868/84868 [=====] - 12s 137us/step - loss: 0.2448 -
val_loss: 0.2329
Epoch 3/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1999 -
val_loss: 0.1898
Epoch 4/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1763 -
val_loss: 0.1624
Epoch 5/100
84868/84868 [=====] - 12s 147us/step - loss: 0.1620 -
val_loss: 0.1461
Epoch 6/100
84868/84868 [=====] - 12s 143us/step - loss: 0.1517 -
val_loss: 0.1501
Epoch 7/100
84868/84868 [=====] - 12s 147us/step - loss: 0.1429 -
val_loss: 0.1437
Epoch 8/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1363 -
val_loss: 0.1312
Epoch 9/100
84868/84868 [=====] - 12s 142us/step - loss: 0.1305 -
val_loss: 0.1508
Epoch 10/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1254 -
val_loss: 0.1165
Epoch 11/100
84868/84868 [=====] - 13s 148us/step - loss: 0.1213 -

```

```
val_loss: 0.1399
Epoch 12/100
84868/84868 [=====] - 12s 144us/step - loss: 0.1183 -
val_loss: 0.1313
Epoch 13/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1157 -
val_loss: 0.1373
Epoch 14/100
84868/84868 [=====] - 12s 139us/step - loss: 0.1128 -
val_loss: 0.1326
Epoch 15/100
84868/84868 [=====] - 12s 137us/step - loss: 0.1108 -
val_loss: 0.1060
Epoch 16/100
84868/84868 [=====] - 12s 136us/step - loss: 0.1084 -
val_loss: 0.1185
Epoch 17/100
84868/84868 [=====] - 11s 133us/step - loss: 0.1071 -
val_loss: 0.1065
Epoch 18/100
84868/84868 [=====] - 11s 133us/step - loss: 0.1045 -
val_loss: 0.1149
Epoch 19/100
84868/84868 [=====] - 11s 134us/step - loss: 0.1033 -
val_loss: 0.1060
Epoch 20/100
84868/84868 [=====] - 11s 133us/step - loss: 0.1021 -
val_loss: 0.1173
Epoch 21/100
84868/84868 [=====] - 11s 132us/step - loss: 0.1002 -
val_loss: 0.1101
Epoch 22/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0985 -
val_loss: 0.0917
Epoch 23/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0972 -
val_loss: 0.1184
Epoch 24/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0960 -
val_loss: 0.1014
Epoch 25/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0955 -
val_loss: 0.0972
Epoch 26/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0950 -
val_loss: 0.0986
Epoch 27/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0932 -
```



```
val_loss: 0.1078
Epoch 28/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0924 -
val_loss: 0.0936
Epoch 29/100
84868/84868 [=====] - 11s 134us/step - loss: 0.0918 -
val_loss: 0.1078
Epoch 30/100
84868/84868 [=====] - 11s 135us/step - loss: 0.0908 -
val_loss: 0.1083
Epoch 31/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0901 -
val_loss: 0.0989
Epoch 32/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0894 -
val_loss: 0.1030
Epoch 33/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0888 -
val_loss: 0.0890
Epoch 34/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0882 -
val_loss: 0.0956
Epoch 35/100
84868/84868 [=====] - 11s 134us/step - loss: 0.0876 -
val_loss: 0.1056
Epoch 36/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0871 -
val_loss: 0.0870
Epoch 37/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0860 -
val_loss: 0.0998
Epoch 38/100
84868/84868 [=====] - 12s 144us/step - loss: 0.0854 -
val_loss: 0.0930
Epoch 39/100
84868/84868 [=====] - 12s 144us/step - loss: 0.0850 -
val_loss: 0.0924
Epoch 40/100
84868/84868 [=====] - 12s 143us/step - loss: 0.0846 -
val_loss: 0.0913
Epoch 41/100
84868/84868 [=====] - 12s 145us/step - loss: 0.0832 -
val_loss: 0.0913
Epoch 42/100
84868/84868 [=====] - 12s 144us/step - loss: 0.0833 -
val_loss: 0.0985
Epoch 43/100
84868/84868 [=====] - 12s 144us/step - loss: 0.0832 -
```

```
val_loss: 0.0940
Epoch 44/100
84868/84868 [=====] - 12s 146us/step - loss: 0.0832 -
val_loss: 0.1046
Epoch 45/100
84868/84868 [=====] - 12s 146us/step - loss: 0.0826 -
val_loss: 0.1055
Epoch 46/100
84868/84868 [=====] - 12s 145us/step - loss: 0.0814 -
val_loss: 0.0785
Epoch 47/100
84868/84868 [=====] - 12s 146us/step - loss: 0.0814 -
val_loss: 0.0913
Epoch 48/100
84868/84868 [=====] - 12s 144us/step - loss: 0.0811 -
val_loss: 0.0901
Epoch 49/100
84868/84868 [=====] - 12s 141us/step - loss: 0.0804 -
val_loss: 0.0793
Epoch 50/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0805 -
val_loss: 0.0810
Epoch 51/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0799 -
val_loss: 0.0876
Epoch 52/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0797 -
val_loss: 0.0823
Epoch 53/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0792 -
val_loss: 0.0772
Epoch 54/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0783 -
val_loss: 0.0869
Epoch 55/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0785 -
val_loss: 0.0767
Epoch 56/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0779 -
val_loss: 0.1017
Epoch 57/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0773 -
val_loss: 0.0977
Epoch 58/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0768 -
val_loss: 0.0703
Epoch 59/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0767 -
```

```
val_loss: 0.0856
Epoch 60/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0760 -
val_loss: 0.0753
Epoch 61/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0761 -
val_loss: 0.0738
Epoch 62/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0759 -
val_loss: 0.0731
Epoch 63/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0756 -
val_loss: 0.0803
Epoch 64/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0755 -
val_loss: 0.0641
Epoch 65/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0752 -
val_loss: 0.0976
Epoch 66/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0747 -
val_loss: 0.0869
Epoch 67/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0743 -
val_loss: 0.0701
Epoch 68/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0743 -
val_loss: 0.0778
Epoch 69/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0740 -
val_loss: 0.0822
Epoch 70/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0736 -
val_loss: 0.0916
Epoch 71/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0733 -
val_loss: 0.0763
Epoch 72/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0732 -
val_loss: 0.0869
Epoch 73/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0728 -
val_loss: 0.0954
Epoch 74/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0731 -
val_loss: 0.0844
Epoch 75/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0725 -
```

```
val_loss: 0.0758
Epoch 76/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0727 -
val_loss: 0.0819
Epoch 77/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0727 -
val_loss: 0.0761
Epoch 78/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0722 -
val_loss: 0.0779
Epoch 79/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0726 -
val_loss: 0.0786
Epoch 80/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0718 -
val_loss: 0.0675
Epoch 81/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0716 -
val_loss: 0.0756
Epoch 82/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0709 -
val_loss: 0.0887
Epoch 83/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0708 -
val_loss: 0.0744
Epoch 84/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0711 -
val_loss: 0.0810
Epoch 85/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0707 -
val_loss: 0.0723
Epoch 86/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0703 -
val_loss: 0.0865
Epoch 87/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0707 -
val_loss: 0.0790
Epoch 88/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0705 -
val_loss: 0.0675
Epoch 89/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0696 -
val_loss: 0.0781
Epoch 90/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0697 -
val_loss: 0.0758
Epoch 91/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0695 -
```

```

val_loss: 0.0680
Epoch 92/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0689 -
val_loss: 0.0848
Epoch 93/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0689 -
val_loss: 0.0977
Epoch 94/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0685 -
val_loss: 0.0837
Epoch 95/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0684 -
val_loss: 0.0720
Epoch 96/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0679 -
val_loss: 0.0784
Epoch 97/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0682 -
val_loss: 0.0692
Epoch 98/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0679 -
val_loss: 0.0655
Epoch 99/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0673 -
val_loss: 0.0601
Epoch 100/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0674 -
val_loss: 0.0835

```

```

[25]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 84868 samples, validate on 21218 samples
Epoch 1/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0667 -
val_loss: 0.0720
Epoch 2/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0666 -
val_loss: 0.0674
Epoch 3/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0669 -
val_loss: 0.0683
Epoch 4/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0667 -

```

```
val_loss: 0.0816
Epoch 5/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0666 -
val_loss: 0.0710
Epoch 6/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0663 -
val_loss: 0.0751
Epoch 7/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0663 -
val_loss: 0.0910
Epoch 8/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0661 -
val_loss: 0.0644
Epoch 9/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0661 -
val_loss: 0.0563
Epoch 10/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0656 -
val_loss: 0.0770
Epoch 11/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0655 -
val_loss: 0.0713
Epoch 12/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0655 -
val_loss: 0.0982
Epoch 13/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0658 -
val_loss: 0.0819
Epoch 14/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0650 -
val_loss: 0.0831
Epoch 15/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0652 -
val_loss: 0.0703
Epoch 16/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0647 -
val_loss: 0.0884
Epoch 17/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0645 -
val_loss: 0.0734
Epoch 18/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0642 -
val_loss: 0.0636
Epoch 19/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0648 -
val_loss: 0.0676
Epoch 20/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0645 -
```

```
val_loss: 0.0941
Epoch 21/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0654 -
val_loss: 0.0711
Epoch 22/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0640 -
val_loss: 0.0617
Epoch 23/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0645 -
val_loss: 0.0808
Epoch 24/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0642 -
val_loss: 0.0615
Epoch 25/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0645 -
val_loss: 0.0681
Epoch 26/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0639 -
val_loss: 0.0616
Epoch 27/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0637 -
val_loss: 0.0655
Epoch 28/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0639 -
val_loss: 0.0803
Epoch 29/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0634 -
val_loss: 0.0718
Epoch 30/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0641 -
val_loss: 0.0615
Epoch 31/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0629 -
val_loss: 0.0672
Epoch 32/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0638 -
val_loss: 0.0912
Epoch 33/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0636 -
val_loss: 0.0624
Epoch 34/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0629 -
val_loss: 0.0561
Epoch 35/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0632 -
val_loss: 0.0592
Epoch 36/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0628 -
```

```
val_loss: 0.0666
Epoch 37/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0629 -
val_loss: 0.0568
Epoch 38/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0633 -
val_loss: 0.0717
Epoch 39/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0627 -
val_loss: 0.0880
Epoch 40/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0629 -
val_loss: 0.0540
Epoch 41/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0628 -
val_loss: 0.0690
Epoch 42/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0623 -
val_loss: 0.0712
Epoch 43/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0623 -
val_loss: 0.0856
Epoch 44/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0623 -
val_loss: 0.0730
Epoch 45/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0628 -
val_loss: 0.0728
Epoch 46/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0634 -
val_loss: 0.0622
Epoch 47/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0630 -
val_loss: 0.0675
Epoch 48/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0629 -
val_loss: 0.0565
Epoch 49/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0627 -
val_loss: 0.0712
Epoch 50/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0624 -
val_loss: 0.0752
Epoch 51/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0622 -
val_loss: 0.0807
Epoch 52/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0625 -
```



```
val_loss: 0.0761
Epoch 53/100
84868/84868 [=====] - 12s 141us/step - loss: 0.0615 -
val_loss: 0.0793
Epoch 54/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0620 -
val_loss: 0.0807
Epoch 55/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0625 -
val_loss: 0.0812
Epoch 56/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0615 -
val_loss: 0.0665
Epoch 57/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0620 -
val_loss: 0.0648
Epoch 58/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0623 -
val_loss: 0.0626
Epoch 59/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0620 -
val_loss: 0.0592
Epoch 60/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0612 -
val_loss: 0.0638
Epoch 61/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0621 -
val_loss: 0.0728
Epoch 62/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0618 -
val_loss: 0.0643
Epoch 63/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0620 -
val_loss: 0.0892
Epoch 64/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0620 -
val_loss: 0.0616
Epoch 65/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0617 -
val_loss: 0.0740
Epoch 66/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0611 -
val_loss: 0.0542
Epoch 67/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0614 -
val_loss: 0.0751
Epoch 68/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0610 -
```

```
val_loss: 0.0686
Epoch 69/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0607 -
val_loss: 0.0693
Epoch 70/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0612 -
val_loss: 0.0598
Epoch 71/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0611 -
val_loss: 0.0802
Epoch 72/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0611 -
val_loss: 0.0623
Epoch 73/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0610 -
val_loss: 0.0722
Epoch 74/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0606 -
val_loss: 0.0645
Epoch 75/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0610 -
val_loss: 0.0763
Epoch 76/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0608 -
val_loss: 0.0729
Epoch 77/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0610 -
val_loss: 0.0721
Epoch 78/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0606 -
val_loss: 0.0599
Epoch 79/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0607 -
val_loss: 0.0644
Epoch 80/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0606 -
val_loss: 0.0737
Epoch 81/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0605 -
val_loss: 0.0751
Epoch 82/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0604 -
val_loss: 0.0637
Epoch 83/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0599 -
val_loss: 0.0663
Epoch 84/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0605 -
```

```
val_loss: 0.0753
Epoch 85/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0597 -
val_loss: 0.0600
Epoch 86/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0599 -
val_loss: 0.0609
Epoch 87/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0599 -
val_loss: 0.0572
Epoch 88/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0596 -
val_loss: 0.0711
Epoch 89/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0601 -
val_loss: 0.0541
Epoch 90/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0597 -
val_loss: 0.0615
Epoch 91/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0598 -
val_loss: 0.0572
Epoch 92/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0595 -
val_loss: 0.0574
Epoch 93/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0598 -
val_loss: 0.0531
Epoch 94/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0588 -
val_loss: 0.0511
Epoch 95/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0597 -
val_loss: 0.0628
Epoch 96/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0598 -
val_loss: 0.0670
Epoch 97/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0592 -
val_loss: 0.0818
Epoch 98/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0596 -
val_loss: 0.0786
Epoch 99/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0590 -
val_loss: 0.0634
Epoch 100/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0592 -
```

val\_loss: 0.0581

```
[26]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 84868 samples, validate on 21218 samples

```
Epoch 1/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0593 -
val_loss: 0.0749
Epoch 2/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0590 -
val_loss: 0.0555
Epoch 3/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0592 -
val_loss: 0.0622
Epoch 4/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0590 -
val_loss: 0.0620
Epoch 5/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0586 -
val_loss: 0.0559
Epoch 6/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0594 -
val_loss: 0.0579
Epoch 7/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0587 -
val_loss: 0.0558
Epoch 8/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0593 -
val_loss: 0.0708
Epoch 9/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0586 -
val_loss: 0.0659
Epoch 10/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0587 -
val_loss: 0.0872
Epoch 11/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0592 -
val_loss: 0.0523
Epoch 12/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0583 -
val_loss: 0.0834
Epoch 13/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0581 -
```

```
val_loss: 0.0604
Epoch 14/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0588 -
val_loss: 0.0552
Epoch 15/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0586 -
val_loss: 0.0658
Epoch 16/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0576 -
val_loss: 0.0582
Epoch 17/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0585 -
val_loss: 0.0760
Epoch 18/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0586 -
val_loss: 0.0640
Epoch 19/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0579 -
val_loss: 0.0701
Epoch 20/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0578 -
val_loss: 0.0589
Epoch 21/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0582 -
val_loss: 0.0596
Epoch 22/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0579 -
val_loss: 0.0768
Epoch 23/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0575 -
val_loss: 0.0744
Epoch 24/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0576 -
val_loss: 0.0686
Epoch 25/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0579 -
val_loss: 0.0539
Epoch 26/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0572 -
val_loss: 0.0657
Epoch 27/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0577 -
val_loss: 0.0633
Epoch 28/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0574 -
val_loss: 0.0649
Epoch 29/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0573 -
```

```
val_loss: 0.0502
Epoch 30/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0570 -
val_loss: 0.0574
Epoch 31/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0567 -
val_loss: 0.0651
Epoch 32/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0571 -
val_loss: 0.0560
Epoch 33/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0571 -
val_loss: 0.0568
Epoch 34/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0564 -
val_loss: 0.0515
Epoch 35/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0566 -
val_loss: 0.0617
Epoch 36/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0568 -
val_loss: 0.0657
Epoch 37/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0569 -
val_loss: 0.0513
Epoch 38/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0565 -
val_loss: 0.0658
Epoch 39/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0566 -
val_loss: 0.0495
Epoch 40/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0564 -
val_loss: 0.0627
Epoch 41/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0565 -
val_loss: 0.0712
Epoch 42/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0572 -
val_loss: 0.0575
Epoch 43/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0566 -
val_loss: 0.0524
Epoch 44/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0564 -
val_loss: 0.0817
Epoch 45/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0559 -
```

```
val_loss: 0.0548
Epoch 46/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0562 -
val_loss: 0.0530
Epoch 47/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0563 -
val_loss: 0.0857
Epoch 48/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0568 -
val_loss: 0.0693
Epoch 49/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0559 -
val_loss: 0.0750
Epoch 50/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0558 -
val_loss: 0.0532
Epoch 51/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0560 -
val_loss: 0.0585
Epoch 52/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0557 -
val_loss: 0.0618
Epoch 53/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0564 -
val_loss: 0.0661
Epoch 54/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0558 -
val_loss: 0.0654
Epoch 55/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0561 -
val_loss: 0.0526
Epoch 56/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0558 -
val_loss: 0.0623
Epoch 57/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0556 -
val_loss: 0.0712
Epoch 58/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0507 -
val_loss: 0.0584
Epoch 59/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0481 -
val_loss: 0.0647
Epoch 60/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0482 -
val_loss: 0.0578
Epoch 61/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0476 -
```

```
val_loss: 0.0467
Epoch 62/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0469 -
val_loss: 0.0469
Epoch 63/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0476 -
val_loss: 0.0552
Epoch 64/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0475 -
val_loss: 0.0391
Epoch 65/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0470 -
val_loss: 0.0517
Epoch 66/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0473 -
val_loss: 0.0608
Epoch 67/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0472 -
val_loss: 0.0437
Epoch 68/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0464 -
val_loss: 0.0570
Epoch 69/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0467 -
val_loss: 0.0598
Epoch 70/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0464 -
val_loss: 0.0519
Epoch 71/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0466 -
val_loss: 0.0480
Epoch 72/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0463 -
val_loss: 0.0531
Epoch 73/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0468 -
val_loss: 0.0625
Epoch 74/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0469 -
val_loss: 0.0705
Epoch 75/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0466 -
val_loss: 0.0667
Epoch 76/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0461 -
val_loss: 0.0455
Epoch 77/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0472 -
```



```
val_loss: 0.0456
Epoch 78/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0468 -
val_loss: 0.0632
Epoch 79/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0470 -
val_loss: 0.0641
Epoch 80/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0464 -
val_loss: 0.0479
Epoch 81/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0465 -
val_loss: 0.0578
Epoch 82/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0466 -
val_loss: 0.0499
Epoch 83/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0466 -
val_loss: 0.0509
Epoch 84/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0472 -
val_loss: 0.0546
Epoch 85/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0467 -
val_loss: 0.0466
Epoch 86/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0470 -
val_loss: 0.0550
Epoch 87/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0464 -
val_loss: 0.0529
Epoch 88/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0468 -
val_loss: 0.0524
Epoch 89/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0466 -
val_loss: 0.0526
Epoch 90/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0467 -
val_loss: 0.0569
Epoch 91/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0467 -
val_loss: 0.0465
Epoch 92/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0468 -
val_loss: 0.0658
Epoch 93/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0464 -
```

```

val_loss: 0.0462
Epoch 94/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0467 -
val_loss: 0.0573
Epoch 95/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0470 -
val_loss: 0.0475
Epoch 96/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0465 -
val_loss: 0.0647
Epoch 97/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0467 -
val_loss: 0.0551
Epoch 98/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0469 -
val_loss: 0.0539
Epoch 99/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0471 -
val_loss: 0.0506
Epoch 100/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0468 -
val_loss: 0.0484

```

```
[27]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[28]: Y_test = np.round(Y_test, 0)
```

```
[29]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))

```

```

Estado: 3., predicted:3.
Estado: 1., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.

```

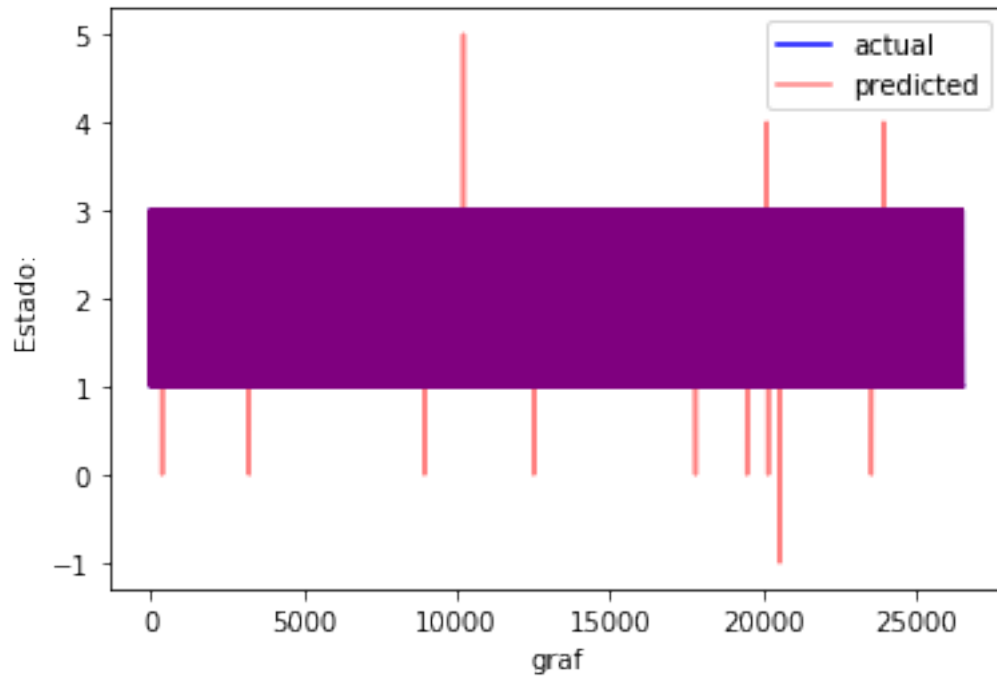
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[30]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9481733666596786

```
[31]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[32]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[32]: 0.9816755900761632
```

```
[:]
```

# Wrist\_elux5\_mae\_Adadel\_final

August 26, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```



```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```



```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[37]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[38]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

Entrenamos la red:

```

[39]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      →validation_split=0.2)

```

Train on 84868 samples, validate on 21218 samples

```

Epoch 1/100
84868/84868 [=====] - 14s 162us/step - loss: 0.3536 -
val_loss: 0.2678
Epoch 2/100
84868/84868 [=====] - 14s 160us/step - loss: 0.2102 -
val_loss: 0.1813
Epoch 3/100
84868/84868 [=====] - 15s 172us/step - loss: 0.1675 -
val_loss: 0.1591
Epoch 4/100
84868/84868 [=====] - 14s 170us/step - loss: 0.1488 -
val_loss: 0.1369
Epoch 5/100
84868/84868 [=====] - 14s 163us/step - loss: 0.1358 -
val_loss: 0.1355
Epoch 6/100
84868/84868 [=====] - 13s 155us/step - loss: 0.1271 -
val_loss: 0.1336
Epoch 7/100
84868/84868 [=====] - 14s 163us/step - loss: 0.1197 -
val_loss: 0.1297
Epoch 8/100
84868/84868 [=====] - 15s 174us/step - loss: 0.1117 -
val_loss: 0.1246
Epoch 9/100
84868/84868 [=====] - 13s 159us/step - loss: 0.1079 -
val_loss: 0.1012
Epoch 10/100
84868/84868 [=====] - 13s 156us/step - loss: 0.1039 -
val_loss: 0.1194

```

Epoch 11/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.1014 -  
val\_loss: 0.0978  
Epoch 12/100  
84868/84868 [=====] - 13s 159us/step - loss: 0.0994 -  
val\_loss: 0.1030  
Epoch 13/100  
84868/84868 [=====] - 14s 165us/step - loss: 0.0971 -  
val\_loss: 0.1096  
Epoch 14/100  
84868/84868 [=====] - 14s 162us/step - loss: 0.0948 -  
val\_loss: 0.0897  
Epoch 15/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0931 -  
val\_loss: 0.0955  
Epoch 16/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0909 -  
val\_loss: 0.0865  
Epoch 17/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0893 -  
val\_loss: 0.0842  
Epoch 18/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0883 -  
val\_loss: 0.0861  
Epoch 19/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0868 -  
val\_loss: 0.0916  
Epoch 20/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0861 -  
val\_loss: 0.0841  
Epoch 21/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0852 -  
val\_loss: 0.0932  
Epoch 22/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0844 -  
val\_loss: 0.0769  
Epoch 23/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0834 -  
val\_loss: 0.0940  
Epoch 24/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0829 -  
val\_loss: 0.0863  
Epoch 25/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0816 -  
val\_loss: 0.0809  
Epoch 26/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0807 -  
val\_loss: 0.0809

Epoch 27/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0798 -  
val\_loss: 0.0827  
Epoch 28/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0791 -  
val\_loss: 0.0842  
Epoch 29/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0790 -  
val\_loss: 0.0882  
Epoch 30/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0774 -  
val\_loss: 0.0812  
Epoch 31/100  
84868/84868 [=====] - 13s 157us/step - loss: 0.0769 -  
val\_loss: 0.0757  
Epoch 32/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0758 -  
val\_loss: 0.0790  
Epoch 33/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0754 -  
val\_loss: 0.0799  
Epoch 34/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0749 -  
val\_loss: 0.0711  
Epoch 35/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0743 -  
val\_loss: 0.0778  
Epoch 36/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0739 -  
val\_loss: 0.0823  
Epoch 37/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0733 -  
val\_loss: 0.0903  
Epoch 38/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0730 -  
val\_loss: 0.0672  
Epoch 39/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0719 -  
val\_loss: 0.0663  
Epoch 40/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0717 -  
val\_loss: 0.0938  
Epoch 41/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0713 -  
val\_loss: 0.0696  
Epoch 42/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0703 -  
val\_loss: 0.0959



Epoch 43/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0702 -  
val\_loss: 0.0830  
Epoch 44/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0699 -  
val\_loss: 0.0812  
Epoch 45/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0702 -  
val\_loss: 0.0681  
Epoch 46/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0688 -  
val\_loss: 0.0782  
Epoch 47/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0692 -  
val\_loss: 0.0734  
Epoch 48/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0693 -  
val\_loss: 0.0796  
Epoch 49/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0677 -  
val\_loss: 0.0663  
Epoch 50/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0626 -  
val\_loss: 0.0528  
Epoch 51/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0603 -  
val\_loss: 0.0772  
Epoch 52/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0603 -  
val\_loss: 0.0712  
Epoch 53/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0601 -  
val\_loss: 0.0639  
Epoch 54/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0588 -  
val\_loss: 0.0544  
Epoch 55/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0586 -  
val\_loss: 0.0750  
Epoch 56/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0575 -  
val\_loss: 0.0637  
Epoch 57/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0580 -  
val\_loss: 0.0577  
Epoch 58/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0582 -  
val\_loss: 0.0641

Epoch 59/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0570 -  
val\_loss: 0.0609  
Epoch 60/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0574 -  
val\_loss: 0.0634  
Epoch 61/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0577 -  
val\_loss: 0.0647  
Epoch 62/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0564 -  
val\_loss: 0.0679  
Epoch 63/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0563 -  
val\_loss: 0.0763  
Epoch 64/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0560 -  
val\_loss: 0.0457  
Epoch 65/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0556 -  
val\_loss: 0.0545  
Epoch 66/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0543 -  
val\_loss: 0.0453  
Epoch 67/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0552 -  
val\_loss: 0.0638  
Epoch 68/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0539 -  
val\_loss: 0.0608  
Epoch 69/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0543 -  
val\_loss: 0.0723  
Epoch 70/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0536 -  
val\_loss: 0.0679  
Epoch 71/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0535 -  
val\_loss: 0.0711  
Epoch 72/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0529 -  
val\_loss: 0.0667  
Epoch 73/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0534 -  
val\_loss: 0.0514  
Epoch 74/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0520 -  
val\_loss: 0.0532

Epoch 75/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0526 -  
val\_loss: 0.0589  
Epoch 76/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0519 -  
val\_loss: 0.0546  
Epoch 77/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0518 -  
val\_loss: 0.0535  
Epoch 78/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0520 -  
val\_loss: 0.0426  
Epoch 79/100  
84868/84868 [=====] - 14s 162us/step - loss: 0.0524 -  
val\_loss: 0.0741  
Epoch 80/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0516 -  
val\_loss: 0.0588  
Epoch 81/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0519 -  
val\_loss: 0.0534  
Epoch 82/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0519 -  
val\_loss: 0.0526  
Epoch 83/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0507 -  
val\_loss: 0.0670  
Epoch 84/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0513 -  
val\_loss: 0.0547  
Epoch 85/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0503 -  
val\_loss: 0.0582  
Epoch 86/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0499 -  
val\_loss: 0.0511  
Epoch 87/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0506 -  
val\_loss: 0.0488  
Epoch 88/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0497 -  
val\_loss: 0.0446  
Epoch 89/100  
84868/84868 [=====] - 14s 161us/step - loss: 0.0499 -  
val\_loss: 0.0523  
Epoch 90/100  
84868/84868 [=====] - 14s 165us/step - loss: 0.0491 -  
val\_loss: 0.0535

```

Epoch 91/100
84868/84868 [=====] - 14s 165us/step - loss: 0.0498 -
val_loss: 0.0462
Epoch 92/100
84868/84868 [=====] - 14s 164us/step - loss: 0.0499 -
val_loss: 0.0530
Epoch 93/100
84868/84868 [=====] - 14s 166us/step - loss: 0.0494 -
val_loss: 0.0559
Epoch 94/100
84868/84868 [=====] - 14s 165us/step - loss: 0.0489 -
val_loss: 0.0626
Epoch 95/100
84868/84868 [=====] - 14s 165us/step - loss: 0.0494 -
val_loss: 0.0564
Epoch 96/100
84868/84868 [=====] - 14s 167us/step - loss: 0.0486 -
val_loss: 0.0440
Epoch 97/100
84868/84868 [=====] - 14s 165us/step - loss: 0.0486 -
val_loss: 0.0614
Epoch 98/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0485 -
val_loss: 0.0548
Epoch 99/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0478 -
val_loss: 0.0836
Epoch 100/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0480 -
val_loss: 0.0543

```

```

[40]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

Train on 84868 samples, validate on 21218 samples

```

Epoch 1/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0473 -
val_loss: 0.0456
Epoch 2/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0474 -
val_loss: 0.0583
Epoch 3/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0479 -
val_loss: 0.0558

```

Epoch 4/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0474 -  
val\_loss: 0.0600  
Epoch 5/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0475 -  
val\_loss: 0.0395  
Epoch 6/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0453  
Epoch 7/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0473 -  
val\_loss: 0.0539  
Epoch 8/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0328  
Epoch 9/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0473 -  
val\_loss: 0.0503  
Epoch 10/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0468 -  
val\_loss: 0.0411  
Epoch 11/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0472 -  
val\_loss: 0.0617  
Epoch 12/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0473 -  
val\_loss: 0.0471  
Epoch 13/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0465 -  
val\_loss: 0.0571  
Epoch 14/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0407  
Epoch 15/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0477 -  
val\_loss: 0.0500  
Epoch 16/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0469 -  
val\_loss: 0.0600  
Epoch 17/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0677  
Epoch 18/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0418  
Epoch 19/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0469 -  
val\_loss: 0.0751

Epoch 20/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0461 -  
val\_loss: 0.0667  
Epoch 21/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0565  
Epoch 22/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0462 -  
val\_loss: 0.0620  
Epoch 23/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0457 -  
val\_loss: 0.0667  
Epoch 24/100  
84868/84868 [=====] - 13s 157us/step - loss: 0.0462 -  
val\_loss: 0.0468  
Epoch 25/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0470 -  
val\_loss: 0.0398  
Epoch 26/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0562  
Epoch 27/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0467 -  
val\_loss: 0.0565  
Epoch 28/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0458 -  
val\_loss: 0.0689  
Epoch 29/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0459 -  
val\_loss: 0.0488  
Epoch 30/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0454 -  
val\_loss: 0.0552  
Epoch 31/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0454 -  
val\_loss: 0.0674  
Epoch 32/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0476  
Epoch 33/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0459 -  
val\_loss: 0.0492  
Epoch 34/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0470 -  
val\_loss: 0.0612  
Epoch 35/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0467 -  
val\_loss: 0.0575

Epoch 36/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0670  
Epoch 37/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0546  
Epoch 38/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0467 -  
val\_loss: 0.0772  
Epoch 39/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0462 -  
val\_loss: 0.0430  
Epoch 40/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0663  
Epoch 41/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0458 -  
val\_loss: 0.0496  
Epoch 42/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0460 -  
val\_loss: 0.0465  
Epoch 43/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0451 -  
val\_loss: 0.0659  
Epoch 44/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0464 -  
val\_loss: 0.0492  
Epoch 45/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0462 -  
val\_loss: 0.0615  
Epoch 46/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0460 -  
val\_loss: 0.0604  
Epoch 47/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0465 -  
val\_loss: 0.0433  
Epoch 48/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0457 -  
val\_loss: 0.0654  
Epoch 49/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0459 -  
val\_loss: 0.0459  
Epoch 50/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0466 -  
val\_loss: 0.0578  
Epoch 51/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0465 -  
val\_loss: 0.0544

Epoch 52/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0444  
Epoch 53/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0461 -  
val\_loss: 0.0463  
Epoch 54/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0438  
Epoch 55/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0457 -  
val\_loss: 0.0676  
Epoch 56/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0468 -  
val\_loss: 0.0457  
Epoch 57/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0671  
Epoch 58/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0426  
Epoch 59/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0672  
Epoch 60/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0472 -  
val\_loss: 0.0423  
Epoch 61/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0467 -  
val\_loss: 0.0561  
Epoch 62/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0569  
Epoch 63/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0451  
Epoch 64/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0603  
Epoch 65/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0470 -  
val\_loss: 0.0518  
Epoch 66/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0440  
Epoch 67/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0469 -  
val\_loss: 0.0458



Epoch 68/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0470 -  
val\_loss: 0.0459  
Epoch 69/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0467 -  
val\_loss: 0.0482  
Epoch 70/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0471 -  
val\_loss: 0.0454  
Epoch 71/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0475 -  
val\_loss: 0.0573  
Epoch 72/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0423  
Epoch 73/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0468 -  
val\_loss: 0.0469  
Epoch 74/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0467 -  
val\_loss: 0.0595  
Epoch 75/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0469 -  
val\_loss: 0.0400  
Epoch 76/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0471 -  
val\_loss: 0.0489  
Epoch 77/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0657  
Epoch 78/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0465 -  
val\_loss: 0.0737  
Epoch 79/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0457 -  
val\_loss: 0.0490  
Epoch 80/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0466 -  
val\_loss: 0.0409  
Epoch 81/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0471 -  
val\_loss: 0.0770  
Epoch 82/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0461 -  
val\_loss: 0.0457  
Epoch 83/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0467 -  
val\_loss: 0.0541

Epoch 84/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0431  
Epoch 85/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0471 -  
val\_loss: 0.0557  
Epoch 86/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0455 -  
val\_loss: 0.0569  
Epoch 87/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0458 -  
val\_loss: 0.0549  
Epoch 88/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0459 -  
val\_loss: 0.0556  
Epoch 89/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0455 -  
val\_loss: 0.0665  
Epoch 90/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0453 -  
val\_loss: 0.0570  
Epoch 91/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0448 -  
val\_loss: 0.0477  
Epoch 92/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0452 -  
val\_loss: 0.0613  
Epoch 93/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0455 -  
val\_loss: 0.0568  
Epoch 94/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0459 -  
val\_loss: 0.0626  
Epoch 95/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0461 -  
val\_loss: 0.0410  
Epoch 96/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0444 -  
val\_loss: 0.0490  
Epoch 97/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0439 -  
val\_loss: 0.0484  
Epoch 98/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0451 -  
val\_loss: 0.0614  
Epoch 99/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0454 -  
val\_loss: 0.0376

```
Epoch 100/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0442 -
val_loss: 0.0439
```

```
[41]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 84868 samples, validate on 21218 samples

```
Epoch 1/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0445 -
val_loss: 0.0369
Epoch 2/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0442 -
val_loss: 0.0542
Epoch 3/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0449 -
val_loss: 0.0541
Epoch 4/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0443 -
val_loss: 0.0369
Epoch 5/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0448 -
val_loss: 0.0429
Epoch 6/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0449 -
val_loss: 0.0443
Epoch 7/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0448 -
val_loss: 0.0547
Epoch 8/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0442 -
val_loss: 0.0502
Epoch 9/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0448 -
val_loss: 0.0526
Epoch 10/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0444 -
val_loss: 0.0563
Epoch 11/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0450 -
val_loss: 0.0435
Epoch 12/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0445 -
val_loss: 0.0483
```

Epoch 13/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0453 -  
val\_loss: 0.0474  
Epoch 14/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0444 -  
val\_loss: 0.0466  
Epoch 15/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0446 -  
val\_loss: 0.0482  
Epoch 16/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0445 -  
val\_loss: 0.0376  
Epoch 17/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0437 -  
val\_loss: 0.0489  
Epoch 18/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0433 -  
val\_loss: 0.0577  
Epoch 19/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0438 -  
val\_loss: 0.0484  
Epoch 20/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0436 -  
val\_loss: 0.0621  
Epoch 21/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0436 -  
val\_loss: 0.0416  
Epoch 22/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0441 -  
val\_loss: 0.0419  
Epoch 23/100  
84868/84868 [=====] - 13s 157us/step - loss: 0.0435 -  
val\_loss: 0.0470  
Epoch 24/100  
84868/84868 [=====] - 13s 158us/step - loss: 0.0439 -  
val\_loss: 0.0462  
Epoch 25/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0444 -  
val\_loss: 0.0455  
Epoch 26/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0437 -  
val\_loss: 0.0570  
Epoch 27/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0440 -  
val\_loss: 0.0551  
Epoch 28/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0438 -  
val\_loss: 0.0581

Epoch 29/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0447 -  
val\_loss: 0.0393  
Epoch 30/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0439 -  
val\_loss: 0.0575  
Epoch 31/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0443 -  
val\_loss: 0.0374  
Epoch 32/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0437 -  
val\_loss: 0.0628  
Epoch 33/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0483 -  
val\_loss: 0.0500  
Epoch 34/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0461 -  
val\_loss: 0.0454  
Epoch 35/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0513  
Epoch 36/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0465 -  
val\_loss: 0.0393  
Epoch 37/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0446 -  
val\_loss: 0.0419  
Epoch 38/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0461 -  
val\_loss: 0.0475  
Epoch 39/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0446 -  
val\_loss: 0.0550  
Epoch 40/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0445 -  
val\_loss: 0.0480  
Epoch 41/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0456 -  
val\_loss: 0.0504  
Epoch 42/100  
84868/84868 [=====] - 13s 157us/step - loss: 0.0451 -  
val\_loss: 0.0534  
Epoch 43/100  
84868/84868 [=====] - 13s 158us/step - loss: 0.0448 -  
val\_loss: 0.0642  
Epoch 44/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0440 -  
val\_loss: 0.0404

Epoch 45/100  
84868/84868 [=====] - 14s 159us/step - loss: 0.0456 -  
val\_loss: 0.0450  
Epoch 46/100  
84868/84868 [=====] - 14s 160us/step - loss: 0.0455 -  
val\_loss: 0.0393  
Epoch 47/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0444 -  
val\_loss: 0.0419  
Epoch 48/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0450 -  
val\_loss: 0.0444  
Epoch 49/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0456 -  
val\_loss: 0.0593  
Epoch 50/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0453 -  
val\_loss: 0.0472  
Epoch 51/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0452 -  
val\_loss: 0.0400  
Epoch 52/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0447 -  
val\_loss: 0.0507  
Epoch 53/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0457 -  
val\_loss: 0.0665  
Epoch 54/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0445 -  
val\_loss: 0.0341  
Epoch 55/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0450 -  
val\_loss: 0.0496  
Epoch 56/100  
84868/84868 [=====] - 13s 158us/step - loss: 0.0467 -  
val\_loss: 0.0479  
Epoch 57/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0454 -  
val\_loss: 0.0400  
Epoch 58/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0465 -  
val\_loss: 0.0573  
Epoch 59/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0463 -  
val\_loss: 0.0405  
Epoch 60/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0462 -  
val\_loss: 0.0387

Epoch 61/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0452 -  
val\_loss: 0.0475  
Epoch 62/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0462 -  
val\_loss: 0.0582  
Epoch 63/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0459 -  
val\_loss: 0.0505  
Epoch 64/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0460 -  
val\_loss: 0.0548  
Epoch 65/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0470 -  
val\_loss: 0.0677  
Epoch 66/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0464 -  
val\_loss: 0.0473  
Epoch 67/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0464 -  
val\_loss: 0.0517  
Epoch 68/100  
84868/84868 [=====] - 13s 157us/step - loss: 0.0463 -  
val\_loss: 0.0561  
Epoch 69/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0462 -  
val\_loss: 0.0514  
Epoch 70/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0461 -  
val\_loss: 0.0672  
Epoch 71/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0466 -  
val\_loss: 0.0405  
Epoch 72/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0463 -  
val\_loss: 0.0533  
Epoch 73/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0469 -  
val\_loss: 0.0521  
Epoch 74/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0473 -  
val\_loss: 0.0715  
Epoch 75/100  
84868/84868 [=====] - 13s 156us/step - loss: 0.0469 -  
val\_loss: 0.0627  
Epoch 76/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0486 -  
val\_loss: 0.0574

Epoch 77/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0494 -  
val\_loss: 0.0563  
Epoch 78/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0500 -  
val\_loss: 0.0508  
Epoch 79/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0489 -  
val\_loss: 0.0578  
Epoch 80/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0482 -  
val\_loss: 0.0632  
Epoch 81/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0484 -  
val\_loss: 0.0569  
Epoch 82/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0494 -  
val\_loss: 0.0627  
Epoch 83/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0493 -  
val\_loss: 0.0573  
Epoch 84/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0500 -  
val\_loss: 0.0498  
Epoch 85/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0492 -  
val\_loss: 0.0516  
Epoch 86/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0476 -  
val\_loss: 0.0542  
Epoch 87/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0488 -  
val\_loss: 0.0637  
Epoch 88/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0506 -  
val\_loss: 0.0456  
Epoch 89/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0494 -  
val\_loss: 0.0636  
Epoch 90/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0506 -  
val\_loss: 0.0519  
Epoch 91/100  
84868/84868 [=====] - 13s 154us/step - loss: 0.0494 -  
val\_loss: 0.0718  
Epoch 92/100  
84868/84868 [=====] - 13s 155us/step - loss: 0.0496 -  
val\_loss: 0.0555



```

Epoch 93/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0496 -
val_loss: 0.0626
Epoch 94/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0518 -
val_loss: 0.0531
Epoch 95/100
84868/84868 [=====] - 14s 160us/step - loss: 0.0511 -
val_loss: 0.0679
Epoch 96/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0514 -
val_loss: 0.0667
Epoch 97/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0498 -
val_loss: 0.0589
Epoch 98/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0506 -
val_loss: 0.0530
Epoch 99/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0491 -
val_loss: 0.0597
Epoch 100/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0515 -
val_loss: 0.0516

```

```
[42]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[43]: Y_test = np.round(Y_test, 0)
```

```
[44]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))

```

```

Estado: 3., predicted:3.
Estado: 1., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.

```

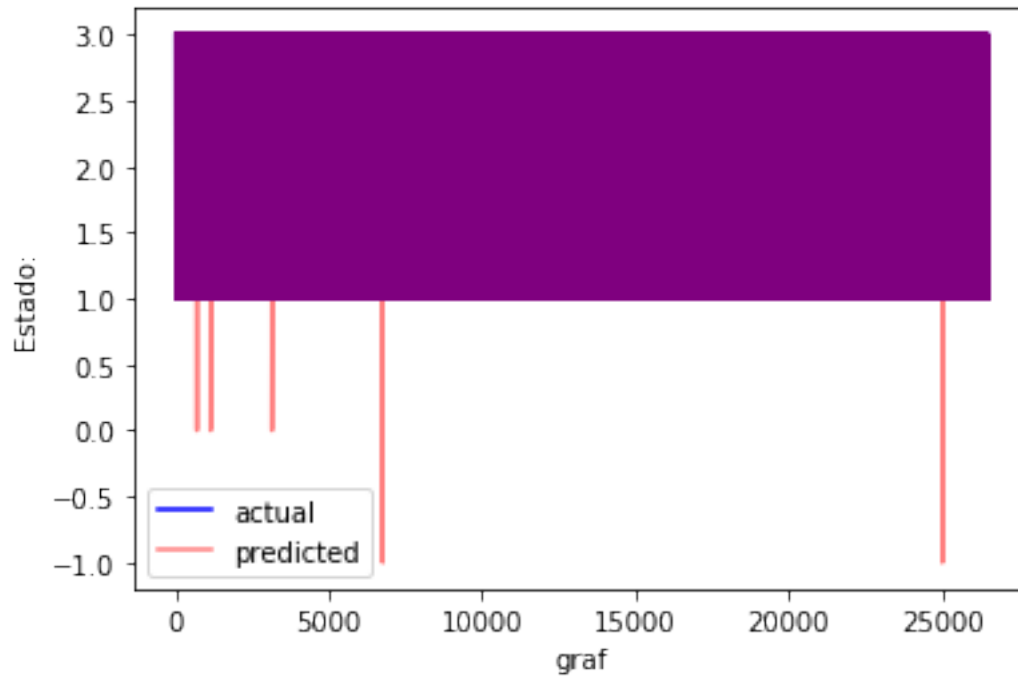
```
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:3.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[45]: from sklearn.metrics import r2_score  
      r2 = r2_score(Y_test, Y_val)  
      print (r2)
```

0.9343474100437075

```
[46]: plt.plot((Y_val),  
              color="b", label="actual")  
      plt.plot((Y_test),  
              color="r", alpha=0.5, label="predicted")  
      plt.xlabel("graf")  
      plt.ylabel("Estado:")  
      plt.legend(loc="best")  
      plt.show()
```



```
[47]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[47]: 0.9774903853404721
```

```
[:]
```

# Wrist\_elux7\_mae\_Adadel\_final

August 26, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```



```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```



```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

Dense(60),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(30),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0826 19:48:56.430401 10972 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0826 19:48:56.463053 10972 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0826 19:48:56.473266 10972 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0826 19:48:56.567031 10972 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0826 19:48:56.823332 10972 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0826 19:48:56.829314 10972 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 84868 samples, validate on 21218 samples

Epoch 1/100  
84868/84868 [=====] - 21s 248us/step - loss: 0.3493 -  
val\_loss: 0.2701  
Epoch 2/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.1877 -  
val\_loss: 0.1668  
Epoch 3/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.1453 -  
val\_loss: 0.1336  
Epoch 4/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.1276 -  
val\_loss: 0.1546  
Epoch 5/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.1161 -  
val\_loss: 0.1220  
Epoch 6/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.1104 -  
val\_loss: 0.0999  
Epoch 7/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.1058 -  
val\_loss: 0.1076  
Epoch 8/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.1019 -  
val\_loss: 0.0884  
Epoch 9/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0975 -  
val\_loss: 0.0951  
Epoch 10/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0949 -  
val\_loss: 0.0978  
Epoch 11/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0920 -  
val\_loss: 0.1036  
Epoch 12/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0918 -  
val\_loss: 0.0928  
Epoch 13/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0858 -  
val\_loss: 0.0812  
Epoch 14/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0823 -  
val\_loss: 0.0872  
Epoch 15/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0799 -  
val\_loss: 0.0814  
Epoch 16/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0799 -  
val\_loss: 0.0770  
Epoch 17/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0778 -  
val\_loss: 0.0906  
Epoch 18/100  
84868/84868 [=====] - 16s 185us/step - loss: 0.0753 -  
val\_loss: 0.0834  
Epoch 19/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0743 -  
val\_loss: 0.0724  
Epoch 20/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0733 -  
val\_loss: 0.0802  
Epoch 21/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0722 -  
val\_loss: 0.0688  
Epoch 22/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0712 -  
val\_loss: 0.0704  
Epoch 23/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0713 -  
val\_loss: 0.0821  
Epoch 24/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0696 -  
val\_loss: 0.0695  
Epoch 25/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0680 -  
val\_loss: 0.0793  
Epoch 26/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0666 -  
val\_loss: 0.0677  
Epoch 27/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0667 -  
val\_loss: 0.0853  
Epoch 28/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0669 -  
val\_loss: 0.0751  
Epoch 29/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0664 -  
val\_loss: 0.0665  
Epoch 30/100

84868/84868 [=====] - 16s 187us/step - loss: 0.0663 -  
val\_loss: 0.0637  
Epoch 31/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0658 -  
val\_loss: 0.0613  
Epoch 32/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0643 -  
val\_loss: 0.0677  
Epoch 33/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0649 -  
val\_loss: 0.0755  
Epoch 34/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0649 -  
val\_loss: 0.0612  
Epoch 35/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0634 -  
val\_loss: 0.0635  
Epoch 36/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0638 -  
val\_loss: 0.0811  
Epoch 37/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0623 -  
val\_loss: 0.0704  
Epoch 38/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0629 -  
val\_loss: 0.0682  
Epoch 39/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0618 -  
val\_loss: 0.0745  
Epoch 40/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0625 -  
val\_loss: 0.0677  
Epoch 41/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0610 -  
val\_loss: 0.0691  
Epoch 42/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0610 -  
val\_loss: 0.0651  
Epoch 43/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0614 -  
val\_loss: 0.0964  
Epoch 44/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0599 -  
val\_loss: 0.0649  
Epoch 45/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0604 -  
val\_loss: 0.0790  
Epoch 46/100



84868/84868 [=====] - 16s 191us/step - loss: 0.0604 -  
val\_loss: 0.0678  
Epoch 47/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0605 -  
val\_loss: 0.0585  
Epoch 48/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0595 -  
val\_loss: 0.0589  
Epoch 49/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0602 -  
val\_loss: 0.0635  
Epoch 50/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0609 -  
val\_loss: 0.0758  
Epoch 51/100  
84868/84868 [=====] - 17s 203us/step - loss: 0.0603 -  
val\_loss: 0.0802  
Epoch 52/100  
84868/84868 [=====] - 17s 203us/step - loss: 0.0594 -  
val\_loss: 0.0675  
Epoch 53/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0598 -  
val\_loss: 0.0692  
Epoch 54/100  
84868/84868 [=====] - 17s 197us/step - loss: 0.0585 -  
val\_loss: 0.0683  
Epoch 55/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0601 -  
val\_loss: 0.0662  
Epoch 56/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0587 -  
val\_loss: 0.0642  
Epoch 57/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0587 -  
val\_loss: 0.0596  
Epoch 58/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0578 -  
val\_loss: 0.0799  
Epoch 59/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0590 -  
val\_loss: 0.0656  
Epoch 60/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0576 -  
val\_loss: 0.0565  
Epoch 61/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0573 -  
val\_loss: 0.0615  
Epoch 62/100

84868/84868 [=====] - 16s 193us/step - loss: 0.0572 -  
val\_loss: 0.0698  
Epoch 63/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0556 -  
val\_loss: 0.0646  
Epoch 64/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0564 -  
val\_loss: 0.0570  
Epoch 65/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0554 -  
val\_loss: 0.0635  
Epoch 66/100  
84868/84868 [=====] - 16s 185us/step - loss: 0.0552 -  
val\_loss: 0.0555  
Epoch 67/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0548 -  
val\_loss: 0.0597  
Epoch 68/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0557 -  
val\_loss: 0.0539  
Epoch 69/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0548 -  
val\_loss: 0.0569  
Epoch 70/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0548 -  
val\_loss: 0.0580  
Epoch 71/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0547 -  
val\_loss: 0.0581  
Epoch 72/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0545 -  
val\_loss: 0.0538  
Epoch 73/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0549 -  
val\_loss: 0.0567  
Epoch 74/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0555 -  
val\_loss: 0.0587  
Epoch 75/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0556 -  
val\_loss: 0.0619  
Epoch 76/100  
84868/84868 [=====] - 17s 197us/step - loss: 0.0549 -  
val\_loss: 0.0577  
Epoch 77/100  
84868/84868 [=====] - 17s 204us/step - loss: 0.0557 -  
val\_loss: 0.0661  
Epoch 78/100

84868/84868 [=====] - 18s 207us/step - loss: 0.0556 -  
val\_loss: 0.0631  
Epoch 79/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0557 -  
val\_loss: 0.0700  
Epoch 80/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0556 -  
val\_loss: 0.0499  
Epoch 81/100  
84868/84868 [=====] - 17s 201us/step - loss: 0.0556 -  
val\_loss: 0.0588  
Epoch 82/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0544 -  
val\_loss: 0.0587  
Epoch 83/100  
84868/84868 [=====] - 18s 209us/step - loss: 0.0555 -  
val\_loss: 0.0571  
Epoch 84/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0547 -  
val\_loss: 0.0601  
Epoch 85/100  
84868/84868 [=====] - 17s 200us/step - loss: 0.0554 -  
val\_loss: 0.0606  
Epoch 86/100  
84868/84868 [=====] - 17s 202us/step - loss: 0.0544 -  
val\_loss: 0.0558  
Epoch 87/100  
84868/84868 [=====] - 18s 210us/step - loss: 0.0531 -  
val\_loss: 0.0542  
Epoch 88/100  
84868/84868 [=====] - 17s 200us/step - loss: 0.0542 -  
val\_loss: 0.0702  
Epoch 89/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0546 -  
val\_loss: 0.0577  
Epoch 90/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0546 -  
val\_loss: 0.0603  
Epoch 91/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0551 -  
val\_loss: 0.0596  
Epoch 92/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0528 -  
val\_loss: 0.0600  
Epoch 93/100  
84868/84868 [=====] - 16s 185us/step - loss: 0.0533 -  
val\_loss: 0.0535  
Epoch 94/100

```

84868/84868 [=====] - 16s 186us/step - loss: 0.0539 -
val_loss: 0.0659
Epoch 95/100
84868/84868 [=====] - 16s 194us/step - loss: 0.0562 -
val_loss: 0.0620
Epoch 96/100
84868/84868 [=====] - 19s 219us/step - loss: 0.0554 -
val_loss: 0.0633
Epoch 97/100
84868/84868 [=====] - 18s 216us/step - loss: 0.0533 -
val_loss: 0.0643
Epoch 98/100
84868/84868 [=====] - 18s 217us/step - loss: 0.0551 -
val_loss: 0.0549
Epoch 99/100
84868/84868 [=====] - 18s 210us/step - loss: 0.0534 -
val_loss: 0.0554
Epoch 100/100
84868/84868 [=====] - 18s 210us/step - loss: 0.0539 -
val_loss: 0.0548

```

```

[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 84868 samples, validate on 21218 samples
Epoch 1/100
84868/84868 [=====] - 17s 200us/step - loss: 0.0551 -
val_loss: 0.0609
Epoch 2/100
84868/84868 [=====] - 17s 200us/step - loss: 0.0539 -
val_loss: 0.0571
Epoch 3/100
84868/84868 [=====] - 17s 198us/step - loss: 0.0535 -
val_loss: 0.0556
Epoch 4/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0534 -
val_loss: 0.0613
Epoch 5/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0538 -
val_loss: 0.0649
Epoch 6/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0525 -
val_loss: 0.0636
Epoch 7/100

```

84868/84868 [=====] - 16s 190us/step - loss: 0.0528 -  
val\_loss: 0.0568  
Epoch 8/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0524 -  
val\_loss: 0.0502  
Epoch 9/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0523 -  
val\_loss: 0.0515  
Epoch 10/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0553 -  
val\_loss: 0.0611  
Epoch 11/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0524 -  
val\_loss: 0.0499  
Epoch 12/100  
84868/84868 [=====] - 18s 209us/step - loss: 0.0534 -  
val\_loss: 0.0572  
Epoch 13/100  
84868/84868 [=====] - 17s 198us/step - loss: 0.0516 -  
val\_loss: 0.0574  
Epoch 14/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0530 -  
val\_loss: 0.0538  
Epoch 15/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0525 -  
val\_loss: 0.0553  
Epoch 16/100  
84868/84868 [=====] - 16s 183us/step - loss: 0.0533 -  
val\_loss: 0.0511  
Epoch 17/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0524 -  
val\_loss: 0.0921  
Epoch 18/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0518 -  
val\_loss: 0.0649  
Epoch 19/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0524 -  
val\_loss: 0.0606  
Epoch 20/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0532 -  
val\_loss: 0.0526  
Epoch 21/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0531 -  
val\_loss: 0.0642  
Epoch 22/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0516 -  
val\_loss: 0.0573  
Epoch 23/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0517 -  
val\_loss: 0.0466  
Epoch 24/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0512 -  
val\_loss: 0.0640  
Epoch 25/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0513 -  
val\_loss: 0.0544  
Epoch 26/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0506 -  
val\_loss: 0.0606  
Epoch 27/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0506 -  
val\_loss: 0.0682  
Epoch 28/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0504 -  
val\_loss: 0.0690  
Epoch 29/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0514 -  
val\_loss: 0.0467  
Epoch 30/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0517 -  
val\_loss: 0.0769  
Epoch 31/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0507 -  
val\_loss: 0.0700  
Epoch 32/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0517 -  
val\_loss: 0.0518  
Epoch 33/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0537 -  
val\_loss: 0.0530  
Epoch 34/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0505 -  
val\_loss: 0.0627  
Epoch 35/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0522 -  
val\_loss: 0.0580  
Epoch 36/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0502 -  
val\_loss: 0.0482  
Epoch 37/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0511 -  
val\_loss: 0.0645  
Epoch 38/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0506 -  
val\_loss: 0.0497  
Epoch 39/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0511 -  
val\_loss: 0.0526  
Epoch 40/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0506 -  
val\_loss: 0.0531  
Epoch 41/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0500 -  
val\_loss: 0.0546  
Epoch 42/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0512 -  
val\_loss: 0.0645  
Epoch 43/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0508 -  
val\_loss: 0.0563  
Epoch 44/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0508 -  
val\_loss: 0.0481  
Epoch 45/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0510 -  
val\_loss: 0.0630  
Epoch 46/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0489 -  
val\_loss: 0.0481  
Epoch 47/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0502 -  
val\_loss: 0.0635  
Epoch 48/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0519 -  
val\_loss: 0.0515  
Epoch 49/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0509 -  
val\_loss: 0.0569  
Epoch 50/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0515 -  
val\_loss: 0.0517  
Epoch 51/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0495 -  
val\_loss: 0.0542  
Epoch 52/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0508 -  
val\_loss: 0.0481  
Epoch 53/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0508 -  
val\_loss: 0.0505  
Epoch 54/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0504 -  
val\_loss: 0.0599  
Epoch 55/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0522 -  
val\_loss: 0.0643  
Epoch 56/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0512 -  
val\_loss: 0.0591  
Epoch 57/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0510 -  
val\_loss: 0.0605  
Epoch 58/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0520 -  
val\_loss: 0.0530  
Epoch 59/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0509 -  
val\_loss: 0.0641  
Epoch 60/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0497 -  
val\_loss: 0.0553  
Epoch 61/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0522 -  
val\_loss: 0.0566  
Epoch 62/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0504 -  
val\_loss: 0.0517  
Epoch 63/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0503 -  
val\_loss: 0.0629  
Epoch 64/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0522 -  
val\_loss: 0.0583  
Epoch 65/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0506 -  
val\_loss: 0.0576  
Epoch 66/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0516 -  
val\_loss: 0.0586  
Epoch 67/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0511 -  
val\_loss: 0.0540  
Epoch 68/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0514 -  
val\_loss: 0.0483  
Epoch 69/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0526 -  
val\_loss: 0.0586  
Epoch 70/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0515 -  
val\_loss: 0.0524  
Epoch 71/100



84868/84868 [=====] - 16s 188us/step - loss: 0.0508 -  
val\_loss: 0.0438  
Epoch 72/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0518 -  
val\_loss: 0.0537  
Epoch 73/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0520 -  
val\_loss: 0.0533  
Epoch 74/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0515 -  
val\_loss: 0.0472  
Epoch 75/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0526 -  
val\_loss: 0.0727  
Epoch 76/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0528 -  
val\_loss: 0.0470  
Epoch 77/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0539 -  
val\_loss: 0.0530  
Epoch 78/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0531 -  
val\_loss: 0.0461  
Epoch 79/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0520 -  
val\_loss: 0.0556  
Epoch 80/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0514 -  
val\_loss: 0.0580  
Epoch 81/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0521 -  
val\_loss: 0.0538  
Epoch 82/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0537 -  
val\_loss: 0.0558  
Epoch 83/100  
84868/84868 [=====] - 17s 197us/step - loss: 0.0529 -  
val\_loss: 0.0522  
Epoch 84/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0516 -  
val\_loss: 0.0497  
Epoch 85/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0534 -  
val\_loss: 0.0603  
Epoch 86/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0529 -  
val\_loss: 0.0633  
Epoch 87/100

```

84868/84868 [=====] - 16s 188us/step - loss: 0.0538 -
val_loss: 0.0516
Epoch 88/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0527 -
val_loss: 0.0692
Epoch 89/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0519 -
val_loss: 0.0564
Epoch 90/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0540 -
val_loss: 0.0525
Epoch 91/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0521 -
val_loss: 0.0582
Epoch 92/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0527 -
val_loss: 0.0528
Epoch 93/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0523 -
val_loss: 0.0624
Epoch 94/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0520 -
val_loss: 0.0635
Epoch 95/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0519 -
val_loss: 0.0589
Epoch 96/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0552 -
val_loss: 0.0482
Epoch 97/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0524 -
val_loss: 0.0576
Epoch 98/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0529 -
val_loss: 0.0543
Epoch 99/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0576 -
val_loss: 0.0592
Epoch 100/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0538 -
val_loss: 0.0545

```

```

[22]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

Train on 84868 samples, validate on 21218 samples

Epoch 1/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0543 -  
val\_loss: 0.0598

Epoch 2/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0541 -  
val\_loss: 0.0671

Epoch 3/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0564 -  
val\_loss: 0.0758

Epoch 4/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0543 -  
val\_loss: 0.0635

Epoch 5/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0537 -  
val\_loss: 0.0620

Epoch 6/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0556 -  
val\_loss: 0.0566

Epoch 7/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0554 -  
val\_loss: 0.0589

Epoch 8/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0556 -  
val\_loss: 0.0566

Epoch 9/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0575 -  
val\_loss: 0.0818

Epoch 10/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0549 -  
val\_loss: 0.0564

Epoch 11/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0588 -  
val\_loss: 0.0568

Epoch 12/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0555 -  
val\_loss: 0.0621

Epoch 13/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0570 -  
val\_loss: 0.0517

Epoch 14/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0539 -  
val\_loss: 0.0623

Epoch 15/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0546 -  
val\_loss: 0.0592

Epoch 16/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0544 -

```
val_loss: 0.0551
Epoch 17/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0548 -
val_loss: 0.0576
Epoch 18/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0542 -
val_loss: 0.0551
Epoch 19/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0578 -
val_loss: 0.0578
Epoch 20/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0564 -
val_loss: 0.0671
Epoch 21/100
84868/84868 [=====] - 16s 183us/step - loss: 0.0547 -
val_loss: 0.0517
Epoch 22/100
84868/84868 [=====] - 16s 183us/step - loss: 0.0608 -
val_loss: 0.0827
Epoch 23/100
84868/84868 [=====] - 16s 184us/step - loss: 0.0571 -
val_loss: 0.0547
Epoch 24/100
84868/84868 [=====] - 16s 183us/step - loss: 0.0562 -
val_loss: 0.0527
Epoch 25/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0571 -
val_loss: 0.0550
Epoch 26/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0565 -
val_loss: 0.0549
Epoch 27/100
84868/84868 [=====] - 16s 183us/step - loss: 0.0561 -
val_loss: 0.0591
Epoch 28/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0565 -
val_loss: 0.0645
Epoch 29/100
84868/84868 [=====] - 16s 183us/step - loss: 0.0597 -
val_loss: 0.0582
Epoch 30/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0575 -
val_loss: 0.0633
Epoch 31/100
84868/84868 [=====] - 15s 181us/step - loss: 0.0560 -
val_loss: 0.0526
Epoch 32/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0631 -
```

```
val_loss: 0.0575
Epoch 33/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0622 -
val_loss: 0.0549
Epoch 34/100
84868/84868 [=====] - 15s 182us/step - loss: 0.0596 -
val_loss: 0.0623
Epoch 35/100
84868/84868 [=====] - 16s 186us/step - loss: 0.0572 -
val_loss: 0.0623
Epoch 36/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0569 -
val_loss: 0.0620
Epoch 37/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0626 -
val_loss: 0.0740
Epoch 38/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0594 -
val_loss: 0.0642
Epoch 39/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0616 -
val_loss: 0.0532
Epoch 40/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0617 -
val_loss: 0.0818
Epoch 41/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0627 -
val_loss: 0.0582
Epoch 42/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0583 -
val_loss: 0.0580
Epoch 43/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0592 -
val_loss: 0.0616
Epoch 44/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0623 -
val_loss: 0.0560
Epoch 45/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0626 -
val_loss: 0.0790
Epoch 46/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0648 -
val_loss: 0.0715
Epoch 47/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0624 -
val_loss: 0.0493
Epoch 48/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0627 -
```

```
val_loss: 0.0548
Epoch 49/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0619 -
val_loss: 0.0689
Epoch 50/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0663 -
val_loss: 0.0599
Epoch 51/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0578 -
val_loss: 0.0653
Epoch 52/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0598 -
val_loss: 0.0570
Epoch 53/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0604 -
val_loss: 0.0547
Epoch 54/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0577 -
val_loss: 0.0677
Epoch 55/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0621 -
val_loss: 0.0656
Epoch 56/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0604 -
val_loss: 0.0552
Epoch 57/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0576 -
val_loss: 0.0606
Epoch 58/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0595 -
val_loss: 0.0653
Epoch 59/100
84868/84868 [=====] - 17s 195us/step - loss: 0.0590 -
val_loss: 0.0680
Epoch 60/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0584 -
val_loss: 0.0540
Epoch 61/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0581 -
val_loss: 0.0636
Epoch 62/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0616 -
val_loss: 0.0482
Epoch 63/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0595 -
val_loss: 0.0543
Epoch 64/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0578 -
```

```
val_loss: 0.0588
Epoch 65/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0588 -
val_loss: 0.0727
Epoch 66/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0581 -
val_loss: 0.0703
Epoch 67/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0571 -
val_loss: 0.0583
Epoch 68/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0585 -
val_loss: 0.0516
Epoch 69/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0607 -
val_loss: 0.0543
Epoch 70/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0588 -
val_loss: 0.0624
Epoch 71/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0578 -
val_loss: 0.0717
Epoch 72/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0560 -
val_loss: 0.0578
Epoch 73/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0585 -
val_loss: 0.0763
Epoch 74/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0581 -
val_loss: 0.0582
Epoch 75/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0557 -
val_loss: 0.0590
Epoch 76/100
84868/84868 [=====] - 17s 196us/step - loss: 0.0566 -
val_loss: 0.0650
Epoch 77/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0593 -
val_loss: 0.0555
Epoch 78/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0583 -
val_loss: 0.0575
Epoch 79/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0566 -
val_loss: 0.0618
Epoch 80/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0567 -
```

```
val_loss: 0.0506
Epoch 81/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0571 -
val_loss: 0.0533
Epoch 82/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0577 -
val_loss: 0.0521
Epoch 83/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0550 -
val_loss: 0.0542
Epoch 84/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0547 -
val_loss: 0.0536
Epoch 85/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0569 -
val_loss: 0.0744
Epoch 86/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0553 -
val_loss: 0.0562
Epoch 87/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0537 -
val_loss: 0.0608
Epoch 88/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0596 -
val_loss: 0.0517
Epoch 89/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0548 -
val_loss: 0.0690
Epoch 90/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0565 -
val_loss: 0.0575
Epoch 91/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0566 -
val_loss: 0.0620
Epoch 92/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0576 -
val_loss: 0.0505
Epoch 93/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0569 -
val_loss: 0.0517
Epoch 94/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0573 -
val_loss: 0.0632
Epoch 95/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0578 -
val_loss: 0.0584
Epoch 96/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0572 -
```



```

val_loss: 0.0609
Epoch 97/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0549 -
val_loss: 0.0502
Epoch 98/100
84868/84868 [=====] - 17s 201us/step - loss: 0.0554 -
val_loss: 0.0562
Epoch 99/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0568 -
val_loss: 0.0840
Epoch 100/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0573 -
val_loss: 0.0621

```

```
[23]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[24]: Y_test = np.round(Y_test, 0)
```

```
[25]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))

```

```

Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.

```

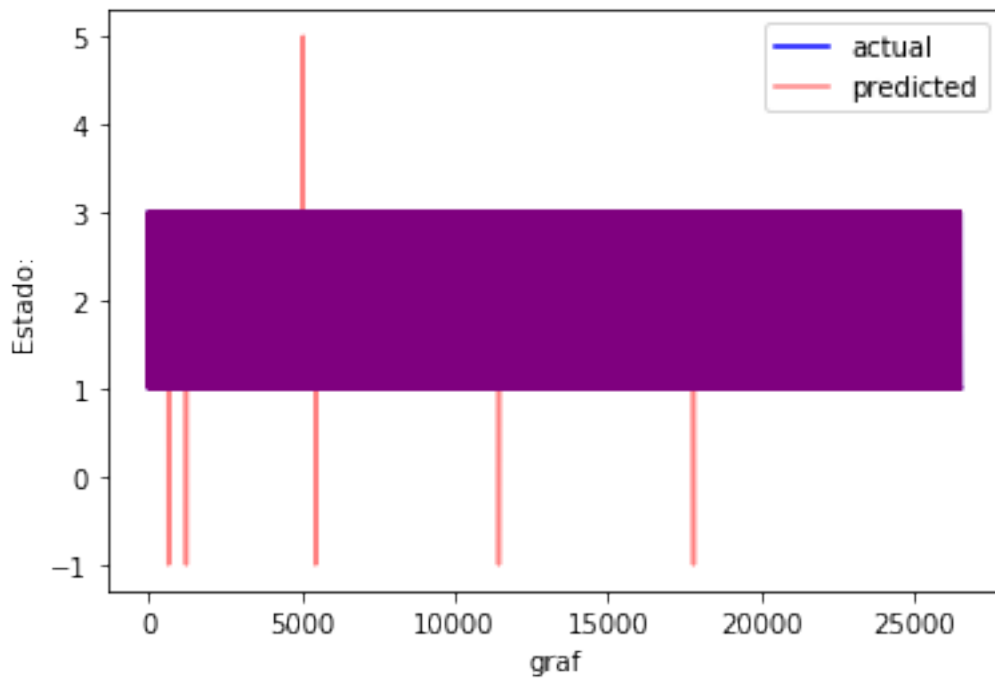
```
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[26]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.8573412608945405

```
[27]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
        color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[28]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[28]: 0.9578086117185732
```

```
[:]
```

# Wrist\_elux4\_mae\_Adadel\_final

August 27, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```



```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```



```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0827 17:13:51.872752 16308 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0827 17:13:51.907613 16308 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0827 17:13:51.918725 16308 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0827 17:13:51.979421 16308 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

[20]:

```

NUM_EPOCHS =100
BATCH_SIZE = 20

history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
→validation_split=0.2)

```

W0827 17:13:52.172904 16308 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0827 17:13:52.178901 16308 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 84868 samples, validate on 21218 samples

Epoch 1/100

84868/84868 [=====] - 16s 193us/step - loss: 0.3930 -  
val\_loss: 0.2707

Epoch 2/100

84868/84868 [=====] - 12s 139us/step - loss: 0.2372 -  
val\_loss: 0.2054

Epoch 3/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1939 -  
val\_loss: 0.1913

Epoch 4/100

84868/84868 [=====] - 12s 139us/step - loss: 0.1695 -  
val\_loss: 0.2000

Epoch 5/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1551 -  
val\_loss: 0.1491

Epoch 6/100

84868/84868 [=====] - 12s 137us/step - loss: 0.1447 -  
val\_loss: 0.1327

Epoch 7/100

84868/84868 [=====] - 12s 139us/step - loss: 0.1364 -  
val\_loss: 0.1520

Epoch 8/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1309 -  
val\_loss: 0.1303

Epoch 9/100

84868/84868 [=====] - 12s 137us/step - loss: 0.1254 -  
val\_loss: 0.1247

Epoch 10/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1212 -  
val\_loss: 0.1369

Epoch 11/100

84868/84868 [=====] - 12s 137us/step - loss: 0.1176 -  
val\_loss: 0.1087

Epoch 12/100

84868/84868 [=====] - 12s 140us/step - loss: 0.1145 -  
val\_loss: 0.1130

Epoch 13/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1110 -  
val\_loss: 0.1023

Epoch 14/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1089 -  
val\_loss: 0.1204

Epoch 15/100

84868/84868 [=====] - 12s 137us/step - loss: 0.1064 -  
val\_loss: 0.1058

Epoch 16/100

84868/84868 [=====] - 12s 139us/step - loss: 0.1038 -

```
val_loss: 0.1162
Epoch 17/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1020 -
val_loss: 0.1071
Epoch 18/100
84868/84868 [=====] - 12s 138us/step - loss: 0.1006 -
val_loss: 0.1133
Epoch 19/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0986 -
val_loss: 0.1220
Epoch 20/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0974 -
val_loss: 0.1014
Epoch 21/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0961 -
val_loss: 0.1050
Epoch 22/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0952 -
val_loss: 0.1058
Epoch 23/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0940 -
val_loss: 0.0992
Epoch 24/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0931 -
val_loss: 0.1051
Epoch 25/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0923 -
val_loss: 0.0874
Epoch 26/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0916 -
val_loss: 0.0869
Epoch 27/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0904 -
val_loss: 0.0927
Epoch 28/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0897 -
val_loss: 0.0909
Epoch 29/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0892 -
val_loss: 0.0896
Epoch 30/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0881 -
val_loss: 0.0899
Epoch 31/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0874 -
val_loss: 0.1076
Epoch 32/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0867 -
```

```
val_loss: 0.0878
Epoch 33/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0866 -
val_loss: 0.0895
Epoch 34/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0859 -
val_loss: 0.0993
Epoch 35/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0857 -
val_loss: 0.0855
Epoch 36/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0842 -
val_loss: 0.0852
Epoch 37/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0838 -
val_loss: 0.0944
Epoch 38/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0836 -
val_loss: 0.1087
Epoch 39/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0834 -
val_loss: 0.0881
Epoch 40/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0828 -
val_loss: 0.0870
Epoch 41/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0819 -
val_loss: 0.0822
Epoch 42/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0821 -
val_loss: 0.0820
Epoch 43/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0822 -
val_loss: 0.0795
Epoch 44/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0816 -
val_loss: 0.0799
Epoch 45/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0808 -
val_loss: 0.0788
Epoch 46/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0814 -
val_loss: 0.0907
Epoch 47/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0806 -
val_loss: 0.0954
Epoch 48/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0802 -
```



```
val_loss: 0.1004
Epoch 49/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0798 -
val_loss: 0.1134
Epoch 50/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0794 -
val_loss: 0.1081
Epoch 51/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0797 -
val_loss: 0.0875
Epoch 52/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0790 -
val_loss: 0.0781
Epoch 53/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0786 -
val_loss: 0.0924
Epoch 54/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0784 -
val_loss: 0.1053
Epoch 55/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0783 -
val_loss: 0.0946
Epoch 56/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0778 -
val_loss: 0.0929
Epoch 57/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0776 -
val_loss: 0.0716
Epoch 58/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0776 -
val_loss: 0.0712
Epoch 59/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0776 -
val_loss: 0.0895
Epoch 60/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0772 -
val_loss: 0.0934
Epoch 61/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0773 -
val_loss: 0.0812
Epoch 62/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0765 -
val_loss: 0.0880
Epoch 63/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0768 -
val_loss: 0.0733
Epoch 64/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0766 -
```

val\_loss: 0.0861  
Epoch 65/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0764 -  
val\_loss: 0.0863  
Epoch 66/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0757 -  
val\_loss: 0.1002  
Epoch 67/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0763 -  
val\_loss: 0.0874  
Epoch 68/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0756 -  
val\_loss: 0.0794  
Epoch 69/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0748 -  
val\_loss: 0.0814  
Epoch 70/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0743 -  
val\_loss: 0.0778  
Epoch 71/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0746 -  
val\_loss: 0.0916  
Epoch 72/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0740 -  
val\_loss: 0.0866  
Epoch 73/100  
84868/84868 [=====] - 12s 138us/step - loss: 0.0740 -  
val\_loss: 0.0787  
Epoch 74/100  
84868/84868 [=====] - 12s 138us/step - loss: 0.0737 -  
val\_loss: 0.0827  
Epoch 75/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0738 -  
val\_loss: 0.0861  
Epoch 76/100  
84868/84868 [=====] - 12s 136us/step - loss: 0.0738 -  
val\_loss: 0.0728  
Epoch 77/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0727 -  
val\_loss: 0.0746  
Epoch 78/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0732 -  
val\_loss: 0.0704  
Epoch 79/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0729 -  
val\_loss: 0.0725  
Epoch 80/100  
84868/84868 [=====] - 12s 136us/step - loss: 0.0730 -

val\_loss: 0.0827  
Epoch 81/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0728 -  
val\_loss: 0.0910  
Epoch 82/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0732 -  
val\_loss: 0.1024  
Epoch 83/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0722 -  
val\_loss: 0.0725  
Epoch 84/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0730 -  
val\_loss: 0.0810  
Epoch 85/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0723 -  
val\_loss: 0.0703  
Epoch 86/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0715 -  
val\_loss: 0.0706  
Epoch 87/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0713 -  
val\_loss: 0.0744  
Epoch 88/100  
84868/84868 [=====] - 12s 140us/step - loss: 0.0722 -  
val\_loss: 0.0711  
Epoch 89/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0710 -  
val\_loss: 0.0892  
Epoch 90/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0713 -  
val\_loss: 0.0826  
Epoch 91/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0711 -  
val\_loss: 0.0772  
Epoch 92/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0711 -  
val\_loss: 0.0903  
Epoch 93/100  
84868/84868 [=====] - 12s 137us/step - loss: 0.0709 -  
val\_loss: 0.0690  
Epoch 94/100  
84868/84868 [=====] - 12s 136us/step - loss: 0.0704 -  
val\_loss: 0.0792  
Epoch 95/100  
84868/84868 [=====] - 12s 138us/step - loss: 0.0700 -  
val\_loss: 0.0649  
Epoch 96/100  
84868/84868 [=====] - 12s 138us/step - loss: 0.0700 -

```
val_loss: 0.0639
Epoch 97/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0693 -
val_loss: 0.0697
Epoch 98/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0699 -
val_loss: 0.0900
Epoch 99/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0689 -
val_loss: 0.0661
Epoch 100/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0684 -
val_loss: 0.0611
```

```
[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 84868 samples, validate on 21218 samples

```
Epoch 1/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0692 -
val_loss: 0.0807
Epoch 2/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0686 -
val_loss: 0.0892
Epoch 3/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0682 -
val_loss: 0.0716
Epoch 4/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0682 -
val_loss: 0.0779
Epoch 5/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0676 -
val_loss: 0.0639
Epoch 6/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0678 -
val_loss: 0.0830
Epoch 7/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0672 -
val_loss: 0.0815
Epoch 8/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0672 -
val_loss: 0.0724
Epoch 9/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0665 -
```

```

val_loss: 0.0739
Epoch 10/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0666 -
val_loss: 0.0884
Epoch 11/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0668 -
val_loss: 0.0846
Epoch 12/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0655 -
val_loss: 0.0717
Epoch 13/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0660 -
val_loss: 0.0650
Epoch 14/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0653 -
val_loss: 0.0727
Epoch 15/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0654 -
val_loss: 0.0661
Epoch 16/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0653 -
val_loss: 0.0627
Epoch 17/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0635 -
val_loss: 0.0732
Epoch 18/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0612 -
val_loss: 0.0754
Epoch 19/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0607 -
val_loss: 0.0765
Epoch 20/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0600 -
val_loss: 0.0573
Epoch 21/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0609 -
val_loss: 0.0705
Epoch 22/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0596 -
val_loss: 0.0648
Epoch 23/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0587 -
val_loss: 0.0719
Epoch 24/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0585 -
val_loss: 0.0682
Epoch 25/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0581 -

```

```
val_loss: 0.0720
Epoch 26/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0579 -
val_loss: 0.0757
Epoch 27/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0576 -
val_loss: 0.0643
Epoch 28/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0579 -
val_loss: 0.0613
Epoch 29/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0567 -
val_loss: 0.0667
Epoch 30/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0573 -
val_loss: 0.0611
Epoch 31/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0567 -
val_loss: 0.0800
Epoch 32/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0566 -
val_loss: 0.0697
Epoch 33/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0562 -
val_loss: 0.0761
Epoch 34/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0558 -
val_loss: 0.0732
Epoch 35/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0557 -
val_loss: 0.0582
Epoch 36/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0552 -
val_loss: 0.0613
Epoch 37/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0557 -
val_loss: 0.0581
Epoch 38/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0554 -
val_loss: 0.0635
Epoch 39/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0551 -
val_loss: 0.0612
Epoch 40/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0549 -
val_loss: 0.0636
Epoch 41/100
84868/84868 [=====] - 12s 146us/step - loss: 0.0548 -
```

```
val_loss: 0.0837
Epoch 42/100
84868/84868 [=====] - 12s 147us/step - loss: 0.0552 -
val_loss: 0.0546
Epoch 43/100
84868/84868 [=====] - 13s 147us/step - loss: 0.0551 -
val_loss: 0.0826
Epoch 44/100
84868/84868 [=====] - 13s 149us/step - loss: 0.0548 -
val_loss: 0.0614
Epoch 45/100
84868/84868 [=====] - 12s 143us/step - loss: 0.0551 -
val_loss: 0.0664
Epoch 46/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0545 -
val_loss: 0.0739
Epoch 47/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0540 -
val_loss: 0.0699
Epoch 48/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0541 -
val_loss: 0.0699
Epoch 49/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0537 -
val_loss: 0.0735
Epoch 50/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0543 -
val_loss: 0.0627
Epoch 51/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0536 -
val_loss: 0.0537
Epoch 52/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0539 -
val_loss: 0.0620
Epoch 53/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0538 -
val_loss: 0.0514
Epoch 54/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0532 -
val_loss: 0.0579
Epoch 55/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0535 -
val_loss: 0.0635
Epoch 56/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0538 -
val_loss: 0.0772
Epoch 57/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0533 -
```

```
val_loss: 0.0610
Epoch 58/100
84868/84868 [=====] - 12s 136us/step - loss: 0.0530 -
val_loss: 0.0937
Epoch 59/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0533 -
val_loss: 0.0683
Epoch 60/100
84868/84868 [=====] - 12s 146us/step - loss: 0.0532 -
val_loss: 0.0480
Epoch 61/100
84868/84868 [=====] - 14s 160us/step - loss: 0.0526 -
val_loss: 0.0528
Epoch 62/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0525 -
val_loss: 0.0567
Epoch 63/100
84868/84868 [=====] - 11s 134us/step - loss: 0.0527 -
val_loss: 0.0552
Epoch 64/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0520 -
val_loss: 0.0670
Epoch 65/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0527 -
val_loss: 0.0804
Epoch 66/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0519 -
val_loss: 0.0561
Epoch 67/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0518 -
val_loss: 0.0602
Epoch 68/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0521 -
val_loss: 0.0633
Epoch 69/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0517 -
val_loss: 0.0525
Epoch 70/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0510 -
val_loss: 0.0534
Epoch 71/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0515 -
val_loss: 0.0582
Epoch 72/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0507 -
val_loss: 0.0597
Epoch 73/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0506 -
```



```
val_loss: 0.0600
Epoch 74/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0513 -
val_loss: 0.0637
Epoch 75/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0511 -
val_loss: 0.0550
Epoch 76/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0513 -
val_loss: 0.0629
Epoch 77/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0508 -
val_loss: 0.0618
Epoch 78/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0505 -
val_loss: 0.0530
Epoch 79/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0505 -
val_loss: 0.0649
Epoch 80/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0503 -
val_loss: 0.0515
Epoch 81/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0509 -
val_loss: 0.0507
Epoch 82/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0500 -
val_loss: 0.0571
Epoch 83/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0500 -
val_loss: 0.0734
Epoch 84/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0502 -
val_loss: 0.0518
Epoch 85/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0494 -
val_loss: 0.0580
Epoch 86/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0503 -
val_loss: 0.0429
Epoch 87/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0497 -
val_loss: 0.0743
Epoch 88/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0498 -
val_loss: 0.0591
Epoch 89/100
84868/84868 [=====] - 11s 133us/step - loss: 0.0504 -
```

```

val_loss: 0.0509
Epoch 90/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0501 -
val_loss: 0.0550
Epoch 91/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0500 -
val_loss: 0.0535
Epoch 92/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0505 -
val_loss: 0.0555
Epoch 93/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0498 -
val_loss: 0.0598
Epoch 94/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0500 -
val_loss: 0.0443
Epoch 95/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0501 -
val_loss: 0.0498
Epoch 96/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0495 -
val_loss: 0.0580
Epoch 97/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0502 -
val_loss: 0.0490
Epoch 98/100
84868/84868 [=====] - 11s 131us/step - loss: 0.0492 -
val_loss: 0.0718
Epoch 99/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0493 -
val_loss: 0.0584
Epoch 100/100
84868/84868 [=====] - 11s 132us/step - loss: 0.0496 -
val_loss: 0.0576

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))

```

Estado: 3., predicted:3.

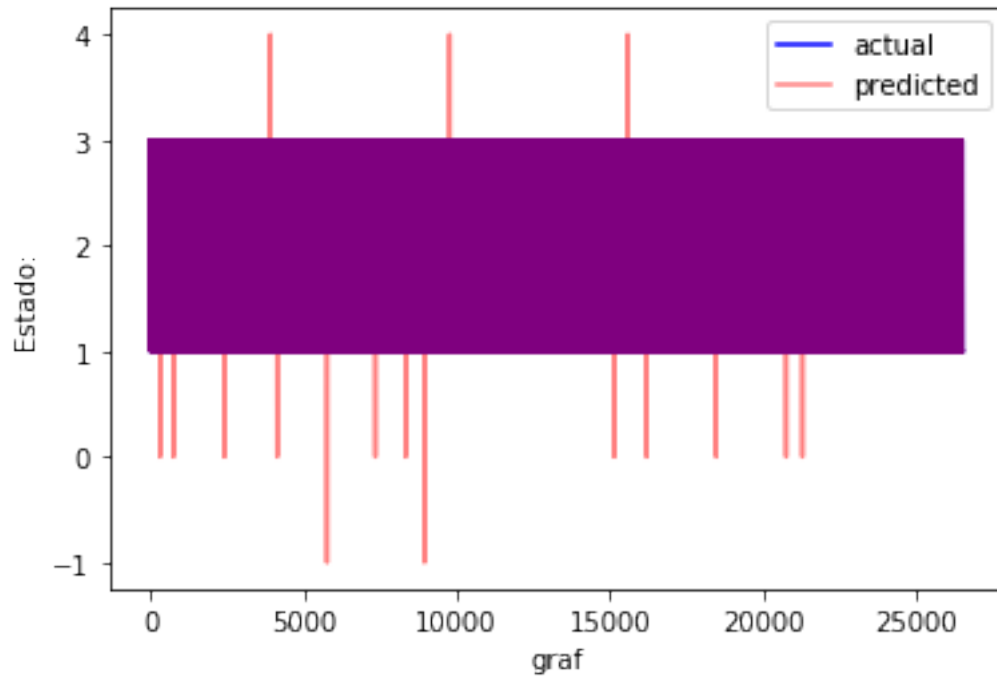
```
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score
      r2 = r2_score(Y_test, Y_val)
      print (r2)
```

0.9449951782739201

```
[26]: plt.plot((Y_val),
              color="b", label="actual")
      plt.plot((Y_test),
              color="r", alpha=0.5, label="predicted")
      plt.xlabel("graf")
      plt.ylabel("Estado:")
      plt.legend(loc="best")
      plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]  
Accu=Y_val2==Y_test  
accur=np.sum(Accu)  
accur/len(Y_val)
```

```
[27]: 0.9811100218686374
```

```
[:]
```

# Wrist\_elux5\_mae\_Adadel\_final

August 27, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```



```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```



```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0827 17:58:21.155245 18896 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0827 17:58:21.167284 18896 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0827 17:58:21.171230 18896 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0827 17:58:21.235178 18896 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0827 17:58:21.421569 18896 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0827 17:58:21.426519 18896 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is

deprecated. Please use `tf.compat.v1.assign` instead.

Train on 84868 samples, validate on 21218 samples

```
Epoch 1/100
84868/84868 [=====] - 14s 168us/step - loss: 0.3635 -
val_loss: 0.2587
Epoch 2/100
84868/84868 [=====] - 13s 154us/step - loss: 0.2186 -
val_loss: 0.1946
Epoch 3/100
84868/84868 [=====] - 13s 157us/step - loss: 0.1677 -
val_loss: 0.1745
Epoch 4/100
84868/84868 [=====] - 14s 160us/step - loss: 0.1433 -
val_loss: 0.1260
Epoch 5/100
84868/84868 [=====] - 13s 157us/step - loss: 0.1290 -
val_loss: 0.1332
Epoch 6/100
84868/84868 [=====] - 13s 155us/step - loss: 0.1189 -
val_loss: 0.1256
Epoch 7/100
84868/84868 [=====] - 14s 160us/step - loss: 0.1120 -
val_loss: 0.1143
Epoch 8/100
84868/84868 [=====] - 14s 161us/step - loss: 0.1073 -
val_loss: 0.1023
Epoch 9/100
84868/84868 [=====] - 13s 158us/step - loss: 0.1036 -
val_loss: 0.1002
Epoch 10/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0996 -
val_loss: 0.1003
Epoch 11/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0966 -
val_loss: 0.0997
Epoch 12/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0939 -
val_loss: 0.0886
Epoch 13/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0922 -
val_loss: 0.1055
Epoch 14/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0898 -
val_loss: 0.1087
Epoch 15/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0876 -
```

```
val_loss: 0.0902
Epoch 16/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0855 -
val_loss: 0.0782
Epoch 17/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0835 -
val_loss: 0.0817
Epoch 18/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0827 -
val_loss: 0.0946
Epoch 19/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0800 -
val_loss: 0.0773
Epoch 20/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0771 -
val_loss: 0.0736
Epoch 21/100
84868/84868 [=====] - 14s 160us/step - loss: 0.0765 -
val_loss: 0.0659
Epoch 22/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0744 -
val_loss: 0.0796
Epoch 23/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0725 -
val_loss: 0.0792
Epoch 24/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0721 -
val_loss: 0.0812
Epoch 25/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0714 -
val_loss: 0.0808
Epoch 26/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0700 -
val_loss: 0.0646
Epoch 27/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0690 -
val_loss: 0.0779
Epoch 28/100
84868/84868 [=====] - 13s 159us/step - loss: 0.0684 -
val_loss: 0.0831
Epoch 29/100
84868/84868 [=====] - 13s 159us/step - loss: 0.0672 -
val_loss: 0.0751
Epoch 30/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0667 -
val_loss: 0.0697
Epoch 31/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0654 -
```



```
val_loss: 0.0661
Epoch 32/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0649 -
val_loss: 0.0639
Epoch 33/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0644 -
val_loss: 0.0642
Epoch 34/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0643 -
val_loss: 0.0702
Epoch 35/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0633 -
val_loss: 0.0709
Epoch 36/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0628 -
val_loss: 0.0588
Epoch 37/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0628 -
val_loss: 0.0676
Epoch 38/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0623 -
val_loss: 0.0728
Epoch 39/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0615 -
val_loss: 0.0593
Epoch 40/100
84868/84868 [=====] - 13s 159us/step - loss: 0.0611 -
val_loss: 0.0724
Epoch 41/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0606 -
val_loss: 0.0611
Epoch 42/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0605 -
val_loss: 0.0625
Epoch 43/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0601 -
val_loss: 0.0649
Epoch 44/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0594 -
val_loss: 0.0656
Epoch 45/100
84868/84868 [=====] - 13s 159us/step - loss: 0.0591 -
val_loss: 0.0631
Epoch 46/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0590 -
val_loss: 0.0813
Epoch 47/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0582 -
```

```
val_loss: 0.0578
Epoch 48/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0587 -
val_loss: 0.0585
Epoch 49/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0576 -
val_loss: 0.0640
Epoch 50/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0577 -
val_loss: 0.0507
Epoch 51/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0566 -
val_loss: 0.0613
Epoch 52/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0563 -
val_loss: 0.0635
Epoch 53/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0560 -
val_loss: 0.0559
Epoch 54/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0558 -
val_loss: 0.0642
Epoch 55/100
84868/84868 [=====] - 13s 159us/step - loss: 0.0558 -
val_loss: 0.0741
Epoch 56/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0559 -
val_loss: 0.0534
Epoch 57/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0546 -
val_loss: 0.0576
Epoch 58/100
84868/84868 [=====] - 14s 159us/step - loss: 0.0546 -
val_loss: 0.0497
Epoch 59/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0538 -
val_loss: 0.0745
Epoch 60/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0531 -
val_loss: 0.0637
Epoch 61/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0535 -
val_loss: 0.0595
Epoch 62/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0536 -
val_loss: 0.0652
Epoch 63/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0529 -
```

```
val_loss: 0.0640
Epoch 64/100
84868/84868 [=====] - 14s 161us/step - loss: 0.0519 -
val_loss: 0.0726
Epoch 65/100
84868/84868 [=====] - 14s 165us/step - loss: 0.0522 -
val_loss: 0.0652
Epoch 66/100
84868/84868 [=====] - 14s 161us/step - loss: 0.0513 -
val_loss: 0.0529
Epoch 67/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0524 -
val_loss: 0.0535
Epoch 68/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0522 -
val_loss: 0.0643
Epoch 69/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0510 -
val_loss: 0.0537
Epoch 70/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0514 -
val_loss: 0.0612
Epoch 71/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0505 -
val_loss: 0.0484
Epoch 72/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0501 -
val_loss: 0.0681
Epoch 73/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0509 -
val_loss: 0.0615
Epoch 74/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0500 -
val_loss: 0.0517
Epoch 75/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0504 -
val_loss: 0.0584
Epoch 76/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0495 -
val_loss: 0.0595
Epoch 77/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0494 -
val_loss: 0.0542
Epoch 78/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0497 -
val_loss: 0.0615
Epoch 79/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0488 -
```

```
val_loss: 0.0580
Epoch 80/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0492 -
val_loss: 0.0493
Epoch 81/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0496 -
val_loss: 0.0534
Epoch 82/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0490 -
val_loss: 0.0656
Epoch 83/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0491 -
val_loss: 0.0583
Epoch 84/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0483 -
val_loss: 0.0631
Epoch 85/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0481 -
val_loss: 0.0550
Epoch 86/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0484 -
val_loss: 0.0651
Epoch 87/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0490 -
val_loss: 0.0697
Epoch 88/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0477 -
val_loss: 0.0573
Epoch 89/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0484 -
val_loss: 0.0461
Epoch 90/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0484 -
val_loss: 0.0481
Epoch 91/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0477 -
val_loss: 0.0652
Epoch 92/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0481 -
val_loss: 0.0509
Epoch 93/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0473 -
val_loss: 0.0579
Epoch 94/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0476 -
val_loss: 0.0501
Epoch 95/100
84868/84868 [=====] - 14s 160us/step - loss: 0.0473 -
```

```
val_loss: 0.0496
Epoch 96/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0468 -
val_loss: 0.0506
Epoch 97/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0473 -
val_loss: 0.0486
Epoch 98/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0463 -
val_loss: 0.0556
Epoch 99/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0464 -
val_loss: 0.0588
Epoch 100/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0466 -
val_loss: 0.0538
```

```
[21]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)
```

Train on 84868 samples, validate on 21218 samples

```
Epoch 1/100
84868/84868 [=====] - 14s 161us/step - loss: 0.0465 -
val_loss: 0.0531
Epoch 2/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0451 -
val_loss: 0.0405
Epoch 3/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0447 -
val_loss: 0.0584
Epoch 4/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0480 -
val_loss: 0.0530
Epoch 5/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0452 -
val_loss: 0.0437
Epoch 6/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0448 -
val_loss: 0.0480
Epoch 7/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0449 -
val_loss: 0.0460
Epoch 8/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0451 -
```

```
val_loss: 0.0420
Epoch 9/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0451 -
val_loss: 0.0488
Epoch 10/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0448 -
val_loss: 0.0462
Epoch 11/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0445 -
val_loss: 0.0484
Epoch 12/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0451 -
val_loss: 0.0563
Epoch 13/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0447 -
val_loss: 0.0486
Epoch 14/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0443 -
val_loss: 0.0519
Epoch 15/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0433 -
val_loss: 0.0535
Epoch 16/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0434 -
val_loss: 0.0488
Epoch 17/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0431 -
val_loss: 0.0523
Epoch 18/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0428 -
val_loss: 0.0592
Epoch 19/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0430 -
val_loss: 0.0629
Epoch 20/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0429 -
val_loss: 0.0526
Epoch 21/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0425 -
val_loss: 0.0444
Epoch 22/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0423 -
val_loss: 0.0373
Epoch 23/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0429 -
val_loss: 0.0497
Epoch 24/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0430 -
```

```
val_loss: 0.0640
Epoch 25/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0428 -
val_loss: 0.0574
Epoch 26/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0428 -
val_loss: 0.0520
Epoch 27/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0431 -
val_loss: 0.0358
Epoch 28/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0427 -
val_loss: 0.0450
Epoch 29/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0422 -
val_loss: 0.0389
Epoch 30/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0431 -
val_loss: 0.0413
Epoch 31/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0425 -
val_loss: 0.0488
Epoch 32/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0427 -
val_loss: 0.0399
Epoch 33/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0422 -
val_loss: 0.0580
Epoch 34/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0434 -
val_loss: 0.0483
Epoch 35/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0425 -
val_loss: 0.0593
Epoch 36/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0429 -
val_loss: 0.0506
Epoch 37/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0429 -
val_loss: 0.0532
Epoch 38/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0422 -
val_loss: 0.0454
Epoch 39/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0420 -
val_loss: 0.0576
Epoch 40/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0423 -
```

```
val_loss: 0.0531
Epoch 41/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0422 -
val_loss: 0.0428
Epoch 42/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0420 -
val_loss: 0.0450
Epoch 43/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0417 -
val_loss: 0.0450
Epoch 44/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0412 -
val_loss: 0.0531
Epoch 45/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0410 -
val_loss: 0.0422
Epoch 46/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0413 -
val_loss: 0.0421
Epoch 47/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0409 -
val_loss: 0.0395
Epoch 48/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0412 -
val_loss: 0.0469
Epoch 49/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0417 -
val_loss: 0.0509
Epoch 50/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0410 -
val_loss: 0.0579
Epoch 51/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0413 -
val_loss: 0.0534
Epoch 52/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0413 -
val_loss: 0.0472
Epoch 53/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0410 -
val_loss: 0.0538
Epoch 54/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0409 -
val_loss: 0.0362
Epoch 55/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0406 -
val_loss: 0.0515
Epoch 56/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0410 -
```



```
val_loss: 0.0511
Epoch 57/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0401 -
val_loss: 0.0383
Epoch 58/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0407 -
val_loss: 0.0659
Epoch 59/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0400 -
val_loss: 0.0470
Epoch 60/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0412 -
val_loss: 0.0383
Epoch 61/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0416 -
val_loss: 0.0649
Epoch 62/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0406 -
val_loss: 0.0484
Epoch 63/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0420 -
val_loss: 0.0377
Epoch 64/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0405 -
val_loss: 0.0429
Epoch 65/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0406 -
val_loss: 0.0511
Epoch 66/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0403 -
val_loss: 0.0479
Epoch 67/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0404 -
val_loss: 0.0444
Epoch 68/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0403 -
val_loss: 0.0411
Epoch 69/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0399 -
val_loss: 0.0475
Epoch 70/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0403 -
val_loss: 0.0440
Epoch 71/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0406 -
val_loss: 0.0473
Epoch 72/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0399 -
```

```
val_loss: 0.0428
Epoch 73/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0399 -
val_loss: 0.0507
Epoch 74/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0393 -
val_loss: 0.0471
Epoch 75/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0392 -
val_loss: 0.0472
Epoch 76/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0398 -
val_loss: 0.0513
Epoch 77/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0396 -
val_loss: 0.0388
Epoch 78/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0392 -
val_loss: 0.0487
Epoch 79/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0409 -
val_loss: 0.0430
Epoch 80/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0391 -
val_loss: 0.0558
Epoch 81/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0396 -
val_loss: 0.0401
Epoch 82/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0396 -
val_loss: 0.0388
Epoch 83/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0393 -
val_loss: 0.0493
Epoch 84/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0387 -
val_loss: 0.0530
Epoch 85/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0389 -
val_loss: 0.0558
Epoch 86/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0401 -
val_loss: 0.0432
Epoch 87/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0400 -
val_loss: 0.0536
Epoch 88/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0394 -
```

```

val_loss: 0.0429
Epoch 89/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0393 -
val_loss: 0.0500
Epoch 90/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0397 -
val_loss: 0.0555
Epoch 91/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0391 -
val_loss: 0.0446
Epoch 92/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0400 -
val_loss: 0.0553
Epoch 93/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0407 -
val_loss: 0.0454
Epoch 94/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0397 -
val_loss: 0.0411
Epoch 95/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0397 -
val_loss: 0.0513
Epoch 96/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0400 -
val_loss: 0.0428
Epoch 97/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0403 -
val_loss: 0.0534
Epoch 98/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0395 -
val_loss: 0.0462
Epoch 99/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0394 -
val_loss: 0.0473
Epoch 100/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0404 -
val_loss: 0.0491

```

```
[22]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[23]: Y_test = np.round(Y_test, 0)
```

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
```

```
print("Estado: "+ np.array2string(label) + ", predicted:" + np.  
↪array2string(prediction))
```

```
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

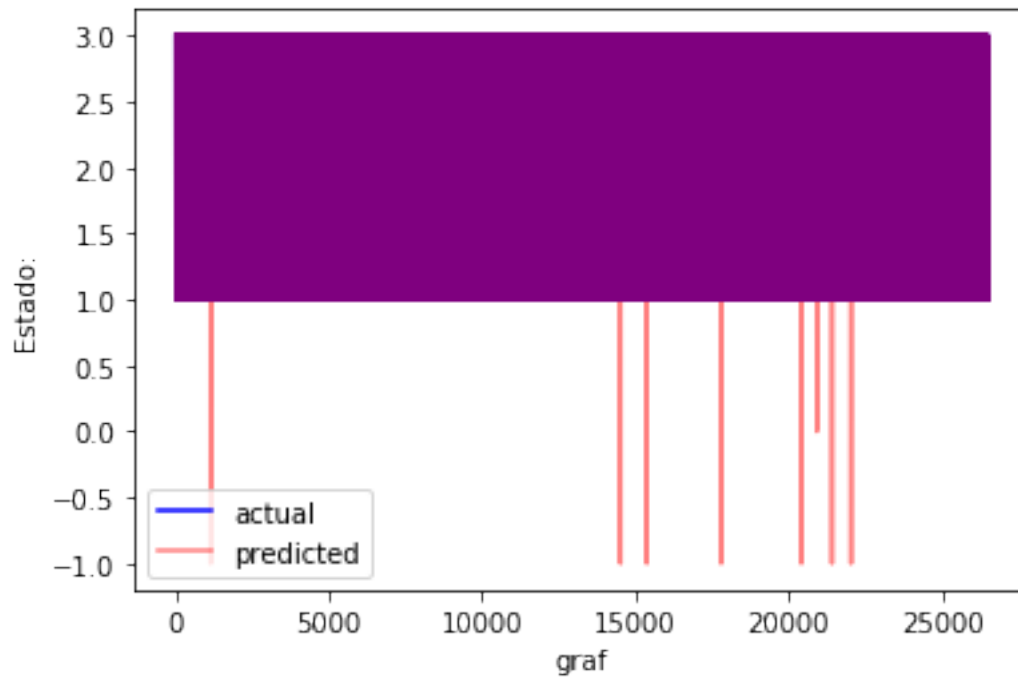
Evaluamos los resultados:

```
[25]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9373327182053833

```
[26]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")
```

```
plt.legend(loc="best")
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[27]: 0.9814493627931529
```

```
[:]
```

# Wrist\_elux7\_mae\_Adadel\_final

August 27, 2019

## 1 Wrist Data

Librerías:

```
[3]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[4]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S3.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```



```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[8]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[10]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```



```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[17]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[18]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[19]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[20]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[21]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

Dense(60),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(30),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0827 18:46:22.944923 19300 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0827 18:46:22.959837 19300 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0827 18:46:22.963827 19300 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0827 18:46:23.061565 19300 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[22]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0827 18:46:23.283006 19300 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0827 18:46:23.288008 19300 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 84868 samples, validate on 21218 samples

```
Epoch 1/100
84868/84868 [=====] - 17s 205us/step - loss: 0.3384 -
val_loss: 0.2349
Epoch 2/100
84868/84868 [=====] - 16s 191us/step - loss: 0.1988 -
val_loss: 0.1797
Epoch 3/100
84868/84868 [=====] - 16s 191us/step - loss: 0.1505 -
val_loss: 0.1360
Epoch 4/100
84868/84868 [=====] - 16s 191us/step - loss: 0.1323 -
val_loss: 0.1396
Epoch 5/100
84868/84868 [=====] - 16s 190us/step - loss: 0.1198 -
val_loss: 0.1167
Epoch 6/100
84868/84868 [=====] - 16s 187us/step - loss: 0.1122 -
val_loss: 0.1205
Epoch 7/100
84868/84868 [=====] - 16s 189us/step - loss: 0.1045 -
val_loss: 0.1122
Epoch 8/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0988 -
val_loss: 0.1034
Epoch 9/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0939 -
val_loss: 0.1069
Epoch 10/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0897 -
val_loss: 0.0963
Epoch 11/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0862 -
val_loss: 0.0863
Epoch 12/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0850 -
val_loss: 0.0950
Epoch 13/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0816 -
val_loss: 0.0891
Epoch 14/100
```



84868/84868 [=====] - 16s 192us/step - loss: 0.0804 -  
val\_loss: 0.0757  
Epoch 15/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0787 -  
val\_loss: 0.0725  
Epoch 16/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0756 -  
val\_loss: 0.0716  
Epoch 17/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0736 -  
val\_loss: 0.0804  
Epoch 18/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0724 -  
val\_loss: 0.0741  
Epoch 19/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0714 -  
val\_loss: 0.0753  
Epoch 20/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0703 -  
val\_loss: 0.0797  
Epoch 21/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0704 -  
val\_loss: 0.0712  
Epoch 22/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0693 -  
val\_loss: 0.0669  
Epoch 23/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0683 -  
val\_loss: 0.0696  
Epoch 24/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0668 -  
val\_loss: 0.0768  
Epoch 25/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0680 -  
val\_loss: 0.0655  
Epoch 26/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0656 -  
val\_loss: 0.0638  
Epoch 27/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0661 -  
val\_loss: 0.0636  
Epoch 28/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0652 -  
val\_loss: 0.0724  
Epoch 29/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0653 -  
val\_loss: 0.0600  
Epoch 30/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0636 -  
val\_loss: 0.0605  
Epoch 31/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0640 -  
val\_loss: 0.0679  
Epoch 32/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0625 -  
val\_loss: 0.0728  
Epoch 33/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0633 -  
val\_loss: 0.0610  
Epoch 34/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0612 -  
val\_loss: 0.0616  
Epoch 35/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0605 -  
val\_loss: 0.0593  
Epoch 36/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0608 -  
val\_loss: 0.0629  
Epoch 37/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0605 -  
val\_loss: 0.0590  
Epoch 38/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0599 -  
val\_loss: 0.0643  
Epoch 39/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0592 -  
val\_loss: 0.0615  
Epoch 40/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0602 -  
val\_loss: 0.0659  
Epoch 41/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0597 -  
val\_loss: 0.0685  
Epoch 42/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0586 -  
val\_loss: 0.0599  
Epoch 43/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0582 -  
val\_loss: 0.0658  
Epoch 44/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0595 -  
val\_loss: 0.0710  
Epoch 45/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0590 -  
val\_loss: 0.0645  
Epoch 46/100

84868/84868 [=====] - 16s 190us/step - loss: 0.0580 -  
val\_loss: 0.0640  
Epoch 47/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0589 -  
val\_loss: 0.0655  
Epoch 48/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0582 -  
val\_loss: 0.0615  
Epoch 49/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0585 -  
val\_loss: 0.0686  
Epoch 50/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0580 -  
val\_loss: 0.0631  
Epoch 51/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0572 -  
val\_loss: 0.0620  
Epoch 52/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0582 -  
val\_loss: 0.0568  
Epoch 53/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0573 -  
val\_loss: 0.0615  
Epoch 54/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0574 -  
val\_loss: 0.0561  
Epoch 55/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0576 -  
val\_loss: 0.0634  
Epoch 56/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0565 -  
val\_loss: 0.0649  
Epoch 57/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0558 -  
val\_loss: 0.0662  
Epoch 58/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0550 -  
val\_loss: 0.0590  
Epoch 59/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0549 -  
val\_loss: 0.0649  
Epoch 60/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0568 -  
val\_loss: 0.0536  
Epoch 61/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0561 -  
val\_loss: 0.0613  
Epoch 62/100

84868/84868 [=====] - 16s 191us/step - loss: 0.0566 -  
val\_loss: 0.0565  
Epoch 63/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0561 -  
val\_loss: 0.0595  
Epoch 64/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0562 -  
val\_loss: 0.0576  
Epoch 65/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0553 -  
val\_loss: 0.0563  
Epoch 66/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0561 -  
val\_loss: 0.0552  
Epoch 67/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0554 -  
val\_loss: 0.0508  
Epoch 68/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0557 -  
val\_loss: 0.0627  
Epoch 69/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0549 -  
val\_loss: 0.0542  
Epoch 70/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0563 -  
val\_loss: 0.0679  
Epoch 71/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0556 -  
val\_loss: 0.0614  
Epoch 72/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0563 -  
val\_loss: 0.0521  
Epoch 73/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0556 -  
val\_loss: 0.1056  
Epoch 74/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0577 -  
val\_loss: 0.0635  
Epoch 75/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0563 -  
val\_loss: 0.0671  
Epoch 76/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0545 -  
val\_loss: 0.0580  
Epoch 77/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0538 -  
val\_loss: 0.0541  
Epoch 78/100

84868/84868 [=====] - 16s 191us/step - loss: 0.0512 -  
val\_loss: 0.0527  
Epoch 79/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0512 -  
val\_loss: 0.0436  
Epoch 80/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0510 -  
val\_loss: 0.0500  
Epoch 81/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0516 -  
val\_loss: 0.0541  
Epoch 82/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0489 -  
val\_loss: 0.0673  
Epoch 83/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0503 -  
val\_loss: 0.0507  
Epoch 84/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0500 -  
val\_loss: 0.0636  
Epoch 85/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0495 -  
val\_loss: 0.0545  
Epoch 86/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0499 -  
val\_loss: 0.0616  
Epoch 87/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0510 -  
val\_loss: 0.0528  
Epoch 88/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0493 -  
val\_loss: 0.0500  
Epoch 89/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0484 -  
val\_loss: 0.0491  
Epoch 90/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0493 -  
val\_loss: 0.0526  
Epoch 91/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0499 -  
val\_loss: 0.0692  
Epoch 92/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0492 -  
val\_loss: 0.0523  
Epoch 93/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0492 -  
val\_loss: 0.0488  
Epoch 94/100

```

84868/84868 [=====] - 16s 191us/step - loss: 0.0483 -
val_loss: 0.0483
Epoch 95/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0475 -
val_loss: 0.0427
Epoch 96/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0478 -
val_loss: 0.0596
Epoch 97/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0479 -
val_loss: 0.0505
Epoch 98/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0482 -
val_loss: 0.0582
Epoch 99/100
84868/84868 [=====] - 16s 187us/step - loss: 0.0478 -
val_loss: 0.0441
Epoch 100/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0485 -
val_loss: 0.0578

```

```

[23]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

```

Train on 84868 samples, validate on 21218 samples
Epoch 1/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0481 -
val_loss: 0.0599
Epoch 2/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0493 -
val_loss: 0.0586
Epoch 3/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0477 -
val_loss: 0.0480
Epoch 4/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0474 -
val_loss: 0.0558
Epoch 5/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0475 -
val_loss: 0.0562
Epoch 6/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0483 -
val_loss: 0.0565
Epoch 7/100

```

84868/84868 [=====] - 16s 188us/step - loss: 0.0481 -  
val\_loss: 0.0536  
Epoch 8/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0476 -  
val\_loss: 0.0625  
Epoch 9/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0491 -  
val\_loss: 0.0678  
Epoch 10/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0484 -  
val\_loss: 0.0596  
Epoch 11/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0496 -  
val\_loss: 0.0644  
Epoch 12/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0488 -  
val\_loss: 0.0550  
Epoch 13/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0472 -  
val\_loss: 0.0484  
Epoch 14/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0494 -  
val\_loss: 0.0581  
Epoch 15/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0492 -  
val\_loss: 0.0510  
Epoch 16/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0473 -  
val\_loss: 0.0448  
Epoch 17/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0483 -  
val\_loss: 0.0489  
Epoch 18/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0497 -  
val\_loss: 0.0528  
Epoch 19/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0483 -  
val\_loss: 0.0541  
Epoch 20/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0477 -  
val\_loss: 0.0540  
Epoch 21/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0483 -  
val\_loss: 0.0632  
Epoch 22/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0481 -  
val\_loss: 0.0409  
Epoch 23/100

84868/84868 [=====] - 16s 191us/step - loss: 0.0497 -  
val\_loss: 0.0503  
Epoch 24/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0505 -  
val\_loss: 0.0578  
Epoch 25/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0497 -  
val\_loss: 0.0548  
Epoch 26/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0499 -  
val\_loss: 0.0572  
Epoch 27/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0493 -  
val\_loss: 0.0439  
Epoch 28/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0524 -  
val\_loss: 0.0554  
Epoch 29/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0506 -  
val\_loss: 0.0534  
Epoch 30/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0491 -  
val\_loss: 0.0531  
Epoch 31/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0510 -  
val\_loss: 0.0715  
Epoch 32/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0497 -  
val\_loss: 0.0530  
Epoch 33/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0508 -  
val\_loss: 0.0473  
Epoch 34/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0487 -  
val\_loss: 0.0479  
Epoch 35/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0490 -  
val\_loss: 0.0577  
Epoch 36/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0513 -  
val\_loss: 0.0463  
Epoch 37/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0537 -  
val\_loss: 0.0933  
Epoch 38/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0511 -  
val\_loss: 0.0534  
Epoch 39/100



84868/84868 [=====] - 16s 191us/step - loss: 0.0522 -  
val\_loss: 0.0546  
Epoch 40/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0520 -  
val\_loss: 0.0700  
Epoch 41/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0526 -  
val\_loss: 0.0526  
Epoch 42/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0548 -  
val\_loss: 0.0583  
Epoch 43/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0537 -  
val\_loss: 0.0524  
Epoch 44/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0520 -  
val\_loss: 0.0489  
Epoch 45/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0507 -  
val\_loss: 0.0568  
Epoch 46/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0520 -  
val\_loss: 0.0437  
Epoch 47/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0524 -  
val\_loss: 0.0591  
Epoch 48/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0524 -  
val\_loss: 0.0601  
Epoch 49/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0508 -  
val\_loss: 0.0518  
Epoch 50/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0523 -  
val\_loss: 0.0510  
Epoch 51/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0533 -  
val\_loss: 0.0543  
Epoch 52/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0498 -  
val\_loss: 0.0472  
Epoch 53/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0522 -  
val\_loss: 0.0433  
Epoch 54/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0536 -  
val\_loss: 0.0693  
Epoch 55/100

84868/84868 [=====] - 16s 190us/step - loss: 0.0528 -  
val\_loss: 0.0492  
Epoch 56/100  
84868/84868 [=====] - 24s 287us/step - loss: 0.0519 -  
val\_loss: 0.0596  
Epoch 57/100  
84868/84868 [=====] - 34s 402us/step - loss: 0.0517 -  
val\_loss: 0.0600  
Epoch 58/100  
84868/84868 [=====] - 30s 358us/step - loss: 0.0535 -  
val\_loss: 0.0621  
Epoch 59/100  
84868/84868 [=====] - 42s 496us/step - loss: 0.0546 -  
val\_loss: 0.0620  
Epoch 60/100  
84868/84868 [=====] - 40s 474us/step - loss: 0.0512 -  
val\_loss: 0.0466  
Epoch 61/100  
84868/84868 [=====] - 29s 343us/step - loss: 0.0508 -  
val\_loss: 0.0571  
Epoch 62/100  
84868/84868 [=====] - 44s 518us/step - loss: 0.0529 -  
val\_loss: 0.0527  
Epoch 63/100  
84868/84868 [=====] - 32s 379us/step - loss: 0.0501 -  
val\_loss: 0.0608  
Epoch 64/100  
84868/84868 [=====] - 31s 363us/step - loss: 0.0508 -  
val\_loss: 0.0563  
Epoch 65/100  
84868/84868 [=====] - 31s 369us/step - loss: 0.0503 -  
val\_loss: 0.0625  
Epoch 66/100  
84868/84868 [=====] - 34s 403us/step - loss: 0.0502 -  
val\_loss: 0.0538  
Epoch 67/100  
84868/84868 [=====] - 39s 460us/step - loss: 0.0514 -  
val\_loss: 0.0634  
Epoch 68/100  
84868/84868 [=====] - 30s 356us/step - loss: 0.0510 -  
val\_loss: 0.0536  
Epoch 69/100  
84868/84868 [=====] - 39s 465us/step - loss: 0.0505 -  
val\_loss: 0.0755  
Epoch 70/100  
84868/84868 [=====] - 32s 377us/step - loss: 0.0471 -  
val\_loss: 0.0560  
Epoch 71/100

```

84868/84868 [=====] - 33s 386us/step - loss: 0.0476 -
val_loss: 0.0507
Epoch 72/100
84868/84868 [=====] - 17s 202us/step - loss: 0.0448 -
val_loss: 0.0472
Epoch 73/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0463 -
val_loss: 0.0570
Epoch 74/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0442 -
val_loss: 0.0505
Epoch 75/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0461 -
val_loss: 0.0713
Epoch 76/100
84868/84868 [=====] - 16s 188us/step - loss: 0.0457 -
val_loss: 0.0408
Epoch 77/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0444 -
val_loss: 0.0476
Epoch 78/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0441 -
val_loss: 0.0461
Epoch 79/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0467 -
val_loss: 0.0632
Epoch 80/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0455 -
val_loss: 0.0375
Epoch 81/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0433 -
val_loss: 0.0460
Epoch 82/100
84868/84868 [=====] - 16s 189us/step - loss: 0.0439 -
val_loss: 0.0594
Epoch 83/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0460 -
val_loss: 0.0531
Epoch 84/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0453 -
val_loss: 0.0467
Epoch 85/100
84868/84868 [=====] - 16s 190us/step - loss: 0.0444 -
val_loss: 0.0442
Epoch 86/100
84868/84868 [=====] - 16s 191us/step - loss: 0.0452 -
val_loss: 0.0477
Epoch 87/100

```

```
84868/84868 [=====] - 16s 190us/step - loss: 0.0452 -  
val_loss: 0.0546  
Epoch 88/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0453 -  
val_loss: 0.0446  
Epoch 89/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0435 -  
val_loss: 0.0430  
Epoch 90/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0441 -  
val_loss: 0.0406  
Epoch 91/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0429 -  
val_loss: 0.0508  
Epoch 92/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0439 -  
val_loss: 0.0425  
Epoch 93/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0440 -  
val_loss: 0.0435  
Epoch 94/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0454 -  
val_loss: 0.0429  
Epoch 95/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0447 -  
val_loss: 0.0835  
Epoch 96/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0464 -  
val_loss: 0.0504  
Epoch 97/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0442 -  
val_loss: 0.0468  
Epoch 98/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0432 -  
val_loss: 0.0455  
Epoch 99/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0438 -  
val_loss: 0.0624  
Epoch 100/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0418 -  
val_loss: 0.0512
```

```
[24]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[25]: Y_test =np.round(Y_test, 0)
```

```
[26]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↪array2string(prediction))
```

```
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
```

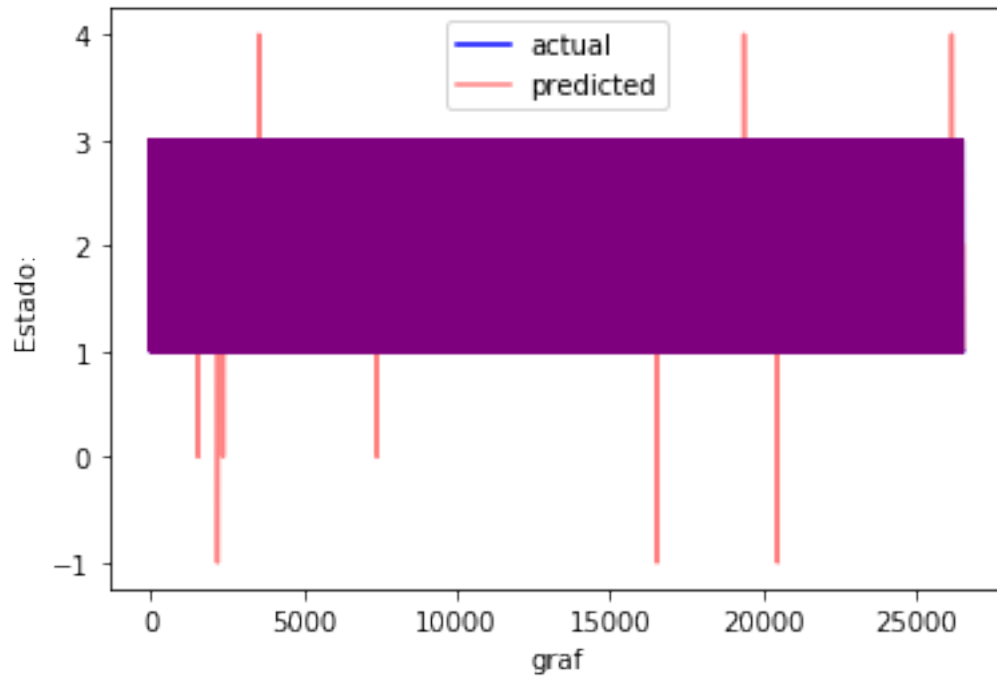
Evaluamos los resultados:

```
[27]: from sklearn.metrics import r2_score
        r2 = r2_score(Y_test, Y_val)
        print (r2)
```

0.9039227793796867

```
[28]: plt.plot((Y_val),
        color="b", label="actual")
```

```
plt.plot((Y_test),
         color="r", alpha=0.5, label="predicted")
plt.xlabel("graf")
plt.ylabel("Estado:")
plt.legend(loc="best")
plt.show()
```



```
[29]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_test
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[29]: 0.9731543624161074
```

```
[ ]:
```

# Wrist\_elux4\_mae\_Adadel\_final

August 28, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```



```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```



```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:10]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0828 16:31:07.587659 16372 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0828 16:31:07.622563 16372 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0828 16:31:07.634500 16372 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0828 16:31:07.699326 16372 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0828 16:31:07.902820 16372 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0828 16:31:07.908801 16372 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.



Train on 84868 samples, validate on 21218 samples

Epoch 1/100

84868/84868 [=====] - 16s 191us/step - loss: 0.4390 -  
val\_loss: 0.3262

Epoch 2/100

84868/84868 [=====] - 12s 142us/step - loss: 0.2624 -  
val\_loss: 0.2508

Epoch 3/100

84868/84868 [=====] - 12s 139us/step - loss: 0.2222 -  
val\_loss: 0.2135

Epoch 4/100

84868/84868 [=====] - 12s 139us/step - loss: 0.2000 -  
val\_loss: 0.1893

Epoch 5/100

84868/84868 [=====] - 12s 141us/step - loss: 0.1845 -  
val\_loss: 0.1879

Epoch 6/100

84868/84868 [=====] - 12s 139us/step - loss: 0.1719 -  
val\_loss: 0.1836

Epoch 7/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1588 -  
val\_loss: 0.1509

Epoch 8/100

84868/84868 [=====] - 12s 137us/step - loss: 0.1419 -  
val\_loss: 0.1455

Epoch 9/100

84868/84868 [=====] - 12s 140us/step - loss: 0.1325 -  
val\_loss: 0.1495

Epoch 10/100

84868/84868 [=====] - 12s 143us/step - loss: 0.1269 -  
val\_loss: 0.1265

Epoch 11/100

84868/84868 [=====] - 12s 140us/step - loss: 0.1224 -  
val\_loss: 0.1430

Epoch 12/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1172 -  
val\_loss: 0.1209

Epoch 13/100

84868/84868 [=====] - 12s 141us/step - loss: 0.1143 -  
val\_loss: 0.1333

Epoch 14/100

84868/84868 [=====] - 12s 140us/step - loss: 0.1112 -  
val\_loss: 0.1083

Epoch 15/100

84868/84868 [=====] - 12s 140us/step - loss: 0.1079 -  
val\_loss: 0.1116

Epoch 16/100

84868/84868 [=====] - 12s 138us/step - loss: 0.1058 -

```
val_loss: 0.1085
Epoch 17/100
84868/84868 [=====] - 12s 140us/step - loss: 0.1040 -
val_loss: 0.0986
Epoch 18/100
84868/84868 [=====] - 12s 140us/step - loss: 0.1023 -
val_loss: 0.1022
Epoch 19/100
84868/84868 [=====] - 12s 140us/step - loss: 0.1009 -
val_loss: 0.1193
Epoch 20/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0990 -
val_loss: 0.1074
Epoch 21/100
84868/84868 [=====] - 12s 141us/step - loss: 0.0971 -
val_loss: 0.1192
Epoch 22/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0960 -
val_loss: 0.0973
Epoch 23/100
84868/84868 [=====] - 12s 142us/step - loss: 0.0951 -
val_loss: 0.1113
Epoch 24/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0931 -
val_loss: 0.1159
Epoch 25/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0921 -
val_loss: 0.0888
Epoch 26/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0910 -
val_loss: 0.1148
Epoch 27/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0905 -
val_loss: 0.0897
Epoch 28/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0893 -
val_loss: 0.1111
Epoch 29/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0885 -
val_loss: 0.0898
Epoch 30/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0883 -
val_loss: 0.1090
Epoch 31/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0872 -
val_loss: 0.0922
Epoch 32/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0868 -
```

val\_loss: 0.1000  
Epoch 33/100  
84868/84868 [=====] - 12s 140us/step - loss: 0.0858 -  
val\_loss: 0.1038  
Epoch 34/100  
84868/84868 [=====] - 12s 140us/step - loss: 0.0852 -  
val\_loss: 0.0820  
Epoch 35/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0851 -  
val\_loss: 0.0808  
Epoch 36/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0840 -  
val\_loss: 0.0962  
Epoch 37/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0836 -  
val\_loss: 0.0781  
Epoch 38/100  
84868/84868 [=====] - 12s 142us/step - loss: 0.0834 -  
val\_loss: 0.0941  
Epoch 39/100  
84868/84868 [=====] - 12s 141us/step - loss: 0.0833 -  
val\_loss: 0.0906  
Epoch 40/100  
84868/84868 [=====] - 12s 140us/step - loss: 0.0822 -  
val\_loss: 0.0842  
Epoch 41/100  
84868/84868 [=====] - 12s 140us/step - loss: 0.0813 -  
val\_loss: 0.0873  
Epoch 42/100  
84868/84868 [=====] - 12s 140us/step - loss: 0.0812 -  
val\_loss: 0.0855  
Epoch 43/100  
84868/84868 [=====] - 12s 138us/step - loss: 0.0805 -  
val\_loss: 0.0809  
Epoch 44/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0803 -  
val\_loss: 0.0915  
Epoch 45/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0801 -  
val\_loss: 0.0798  
Epoch 46/100  
84868/84868 [=====] - 12s 138us/step - loss: 0.0795 -  
val\_loss: 0.0854  
Epoch 47/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0793 -  
val\_loss: 0.0939  
Epoch 48/100  
84868/84868 [=====] - 12s 139us/step - loss: 0.0787 -

```
val_loss: 0.0887
Epoch 49/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0783 -
val_loss: 0.0777
Epoch 50/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0783 -
val_loss: 0.0854
Epoch 51/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0777 -
val_loss: 0.0967
Epoch 52/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0772 -
val_loss: 0.0861
Epoch 53/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0769 -
val_loss: 0.1039
Epoch 54/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0769 -
val_loss: 0.0904
Epoch 55/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0773 -
val_loss: 0.0856
Epoch 56/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0770 -
val_loss: 0.0883
Epoch 57/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0761 -
val_loss: 0.1035
Epoch 58/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0761 -
val_loss: 0.0813
Epoch 59/100
84868/84868 [=====] - 12s 143us/step - loss: 0.0762 -
val_loss: 0.0983
Epoch 60/100
84868/84868 [=====] - 12s 146us/step - loss: 0.0761 -
val_loss: 0.0851
Epoch 61/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0757 -
val_loss: 0.0937
Epoch 62/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0750 -
val_loss: 0.0761
Epoch 63/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0758 -
val_loss: 0.0802
Epoch 64/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0749 -
```

```
val_loss: 0.0980
Epoch 65/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0743 -
val_loss: 0.0867
Epoch 66/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0743 -
val_loss: 0.0802
Epoch 67/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0738 -
val_loss: 0.0786
Epoch 68/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0739 -
val_loss: 0.1063
Epoch 69/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0736 -
val_loss: 0.0824
Epoch 70/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0735 -
val_loss: 0.0764
Epoch 71/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0735 -
val_loss: 0.0843
Epoch 72/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0735 -
val_loss: 0.0696
Epoch 73/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0732 -
val_loss: 0.0900
Epoch 74/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0731 -
val_loss: 0.0829
Epoch 75/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0727 -
val_loss: 0.0951
Epoch 76/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0727 -
val_loss: 0.0766
Epoch 77/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0726 -
val_loss: 0.0829
Epoch 78/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0726 -
val_loss: 0.0616
Epoch 79/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0717 -
val_loss: 0.0963
Epoch 80/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0710 -
```

```
val_loss: 0.0774
Epoch 81/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0716 -
val_loss: 0.0634
Epoch 82/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0714 -
val_loss: 0.0741
Epoch 83/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0708 -
val_loss: 0.0842
Epoch 84/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0705 -
val_loss: 0.0723
Epoch 85/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0700 -
val_loss: 0.0869
Epoch 86/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0704 -
val_loss: 0.0961
Epoch 87/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0702 -
val_loss: 0.0714
Epoch 88/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0699 -
val_loss: 0.0868
Epoch 89/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0702 -
val_loss: 0.0852
Epoch 90/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0696 -
val_loss: 0.0660
Epoch 91/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0692 -
val_loss: 0.0859
Epoch 92/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0694 -
val_loss: 0.0837
Epoch 93/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0693 -
val_loss: 0.0835
Epoch 94/100
84868/84868 [=====] - 12s 137us/step - loss: 0.0691 -
val_loss: 0.0707
Epoch 95/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0689 -
val_loss: 0.0701
Epoch 96/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0689 -
```

```

val_loss: 0.0705
Epoch 97/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0683 -
val_loss: 0.0765
Epoch 98/100
84868/84868 [=====] - 12s 140us/step - loss: 0.0685 -
val_loss: 0.0791
Epoch 99/100
84868/84868 [=====] - 12s 139us/step - loss: 0.0682 -
val_loss: 0.0643
Epoch 100/100
84868/84868 [=====] - 12s 138us/step - loss: 0.0678 -
val_loss: 0.0686

```

```
[21]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[22]: Y_test = np.round(Y_test, 0)
```

```
[23]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        →array2string(prediction))

```

```

Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.

```

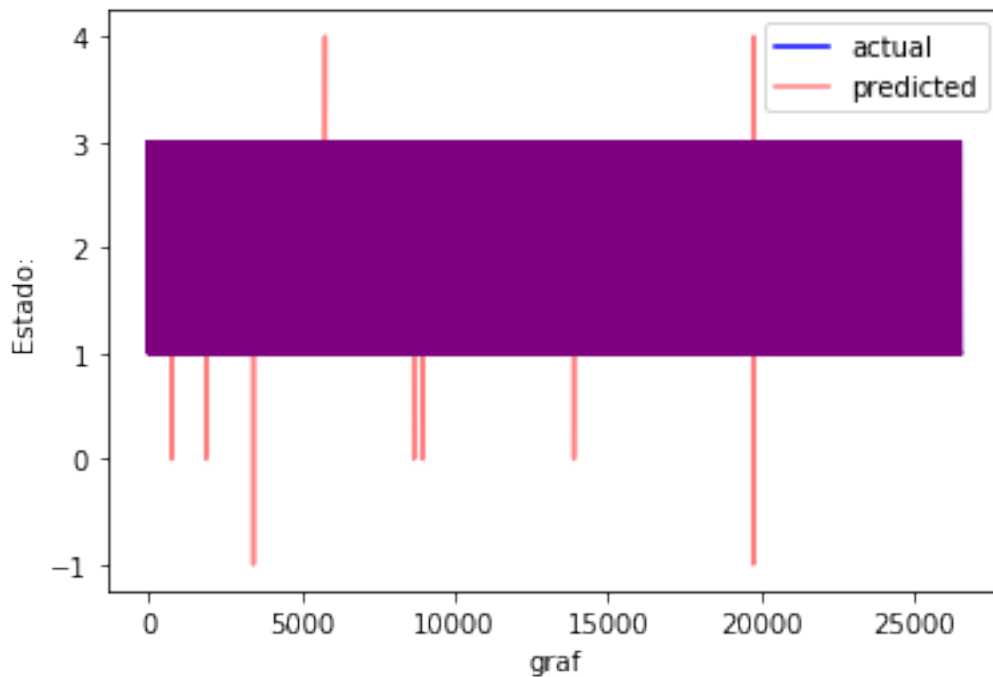
```
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[24]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.8910521232193426

```
[25]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```





```
[26]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[26]: 0.965538043888093
```

```
[:]
```

# Wrist\_elux5\_mae\_Adadel\_final

August 28, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```



```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```



```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100))
```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0828 18:41:15.603651 23756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0828 18:41:15.617621 23756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0828 18:41:15.621641 23756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0828 18:41:15.691451 23756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0828 18:41:15.885896 23756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0828 18:41:15.890924 23756 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is

deprecated. Please use `tf.compat.v1.assign` instead.

Train on 84868 samples, validate on 21218 samples

Epoch 1/100

84868/84868 [=====] - 15s 171us/step - loss: 0.3657 -  
val\_loss: 0.2790

Epoch 2/100

84868/84868 [=====] - 13s 154us/step - loss: 0.2181 -  
val\_loss: 0.1970

Epoch 3/100

84868/84868 [=====] - 13s 155us/step - loss: 0.1727 -  
val\_loss: 0.1643

Epoch 4/100

84868/84868 [=====] - 13s 155us/step - loss: 0.1439 -  
val\_loss: 0.1497

Epoch 5/100

84868/84868 [=====] - 13s 154us/step - loss: 0.1286 -  
val\_loss: 0.1286

Epoch 6/100

84868/84868 [=====] - 13s 155us/step - loss: 0.1194 -  
val\_loss: 0.1196

Epoch 7/100

84868/84868 [=====] - 13s 155us/step - loss: 0.1114 -  
val\_loss: 0.1178

Epoch 8/100

84868/84868 [=====] - 13s 155us/step - loss: 0.1059 -  
val\_loss: 0.1143

Epoch 9/100

84868/84868 [=====] - 13s 154us/step - loss: 0.1001 -  
val\_loss: 0.1088

Epoch 10/100

84868/84868 [=====] - 13s 155us/step - loss: 0.0959 -  
val\_loss: 0.0914

Epoch 11/100

84868/84868 [=====] - 13s 155us/step - loss: 0.0925 -  
val\_loss: 0.0882

Epoch 12/100

84868/84868 [=====] - 13s 154us/step - loss: 0.0897 -  
val\_loss: 0.0932

Epoch 13/100

84868/84868 [=====] - 13s 155us/step - loss: 0.0873 -  
val\_loss: 0.0862

Epoch 14/100

84868/84868 [=====] - 13s 155us/step - loss: 0.0852 -  
val\_loss: 0.0839

Epoch 15/100

84868/84868 [=====] - 13s 155us/step - loss: 0.0828 -

```
val_loss: 0.0839
Epoch 16/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0821 -
val_loss: 0.0860
Epoch 17/100
84868/84868 [=====] - 14s 167us/step - loss: 0.0798 -
val_loss: 0.0924
Epoch 18/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0783 -
val_loss: 0.0865
Epoch 19/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0768 -
val_loss: 0.0800
Epoch 20/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0760 -
val_loss: 0.0775
Epoch 21/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0743 -
val_loss: 0.0773
Epoch 22/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0731 -
val_loss: 0.0760
Epoch 23/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0714 -
val_loss: 0.0854
Epoch 24/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0704 -
val_loss: 0.0772
Epoch 25/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0690 -
val_loss: 0.0762
Epoch 26/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0686 -
val_loss: 0.0735
Epoch 27/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0678 -
val_loss: 0.0752
Epoch 28/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0667 -
val_loss: 0.0688
Epoch 29/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0658 -
val_loss: 0.0779
Epoch 30/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0650 -
val_loss: 0.0677
Epoch 31/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0646 -
```

```
val_loss: 0.0725
Epoch 32/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0639 -
val_loss: 0.0658
Epoch 33/100
84868/84868 [=====] - 13s 152us/step - loss: 0.0635 -
val_loss: 0.0760
Epoch 34/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0627 -
val_loss: 0.0721
Epoch 35/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0624 -
val_loss: 0.0688
Epoch 36/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0614 -
val_loss: 0.0606
Epoch 37/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0611 -
val_loss: 0.0850
Epoch 38/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0618 -
val_loss: 0.0620
Epoch 39/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0606 -
val_loss: 0.0825
Epoch 40/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0598 -
val_loss: 0.0715
Epoch 41/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0600 -
val_loss: 0.0701
Epoch 42/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0598 -
val_loss: 0.0581
Epoch 43/100
84868/84868 [=====] - 13s 158us/step - loss: 0.0588 -
val_loss: 0.0551
Epoch 44/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0584 -
val_loss: 0.0698
Epoch 45/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0590 -
val_loss: 0.0605
Epoch 46/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0584 -
val_loss: 0.0601
Epoch 47/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0578 -
```

```
val_loss: 0.0573
Epoch 48/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0575 -
val_loss: 0.0547
Epoch 49/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0568 -
val_loss: 0.0641
Epoch 50/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0561 -
val_loss: 0.0696
Epoch 51/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0560 -
val_loss: 0.0733
Epoch 52/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0563 -
val_loss: 0.0633
Epoch 53/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0560 -
val_loss: 0.0542
Epoch 54/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0553 -
val_loss: 0.0636
Epoch 55/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0562 -
val_loss: 0.0652
Epoch 56/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0558 -
val_loss: 0.0634
Epoch 57/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0547 -
val_loss: 0.0625
Epoch 58/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0548 -
val_loss: 0.0544
Epoch 59/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0552 -
val_loss: 0.0532
Epoch 60/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0550 -
val_loss: 0.0614
Epoch 61/100
84868/84868 [=====] - 13s 151us/step - loss: 0.0544 -
val_loss: 0.0514
Epoch 62/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0535 -
val_loss: 0.0516
Epoch 63/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0543 -
```

```
val_loss: 0.0664
Epoch 64/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0527 -
val_loss: 0.0695
Epoch 65/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0530 -
val_loss: 0.0668
Epoch 66/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0522 -
val_loss: 0.0583
Epoch 67/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0518 -
val_loss: 0.0621
Epoch 68/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0517 -
val_loss: 0.0658
Epoch 69/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0520 -
val_loss: 0.0508
Epoch 70/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0513 -
val_loss: 0.0638
Epoch 71/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0517 -
val_loss: 0.0570
Epoch 72/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0508 -
val_loss: 0.0639
Epoch 73/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0513 -
val_loss: 0.0600
Epoch 74/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0504 -
val_loss: 0.0532
Epoch 75/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0506 -
val_loss: 0.0498
Epoch 76/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0516 -
val_loss: 0.0564
Epoch 77/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0504 -
val_loss: 0.0607
Epoch 78/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0506 -
val_loss: 0.0506
Epoch 79/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0509 -
```



```
val_loss: 0.0577
Epoch 80/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0504 -
val_loss: 0.0545
Epoch 81/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0513 -
val_loss: 0.0556
Epoch 82/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0510 -
val_loss: 0.0516
Epoch 83/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0504 -
val_loss: 0.0513
Epoch 84/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0506 -
val_loss: 0.0602
Epoch 85/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0509 -
val_loss: 0.0646
Epoch 86/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0500 -
val_loss: 0.0453
Epoch 87/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0508 -
val_loss: 0.0506
Epoch 88/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0504 -
val_loss: 0.0555
Epoch 89/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0498 -
val_loss: 0.0502
Epoch 90/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0497 -
val_loss: 0.0637
Epoch 91/100
84868/84868 [=====] - 13s 157us/step - loss: 0.0498 -
val_loss: 0.0577
Epoch 92/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0502 -
val_loss: 0.0552
Epoch 93/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0491 -
val_loss: 0.0572
Epoch 94/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0500 -
val_loss: 0.0462
Epoch 95/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0497 -
```

```

val_loss: 0.0641
Epoch 96/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0494 -
val_loss: 0.0451
Epoch 97/100
84868/84868 [=====] - 13s 153us/step - loss: 0.0502 -
val_loss: 0.0499
Epoch 98/100
84868/84868 [=====] - 13s 154us/step - loss: 0.0490 -
val_loss: 0.0498
Epoch 99/100
84868/84868 [=====] - 13s 156us/step - loss: 0.0496 -
val_loss: 0.0556
Epoch 100/100
84868/84868 [=====] - 13s 155us/step - loss: 0.0488 -
val_loss: 0.0546

```

```
[21]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[22]: Y_test = np.round(Y_test, 0)
```

```
[23]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↳array2string(prediction))

```

```

Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.

```

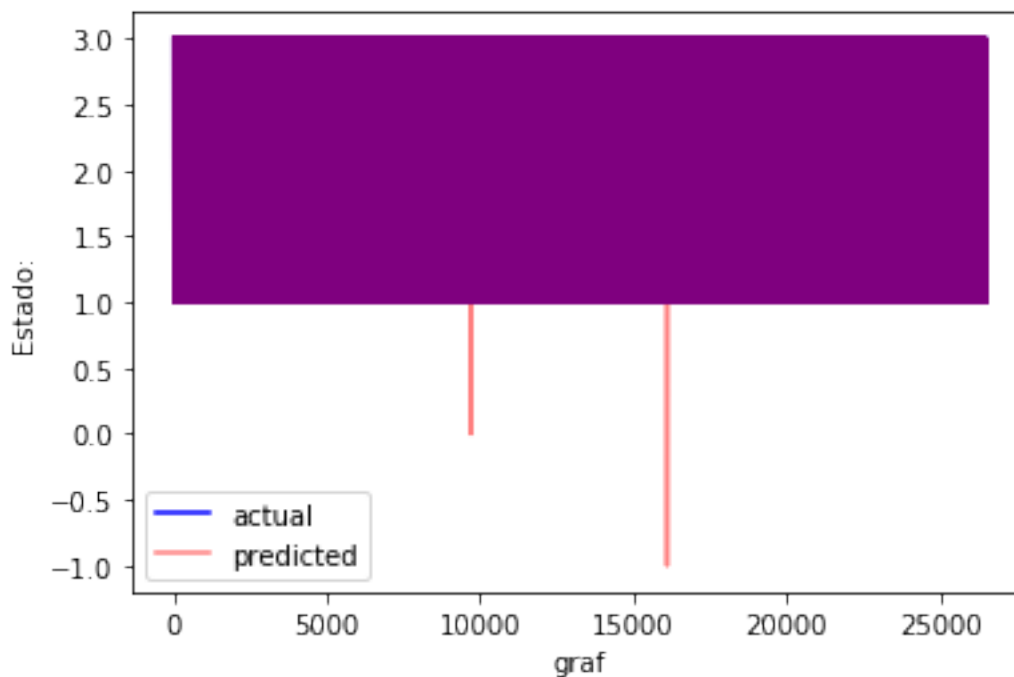
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.

Evaluamos los resultados:

```
[24]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.8935274261160827

```
[25]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[26]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[26]: 0.9730412487746022
```

```
[:]
```

# Wrist\_elux7\_mae\_Adadel\_final

August 28, 2019

## 1 Wrist Data

Librerías:

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
from sklearn.metrics import f1_score
```

Using TensorFlow backend.

### 1.1 Wrist

Cargamos los datos:

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>=4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pk1','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>=4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>=4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```



```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>=4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>=4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)

```

```
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>=4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)
```

```
[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>=4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)

```

```

[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>=4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>=4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>=4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```



```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>=4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

        C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>=4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>=4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>=4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]

```

```

for i in range(12):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>=4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

Unimos los datos:

```
[17]: MAT=np.
      ↪concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT15,MAT16,MAT17,MAT18,MAT19,MAT20,MAT21,MAT22,MAT23,MAT24,MAT25,MAT26,MAT27,MAT28,MAT29,MAT30,MAT31,MAT32,MAT33,MAT34,MAT35,MAT36,MAT37,MAT38,MAT39,MAT40,MAT41,MAT42,MAT43,MAT44,MAT45,MAT46,MAT47,MAT48,MAT49,MAT50,MAT51,MAT52,MAT53,MAT54,MAT55,MAT56,MAT57,MAT58,MAT59,MAT60,MAT61,MAT62,MAT63,MAT64,MAT65,MAT66,MAT67,MAT68,MAT69,MAT70,MAT71,MAT72,MAT73,MAT74,MAT75,MAT76,MAT77,MAT78,MAT79,MAT80,MAT81,MAT82,MAT83,MAT84,MAT85,MAT86,MAT87,MAT88,MAT89,MAT90,MAT91,MAT92,MAT93,MAT94,MAT95,MAT96,MAT97,MAT98,MAT99,MAT100,MAT101,MAT102,MAT103,MAT104,MAT105,MAT106,MAT107,MAT108,MAT109,MAT110,MAT111,MAT112,MAT113,MAT114,MAT115,MAT116,MAT117,MAT118,MAT119,MAT120,MAT121,MAT122,MAT123,MAT124,MAT125,MAT126,MAT127,MAT128,MAT129,MAT130,MAT131,MAT132,MAT133,MAT134,MAT135,MAT136,MAT137,MAT138,MAT139,MAT140,MAT141,MAT142,MAT143,MAT144,MAT145,MAT146,MAT147,MAT148,MAT149,MAT150,MAT151,MAT152,MAT153,MAT154,MAT155,MAT156,MAT157,MAT158,MAT159,MAT160,MAT161,MAT162,MAT163,MAT164,MAT165,MAT166,MAT167,MAT168,MAT169,MAT170,MAT171,MAT172,MAT173,MAT174,MAT175,MAT176,MAT177,MAT178,MAT179,MAT180,MAT181,MAT182,MAT183,MAT184,MAT185,MAT186,MAT187,MAT188,MAT189,MAT190,MAT191,MAT192,MAT193,MAT194,MAT195,MAT196,MAT197,MAT198,MAT199,MAT200,MAT201,MAT202,MAT203,MAT204,MAT205,MAT206,MAT207,MAT208,MAT209,MAT210,MAT211,MAT212,MAT213,MAT214,MAT215,MAT216,MAT217,MAT218,MAT219,MAT220,MAT221,MAT222,MAT223,MAT224,MAT225,MAT226,MAT227,MAT228,MAT229,MAT230,MAT231,MAT232,MAT233,MAT234,MAT235,MAT236,MAT237,MAT238,MAT239,MAT240,MAT241,MAT242,MAT243,MAT244,MAT245,MAT246,MAT247,MAT248,MAT249,MAT250,MAT251,MAT252,MAT253,MAT254,MAT255,MAT256,MAT257,MAT258,MAT259,MAT260,MAT261,MAT262,MAT263,MAT264,MAT265,MAT266,MAT267,MAT268,MAT269,MAT270,MAT271,MAT272,MAT273,MAT274,MAT275,MAT276,MAT277,MAT278,MAT279,MAT280,MAT281,MAT282,MAT283,MAT284,MAT285,MAT286,MAT287,MAT288,MAT289,MAT290,MAT291,MAT292,MAT293,MAT294,MAT295,MAT296,MAT297,MAT298,MAT299,MAT300,MAT301,MAT302,MAT303,MAT304,MAT305,MAT306,MAT307,MAT308,MAT309,MAT310,MAT311,MAT312,MAT313,MAT314,MAT315,MAT316,MAT317,MAT318,MAT319,MAT320,MAT321,MAT322,MAT323,MAT324,MAT325,MAT326,MAT327,MAT328,MAT329,MAT330,MAT331,MAT332,MAT333,MAT334,MAT335,MAT336,MAT337,MAT338,MAT339,MAT340,MAT341,MAT342,MAT343,MAT344,MAT345,MAT346,MAT347,MAT348,MAT349,MAT350,MAT351,MAT352,MAT353,MAT354,MAT355,MAT356,MAT357,MAT358,MAT359,MAT360,MAT361,MAT362,MAT363,MAT364,MAT365,MAT366,MAT367,MAT368,MAT369,MAT370,MAT371,MAT372,MAT373,MAT374,MAT375,MAT376,MAT377,MAT378,MAT379,MAT380,MAT381,MAT382,MAT383,MAT384,MAT385,MAT386,MAT387,MAT388,MAT389,MAT390,MAT391,MAT392,MAT393,MAT394,MAT395,MAT396,MAT397,MAT398,MAT399,MAT400,MAT401,MAT402,MAT403,MAT404,MAT405,MAT406,MAT407,MAT408,MAT409,MAT410,MAT411,MAT412,MAT413,MAT414,MAT415,MAT416,MAT417,MAT418,MAT419,MAT420,MAT421,MAT422,MAT423,MAT424,MAT425,MAT426,MAT427,MAT428,MAT429,MAT430,MAT431,MAT432,MAT433,MAT434,MAT435,MAT436,MAT437,MAT438,MAT439,MAT440,MAT441,MAT442,MAT443,MAT444,MAT445,MAT446,MAT447,MAT448,MAT449,MAT450,MAT451,MAT452,MAT453,MAT454,MAT455,MAT456,MAT457,MAT458,MAT459,MAT460,MAT461,MAT462,MAT463,MAT464,MAT465,MAT466,MAT467,MAT468,MAT469,MAT470,MAT471,MAT472,MAT473,MAT474,MAT475,MAT476,MAT477,MAT478,MAT479,MAT480,MAT481,MAT482,MAT483,MAT484,MAT485,MAT486,MAT487,MAT488,MAT489,MAT490,MAT491,MAT492,MAT493,MAT494,MAT495,MAT496,MAT497,MAT498,MAT499,MAT500,MAT501,MAT502,MAT503,MAT504,MAT505,MAT506,MAT507,MAT508,MAT509,MAT510,MAT511,MAT512,MAT513,MAT514,MAT515,MAT516,MAT517,MAT518,MAT519,MAT520,MAT521,MAT522,MAT523,MAT524,MAT525,MAT526,MAT527,MAT528,MAT529,MAT530,MAT531,MAT532,MAT533,MAT534,MAT535,MAT536,MAT537,MAT538,MAT539,MAT540,MAT541,MAT542,MAT543,MAT544,MAT545,MAT546,MAT547,MAT548,MAT549,MAT550,MAT551,MAT552,MAT553,MAT554,MAT555,MAT556,MAT557,MAT558,MAT559,MAT560,MAT561,MAT562,MAT563,MAT564,MAT565,MAT566,MAT567,MAT568,MAT569,MAT570,MAT571,MAT572,MAT573,MAT574,MAT575,MAT576,MAT577,MAT578,MAT579,MAT580,MAT581,MAT582,MAT583,MAT584,MAT585,MAT586,MAT587,MAT588,MAT589,MAT590,MAT591,MAT592,MAT593,MAT594,MAT595,MAT596,MAT597,MAT598,MAT599,MAT600,MAT601,MAT602,MAT603,MAT604,MAT605,MAT606,MAT607,MAT608,MAT609,MAT610,MAT611,MAT612,MAT613,MAT614,MAT615,MAT616,MAT617,MAT618,MAT619,MAT620,MAT621,MAT622,MAT623,MAT624,MAT625,MAT626,MAT627,MAT628,MAT629,MAT630,MAT631,MAT632,MAT633,MAT634,MAT635,MAT636,MAT637,MAT638,MAT639,MAT640,MAT641,MAT642,MAT643,MAT644,MAT645,MAT646,MAT647,MAT648,MAT649,MAT650,MAT651,MAT652,MAT653,MAT654,MAT655,MAT656,MAT657,MAT658,MAT659,MAT660,MAT661,MAT662,MAT663,MAT664,MAT665,MAT666,MAT667,MAT668,MAT669,MAT670,MAT671,MAT672,MAT673,MAT674,MAT675,MAT676,MAT677,MAT678,MAT679,MAT680,MAT681,MAT682,MAT683,MAT684,MAT685,MAT686,MAT687,MAT688,MAT689,MAT690,MAT691,MAT692,MAT693,MAT694,MAT695,MAT696,MAT697,MAT698,MAT699,MAT700,MAT701,MAT702,MAT703,MAT704,MAT705,MAT706,MAT707,MAT708,MAT709,MAT710,MAT711,MAT712,MAT713,MAT714,MAT715,MAT716,MAT717,MAT718,MAT719,MAT720,MAT721,MAT722,MAT723,MAT724,MAT725,MAT726,MAT727,MAT728,MAT729,MAT730,MAT731,MAT732,MAT733,MAT734,MAT735,MAT736,MAT737,MAT738,MAT739,MAT740,MAT741,MAT742,MAT743,MAT744,MAT745,MAT746,MAT747,MAT748,MAT749,MAT750,MAT751,MAT752,MAT753,MAT754,MAT755,MAT756,MAT757,MAT758,MAT759,MAT760,MAT761,MAT762,MAT763,MAT764,MAT765,MAT766,MAT767,MAT768,MAT769,MAT770,MAT771,MAT772,MAT773,MAT774,MAT775,MAT776,MAT777,MAT778,MAT779,MAT780,MAT781,MAT782,MAT783,MAT784,MAT785,MAT786,MAT787,MAT788,MAT789,MAT790,MAT791,MAT792,MAT793,MAT794,MAT795,MAT796,MAT797,MAT798,MAT799,MAT800,MAT801,MAT802,MAT803,MAT804,MAT805,MAT806,MAT807,MAT808,MAT809,MAT810,MAT811,MAT812,MAT813,MAT814,MAT815,MAT816,MAT817,MAT818,MAT819,MAT820,MAT821,MAT822,MAT823,MAT824,MAT825,MAT826,MAT827,MAT828,MAT829,MAT830,MAT831,MAT832,MAT833,MAT834,MAT835,MAT836,MAT837,MAT838,MAT839,MAT840,MAT841,MAT842,MAT843,MAT844,MAT845,MAT846,MAT847,MAT848,MAT849,MAT850,MAT851,MAT852,MAT853,MAT854,MAT855,MAT856,MAT857,MAT858,MAT859,MAT860,MAT861,MAT862,MAT863,MAT864,MAT865,MAT866,MAT867,MAT868,MAT869,MAT870,MAT871,MAT872,MAT873,MAT874,MAT875,MAT876,MAT877,MAT878,MAT879,MAT880,MAT881,MAT882,MAT883,MAT884,MAT885,MAT886,MAT887,MAT888,MAT889,MAT890,MAT891,MAT892,MAT893,MAT894,MAT895,MAT896,MAT897,MAT898,MAT899,MAT900,MAT901,MAT902,MAT903,MAT904,MAT905,MAT906,MAT907,MAT908,MAT909,MAT910,MAT911,MAT912,MAT913,MAT914,MAT915,MAT916,MAT917,MAT918,MAT919,MAT920,MAT921,MAT922,MAT923,MAT924,MAT925,MAT926,MAT927,MAT928,MAT929,MAT930,MAT931,MAT932,MAT933,MAT934,MAT935,MAT936,MAT937,MAT938,MAT939,MAT940,MAT941,MAT942,MAT943,MAT944,MAT945,MAT946,MAT947,MAT948,MAT949,MAT950,MAT951,MAT952,MAT953,MAT954,MAT955,MAT956,MAT957,MAT958,MAT959,MAT960,MAT961,MAT962,MAT963,MAT964,MAT965,MAT966,MAT967,MAT968,MAT969,MAT970,MAT971,MAT972,MAT973,MAT974,MAT975,MAT976,MAT977,MAT978,MAT979,MAT980,MAT981,MAT982,MAT983,MAT984,MAT985,MAT986,MAT987,MAT988,MAT989,MAT990,MAT991,MAT992,MAT993,MAT994,MAT995,MAT996,MAT997,MAT998,MAT999,MAT1000)

```

Dividimos en los conjuntos de validación y entrenamiento:

```
[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      ↪test_size=validation_size, random_state=seed)

```

Definimos la arquitectura de la red:

```
[19]: model = Sequential([
      Dense(128, input_shape=(7,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),

```

```

Dense(60),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(40),
Activation('elu'),
Dense(30),
Activation('elu'),
Dense(1),
Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

WARNING: Logging before flag parsing goes to stderr.  
W0828 19:17:10.691833 3912 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0828 19:17:10.709784 3912 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0828 19:17:10.712776 3912 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0828 19:17:10.799576 3912 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

Entrenamos la red:

```

[20]: NUM_EPOCHS =100
      BATCH_SIZE = 20

      history = model.fit(X_train, Y_train, batch_size=BATCH_SIZE, epochs=NUM_EPOCHS,
      ↪validation_split=0.2)

```

W0828 19:17:11.028969 3912 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0828 19:17:11.033917 3912 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 84868 samples, validate on 21218 samples

Epoch 1/100

84868/84868 [=====] - 17s 202us/step - loss: 0.3514 -  
val\_loss: 0.2646

Epoch 2/100

84868/84868 [=====] - 16s 188us/step - loss: 0.1969 -  
val\_loss: 0.1673

Epoch 3/100

84868/84868 [=====] - 16s 188us/step - loss: 0.1511 -  
val\_loss: 0.1494

Epoch 4/100

84868/84868 [=====] - 16s 187us/step - loss: 0.1276 -  
val\_loss: 0.1175

Epoch 5/100

84868/84868 [=====] - 16s 188us/step - loss: 0.1134 -  
val\_loss: 0.1056

Epoch 6/100

84868/84868 [=====] - 16s 188us/step - loss: 0.1030 -  
val\_loss: 0.0972

Epoch 7/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0959 -  
val\_loss: 0.0963

Epoch 8/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0917 -  
val\_loss: 0.0900

Epoch 9/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0896 -  
val\_loss: 0.0792

Epoch 10/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0875 -  
val\_loss: 0.0826

Epoch 11/100

84868/84868 [=====] - 16s 189us/step - loss: 0.0860 -  
val\_loss: 0.0895

Epoch 12/100

84868/84868 [=====] - 16s 188us/step - loss: 0.0839 -  
val\_loss: 0.1022

Epoch 13/100

84868/84868 [=====] - 16s 189us/step - loss: 0.0799 -  
val\_loss: 0.0764

Epoch 14/100

84868/84868 [=====] - 16s 189us/step - loss: 0.0799 -  
val\_loss: 0.0705  
Epoch 15/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0784 -  
val\_loss: 0.0696  
Epoch 16/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0754 -  
val\_loss: 0.0814  
Epoch 17/100  
84868/84868 [=====] - 16s 186us/step - loss: 0.0743 -  
val\_loss: 0.0927  
Epoch 18/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0726 -  
val\_loss: 0.0675  
Epoch 19/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0714 -  
val\_loss: 0.0684  
Epoch 20/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0704 -  
val\_loss: 0.0641  
Epoch 21/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0689 -  
val\_loss: 0.0605  
Epoch 22/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0675 -  
val\_loss: 0.0719  
Epoch 23/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0639 -  
val\_loss: 0.0773  
Epoch 24/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0652 -  
val\_loss: 0.0973  
Epoch 25/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0657 -  
val\_loss: 0.0676  
Epoch 26/100  
84868/84868 [=====] - 16s 189us/step - loss: 0.0624 -  
val\_loss: 0.0691  
Epoch 27/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0589 -  
val\_loss: 0.0702  
Epoch 28/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0580 -  
val\_loss: 0.0647  
Epoch 29/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0577 -  
val\_loss: 0.0701  
Epoch 30/100



84868/84868 [=====] - 16s 188us/step - loss: 0.0572 -  
val\_loss: 0.0565  
Epoch 31/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0562 -  
val\_loss: 0.0594  
Epoch 32/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0563 -  
val\_loss: 0.0503  
Epoch 33/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0546 -  
val\_loss: 0.0581  
Epoch 34/100  
84868/84868 [=====] - 16s 188us/step - loss: 0.0542 -  
val\_loss: 0.0632  
Epoch 35/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0545 -  
val\_loss: 0.0648  
Epoch 36/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0550 -  
val\_loss: 0.0591  
Epoch 37/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0543 -  
val\_loss: 0.0585  
Epoch 38/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0518 -  
val\_loss: 0.0594  
Epoch 39/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0513 -  
val\_loss: 0.0531  
Epoch 40/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0529 -  
val\_loss: 0.0517  
Epoch 41/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0519 -  
val\_loss: 0.0525  
Epoch 42/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0502 -  
val\_loss: 0.0557  
Epoch 43/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0506 -  
val\_loss: 0.0543  
Epoch 44/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0500 -  
val\_loss: 0.0473  
Epoch 45/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0498 -  
val\_loss: 0.0440  
Epoch 46/100

84868/84868 [=====] - 16s 190us/step - loss: 0.0501 -  
val\_loss: 0.0541  
Epoch 47/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0493 -  
val\_loss: 0.0513  
Epoch 48/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0490 -  
val\_loss: 0.0527  
Epoch 49/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0492 -  
val\_loss: 0.0500  
Epoch 50/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0492 -  
val\_loss: 0.0569  
Epoch 51/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0488 -  
val\_loss: 0.0600  
Epoch 52/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0497 -  
val\_loss: 0.0756  
Epoch 53/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0477 -  
val\_loss: 0.0521  
Epoch 54/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0481 -  
val\_loss: 0.0457  
Epoch 55/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0484 -  
val\_loss: 0.0615  
Epoch 56/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0480 -  
val\_loss: 0.0545  
Epoch 57/100  
84868/84868 [=====] - 17s 195us/step - loss: 0.0489 -  
val\_loss: 0.0488  
Epoch 58/100  
84868/84868 [=====] - 17s 202us/step - loss: 0.0486 -  
val\_loss: 0.0475  
Epoch 59/100  
84868/84868 [=====] - 17s 199us/step - loss: 0.0476 -  
val\_loss: 0.0443  
Epoch 60/100  
84868/84868 [=====] - 17s 200us/step - loss: 0.0475 -  
val\_loss: 0.0503  
Epoch 61/100  
84868/84868 [=====] - 17s 196us/step - loss: 0.0457 -  
val\_loss: 0.0479  
Epoch 62/100

84868/84868 [=====] - 16s 187us/step - loss: 0.0464 -  
val\_loss: 0.0490  
Epoch 63/100  
84868/84868 [=====] - 16s 187us/step - loss: 0.0462 -  
val\_loss: 0.0535  
Epoch 64/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0459 -  
val\_loss: 0.0511  
Epoch 65/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0452 -  
val\_loss: 0.0795  
Epoch 66/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0465 -  
val\_loss: 0.0547  
Epoch 67/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0468 -  
val\_loss: 0.0476  
Epoch 68/100  
84868/84868 [=====] - 16s 194us/step - loss: 0.0470 -  
val\_loss: 0.0523  
Epoch 69/100  
84868/84868 [=====] - 17s 196us/step - loss: 0.0459 -  
val\_loss: 0.0473  
Epoch 70/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0456 -  
val\_loss: 0.0479  
Epoch 71/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0456 -  
val\_loss: 0.0440  
Epoch 72/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0457 -  
val\_loss: 0.0505  
Epoch 73/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0464 -  
val\_loss: 0.0516  
Epoch 74/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0466 -  
val\_loss: 0.0475  
Epoch 75/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0451 -  
val\_loss: 0.0494  
Epoch 76/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0465 -  
val\_loss: 0.0486  
Epoch 77/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0459 -  
val\_loss: 0.0523  
Epoch 78/100

84868/84868 [=====] - 16s 192us/step - loss: 0.0450 -  
val\_loss: 0.0487  
Epoch 79/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0446 -  
val\_loss: 0.0466  
Epoch 80/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0436 -  
val\_loss: 0.0527  
Epoch 81/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0446 -  
val\_loss: 0.0504  
Epoch 82/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0442 -  
val\_loss: 0.0445  
Epoch 83/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0449 -  
val\_loss: 0.0580  
Epoch 84/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0438 -  
val\_loss: 0.0434  
Epoch 85/100  
84868/84868 [=====] - 16s 191us/step - loss: 0.0443 -  
val\_loss: 0.0633  
Epoch 86/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0455 -  
val\_loss: 0.0488  
Epoch 87/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0434 -  
val\_loss: 0.0540  
Epoch 88/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0421 -  
val\_loss: 0.0458  
Epoch 89/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0438 -  
val\_loss: 0.0366  
Epoch 90/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0433 -  
val\_loss: 0.0522  
Epoch 91/100  
84868/84868 [=====] - 16s 190us/step - loss: 0.0427 -  
val\_loss: 0.0536  
Epoch 92/100  
84868/84868 [=====] - 16s 192us/step - loss: 0.0427 -  
val\_loss: 0.0529  
Epoch 93/100  
84868/84868 [=====] - 16s 193us/step - loss: 0.0445 -  
val\_loss: 0.0529  
Epoch 94/100

```

84868/84868 [=====] - 16s 193us/step - loss: 0.0441 -
val_loss: 0.0501
Epoch 95/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0430 -
val_loss: 0.0436
Epoch 96/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0432 -
val_loss: 0.0464
Epoch 97/100
84868/84868 [=====] - 17s 195us/step - loss: 0.0429 -
val_loss: 0.0498
Epoch 98/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0436 -
val_loss: 0.0437
Epoch 99/100
84868/84868 [=====] - 16s 192us/step - loss: 0.0424 -
val_loss: 0.0457
Epoch 100/100
84868/84868 [=====] - 16s 193us/step - loss: 0.0435 -
val_loss: 0.0582

```

```
[21]: Y_test = model.predict(X_val).flatten()
```

Redondeamos los resultados puesto que deben de ser enteros:

```
[22]: Y_test = np.round(Y_test, 0)
```

```
[23]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        prediction = Y_test[i]
        print("Estado: " + np.array2string(label) + ", predicted:" + np.
        ↳array2string(prediction))

```

```

Estado: 3., predicted:3.
Estado: 1., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 1., predicted:1.

```

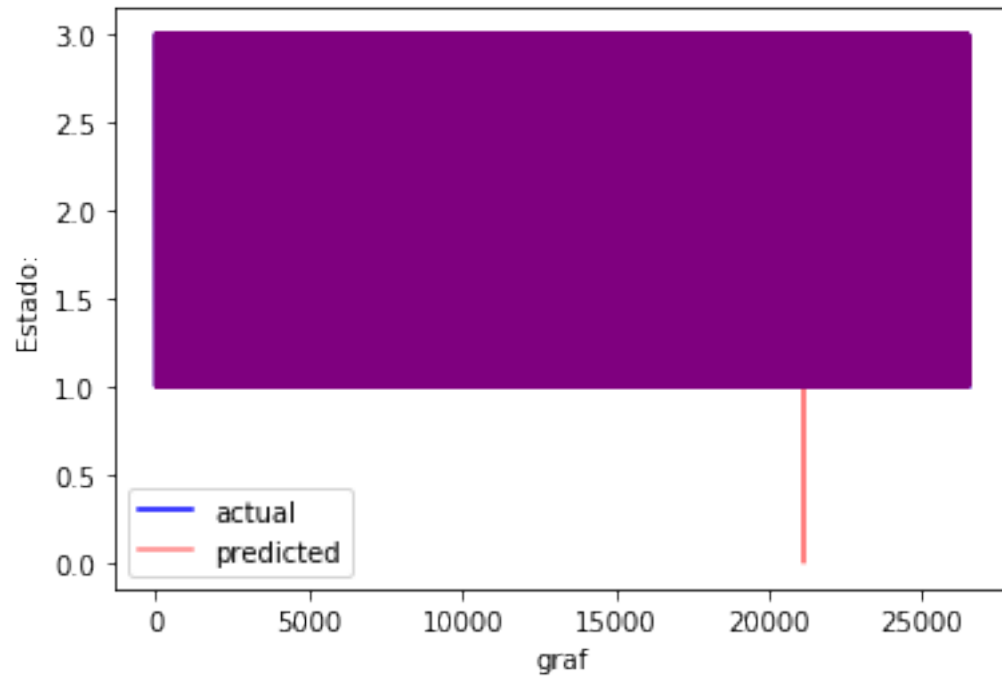
```
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

Evaluamos los resultados:

```
[24]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_test, Y_val)  
print (r2)
```

0.9113167266916418

```
[25]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_test),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[26]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==Y_test
      accur=np.sum(Accu)
      accur/len(Y_val)
```

```
[26]: 0.9678003167181962
```

```
[:]
```

# TFM\_wrist\_data\_ENSEMBLE-final

August 23, 2019

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
```

Using TensorFlow backend.

## 0.1 Ensemble

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
```



```

l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):

```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```

```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)

```

```

[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A2l=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A2l))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A2l)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A2l)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A2l[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)

```

```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```



```

B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```

```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

```

[17]: MAT=np.
      →concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT

```

```

[18]: X = MAT[:, 1:8]
      Y = MAT[:, 0]
      validation_size = 0.2
      seed = 7
      X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
      →test_size=validation_size, random_state=seed)

```

```

[19]: X_trainA= np.delete(X_train,3 , 1)
      X_trainB= np.delete(X_train,4 , 1)
      X_valA= np.delete(X_val,3, 1)
      X_valB= np.delete(X_val,4 , 1)

```

```

[24]: model = Sequential([
      Dense(128, input_shape=(6,)),
      Activation('elu'),
      Dense(70),
      Activation('elu'),
      Dense(48),
      Activation('elu'),

```



```

    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')

```

```

[25]: NUM_EPOCHS =100
      BATCH_SIZE = 15

      history = model.fit(X_trainA, Y_train, batch_size=BATCH_SIZE,
      ↪epochs=NUM_EPOCHS, validation_split=0.2)

```

Train on 115092 samples, validate on 28773 samples

```

Epoch 1/100
115092/115092 [=====] - 25s 220us/step - loss: 0.5107 -
val_loss: 0.4044
Epoch 2/100
115092/115092 [=====] - 25s 214us/step - loss: 0.2917 -
val_loss: 0.2468
Epoch 3/100
115092/115092 [=====] - 24s 210us/step - loss: 0.2212 -
val_loss: 0.2127
Epoch 4/100
115092/115092 [=====] - 24s 210us/step - loss: 0.1850 -
val_loss: 0.1663
Epoch 5/100
115092/115092 [=====] - 24s 212us/step - loss: 0.1632 -
val_loss: 0.1613
Epoch 6/100
115092/115092 [=====] - 24s 212us/step - loss: 0.1479 -
val_loss: 0.1500
Epoch 7/100
115092/115092 [=====] - 24s 211us/step - loss: 0.1359 -
val_loss: 0.1363
Epoch 8/100
115092/115092 [=====] - 24s 211us/step - loss: 0.1273 -
val_loss: 0.1370
Epoch 9/100
115092/115092 [=====] - 24s 210us/step - loss: 0.1204 -
val_loss: 0.1197
Epoch 10/100
115092/115092 [=====] - 24s 211us/step - loss: 0.1142 -
val_loss: 0.1229
Epoch 11/100
115092/115092 [=====] - 24s 211us/step - loss: 0.1101 -
val_loss: 0.1110

```

Epoch 12/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.1065 -  
val\_loss: 0.1056  
Epoch 13/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.1033 -  
val\_loss: 0.1306  
Epoch 14/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0999 -  
val\_loss: 0.1107  
Epoch 15/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0965 -  
val\_loss: 0.0925  
Epoch 16/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0950 -  
val\_loss: 0.1023  
Epoch 17/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0928 -  
val\_loss: 0.0929  
Epoch 18/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0911 -  
val\_loss: 0.0914  
Epoch 19/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0894 -  
val\_loss: 0.1122  
Epoch 20/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0884 -  
val\_loss: 0.0868  
Epoch 21/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0869 -  
val\_loss: 0.0875  
Epoch 22/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0847 -  
val\_loss: 0.0852  
Epoch 23/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0832 -  
val\_loss: 0.0786  
Epoch 24/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0830 -  
val\_loss: 0.0895  
Epoch 25/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0817 -  
val\_loss: 0.0824  
Epoch 26/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0798 -  
val\_loss: 0.0709  
Epoch 27/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0792 -  
val\_loss: 0.0848

Epoch 28/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0781 -  
val\_loss: 0.0832  
Epoch 29/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0771 -  
val\_loss: 0.0791  
Epoch 30/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0760 -  
val\_loss: 0.0745  
Epoch 31/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0748 -  
val\_loss: 0.0842  
Epoch 32/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0737 -  
val\_loss: 0.0707  
Epoch 33/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0733 -  
val\_loss: 0.0689  
Epoch 34/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0726 -  
val\_loss: 0.0901  
Epoch 35/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0722 -  
val\_loss: 0.0745  
Epoch 36/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0705 -  
val\_loss: 0.0700  
Epoch 37/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0703 -  
val\_loss: 0.0631  
Epoch 38/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0700 -  
val\_loss: 0.0605  
Epoch 39/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0697 -  
val\_loss: 0.0840  
Epoch 40/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0695 -  
val\_loss: 0.0674  
Epoch 41/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0695 -  
val\_loss: 0.0679  
Epoch 42/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0686 -  
val\_loss: 0.0627  
Epoch 43/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0676 -  
val\_loss: 0.0644

Epoch 44/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0667 -  
val\_loss: 0.0839  
Epoch 45/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0665 -  
val\_loss: 0.0685  
Epoch 46/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0650 -  
val\_loss: 0.0744  
Epoch 47/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0644 -  
val\_loss: 0.0612  
Epoch 48/100  
115092/115092 [=====] - 25s 217us/step - loss: 0.0645 -  
val\_loss: 0.0954  
Epoch 49/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0643 -  
val\_loss: 0.0644  
Epoch 50/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0647 -  
val\_loss: 0.0511  
Epoch 51/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0640 -  
val\_loss: 0.0740  
Epoch 52/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0635 -  
val\_loss: 0.0709  
Epoch 53/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0628 -  
val\_loss: 0.0652  
Epoch 54/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0624 -  
val\_loss: 0.0603  
Epoch 55/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0621 -  
val\_loss: 0.0614  
Epoch 56/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0618 -  
val\_loss: 0.0635  
Epoch 57/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0620 -  
val\_loss: 0.0631  
Epoch 58/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0621 -  
val\_loss: 0.0620  
Epoch 59/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0619 -  
val\_loss: 0.0770

Epoch 60/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0624 -  
val\_loss: 0.0670  
Epoch 61/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0614 -  
val\_loss: 0.1005  
Epoch 62/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0629 -  
val\_loss: 0.0597  
Epoch 63/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0626 -  
val\_loss: 0.0655  
Epoch 64/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0637 -  
val\_loss: 0.0592  
Epoch 65/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0625 -  
val\_loss: 0.0639  
Epoch 66/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0627 -  
val\_loss: 0.0570  
Epoch 67/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0636 -  
val\_loss: 0.0631  
Epoch 68/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0628 -  
val\_loss: 0.0654  
Epoch 69/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0645 -  
val\_loss: 0.0598  
Epoch 70/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0651 -  
val\_loss: 0.0674  
Epoch 71/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0654 -  
val\_loss: 0.0630  
Epoch 72/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0653 -  
val\_loss: 0.0617  
Epoch 73/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0652 -  
val\_loss: 0.0560  
Epoch 74/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0654 -  
val\_loss: 0.0580  
Epoch 75/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0658 -  
val\_loss: 0.1430

Epoch 76/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0655 -  
val\_loss: 0.0602  
Epoch 77/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0664 -  
val\_loss: 0.0771  
Epoch 78/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0679 -  
val\_loss: 0.0799  
Epoch 79/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0694 -  
val\_loss: 0.0640  
Epoch 80/100  
115092/115092 [=====] - 24s 212us/step - loss: 0.0671 -  
val\_loss: 0.0661  
Epoch 81/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0674 -  
val\_loss: 0.0845  
Epoch 82/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0666 -  
val\_loss: 0.0653  
Epoch 83/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0676 -  
val\_loss: 0.0821  
Epoch 84/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0673 -  
val\_loss: 0.0690  
Epoch 85/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0684 -  
val\_loss: 0.0666  
Epoch 86/100  
115092/115092 [=====] - 24s 210us/step - loss: 0.0677 -  
val\_loss: 0.0785  
Epoch 87/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0675 -  
val\_loss: 0.0698  
Epoch 88/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0673 -  
val\_loss: 0.0775  
Epoch 89/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0685 -  
val\_loss: 0.0626  
Epoch 90/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0687 -  
val\_loss: 0.0646  
Epoch 91/100  
115092/115092 [=====] - 24s 211us/step - loss: 0.0692 -  
val\_loss: 0.0596

```

Epoch 92/100
115092/115092 [=====] - 24s 212us/step - loss: 0.0686 -
val_loss: 0.0674
Epoch 93/100
115092/115092 [=====] - 24s 211us/step - loss: 0.0670 -
val_loss: 0.0672
Epoch 94/100
115092/115092 [=====] - 25s 213us/step - loss: 0.0662 -
val_loss: 0.0620
Epoch 95/100
115092/115092 [=====] - 24s 211us/step - loss: 0.0665 -
val_loss: 0.0627
Epoch 96/100
115092/115092 [=====] - 24s 212us/step - loss: 0.0649 -
val_loss: 0.1057
Epoch 97/100
115092/115092 [=====] - 24s 211us/step - loss: 0.0669 -
val_loss: 0.0692
Epoch 98/100
115092/115092 [=====] - 24s 211us/step - loss: 0.0669 -
val_loss: 0.0746
Epoch 99/100
115092/115092 [=====] - 24s 210us/step - loss: 0.0658 -
val_loss: 0.0740
Epoch 100/100
115092/115092 [=====] - 24s 212us/step - loss: 0.0650 -
val_loss: 0.0608

```

```
[26]: Y_testA = model.predict(X_valA).flatten()
```

```
[27]: Y_testA = np.round(Y_testA, 0)
```

```
[28]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        predictionA = Y_testA[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        →array2string(predictionA))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:3.

```

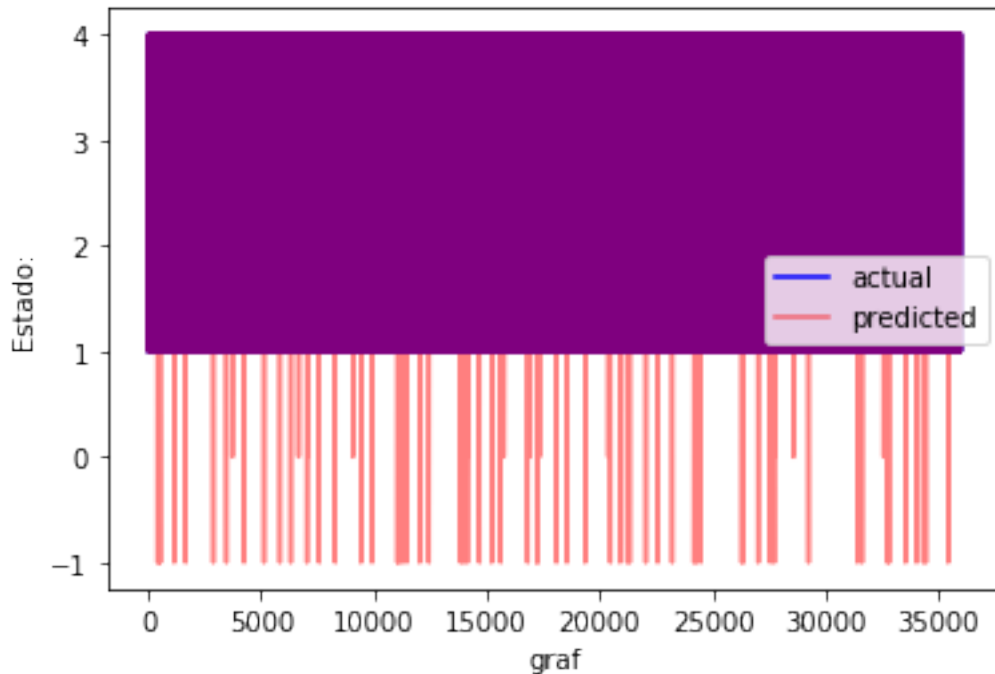
```
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:2.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

```
[29]: from sklearn.metrics import r2_score  
      r2 = r2_score(Y_testA, Y_val)  
      print (r2)
```

0.9455439396680531

```
[30]: plt.plot((Y_val),  
              color="b", label="actual")  
      plt.plot((Y_testA),  
              color="r", alpha=0.5, label="predicted")  
      plt.xlabel("graf")  
      plt.ylabel("Estado:")  
      plt.legend(loc="best")  
      plt.show()
```





```
[31]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_testA
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[31]: 0.9715572608224206
```

```
[32]: model = Sequential([
    Dense(128, input_shape=(6,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(48),
    Activation('elu'),
    Dense(24),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta', loss='mae')
```

```
[33]: NUM_EPOCHS =100
BATCH_SIZE = 20

history = model.fit(X_trainB, Y_train, batch_size=BATCH_SIZE,
    ↪epochs=NUM_EPOCHS, validation_split=0.2)
```

Train on 115092 samples, validate on 28773 samples

Epoch 1/100

115092/115092 [=====] - 19s 162us/step - loss: 0.6112 -  
val\_loss: 0.4906

Epoch 2/100

115092/115092 [=====] - 18s 159us/step - loss: 0.3958 -  
val\_loss: 0.3515

Epoch 3/100

115092/115092 [=====] - 18s 159us/step - loss: 0.3198 -  
val\_loss: 0.2893

Epoch 4/100

115092/115092 [=====] - 18s 159us/step - loss: 0.2816 -  
val\_loss: 0.2707

Epoch 5/100

115092/115092 [=====] - 18s 159us/step - loss: 0.2546 -  
val\_loss: 0.2396

Epoch 6/100

115092/115092 [=====] - 18s 159us/step - loss: 0.2246 -  
val\_loss: 0.2046

Epoch 7/100

115092/115092 [=====] - 18s 159us/step - loss: 0.2022 -  
val\_loss: 0.2077

Epoch 8/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1886 -  
val\_loss: 0.2034

Epoch 9/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1794 -  
val\_loss: 0.1701

Epoch 10/100

115092/115092 [=====] - 18s 158us/step - loss: 0.1715 -  
val\_loss: 0.1950

Epoch 11/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1636 -  
val\_loss: 0.1571

Epoch 12/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1586 -  
val\_loss: 0.1504

Epoch 13/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1547 -  
val\_loss: 0.1522

Epoch 14/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1501 -  
val\_loss: 0.1574

Epoch 15/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1474 -  
val\_loss: 0.1407

Epoch 16/100

115092/115092 [=====] - 18s 159us/step - loss: 0.1443 -

```
val_loss: 0.1471
Epoch 17/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1422 -
val_loss: 0.1458
Epoch 18/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1404 -
val_loss: 0.1503
Epoch 19/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1389 -
val_loss: 0.1495
Epoch 20/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1370 -
val_loss: 0.1496
Epoch 21/100
115092/115092 [=====] - 18s 158us/step - loss: 0.1358 -
val_loss: 0.1370
Epoch 22/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1348 -
val_loss: 0.1290
Epoch 23/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1339 -
val_loss: 0.1368
Epoch 24/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1324 -
val_loss: 0.1331
Epoch 25/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1315 -
val_loss: 0.1372
Epoch 26/100
115092/115092 [=====] - 19s 161us/step - loss: 0.1313 -
val_loss: 0.1279
Epoch 27/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1305 -
val_loss: 0.1325
Epoch 28/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1290 -
val_loss: 0.1294
Epoch 29/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1287 -
val_loss: 0.1622
Epoch 30/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1269 -
val_loss: 0.1525
Epoch 31/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1262 -
val_loss: 0.1315
Epoch 32/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1260 -
```

```
val_loss: 0.1321
Epoch 33/100
115092/115092 [=====] - 18s 160us/step - loss: 0.1245 -
val_loss: 0.1277
Epoch 34/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1245 -
val_loss: 0.1249
Epoch 35/100
115092/115092 [=====] - 18s 160us/step - loss: 0.1234 -
val_loss: 0.1254
Epoch 36/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1221 -
val_loss: 0.1168
Epoch 37/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1207 -
val_loss: 0.1330
Epoch 38/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1208 -
val_loss: 0.1148
Epoch 39/100
115092/115092 [=====] - 18s 160us/step - loss: 0.1204 -
val_loss: 0.1181
Epoch 40/100
115092/115092 [=====] - 18s 160us/step - loss: 0.1202 -
val_loss: 0.1238
Epoch 41/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1193 -
val_loss: 0.1340
Epoch 42/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1186 -
val_loss: 0.1160
Epoch 43/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1183 -
val_loss: 0.1274
Epoch 44/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1177 -
val_loss: 0.1163
Epoch 45/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1178 -
val_loss: 0.1248
Epoch 46/100
115092/115092 [=====] - 18s 160us/step - loss: 0.1171 -
val_loss: 0.1183
Epoch 47/100
115092/115092 [=====] - 18s 159us/step - loss: 0.1163 -
val_loss: 0.1113
Epoch 48/100
115092/115092 [=====] - 18s 160us/step - loss: 0.1163 -
```

val\_loss: 0.1228  
Epoch 49/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1165 -  
val\_loss: 0.1167  
Epoch 50/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1153 -  
val\_loss: 0.1135  
Epoch 51/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1160 -  
val\_loss: 0.1195  
Epoch 52/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1155 -  
val\_loss: 0.1205  
Epoch 53/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1145 -  
val\_loss: 0.1411  
Epoch 54/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1136 -  
val\_loss: 0.1123  
Epoch 55/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1137 -  
val\_loss: 0.1254  
Epoch 56/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1146 -  
val\_loss: 0.1128  
Epoch 57/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1130 -  
val\_loss: 0.1189  
Epoch 58/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1129 -  
val\_loss: 0.1286  
Epoch 59/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1130 -  
val\_loss: 0.1164  
Epoch 60/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1128 -  
val\_loss: 0.1244  
Epoch 61/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1123 -  
val\_loss: 0.1102  
Epoch 62/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1120 -  
val\_loss: 0.1175  
Epoch 63/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1117 -  
val\_loss: 0.1084  
Epoch 64/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1103 -

val\_loss: 0.1182  
Epoch 65/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1105 -  
val\_loss: 0.1169  
Epoch 66/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1093 -  
val\_loss: 0.1100  
Epoch 67/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1087 -  
val\_loss: 0.1110  
Epoch 68/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1087 -  
val\_loss: 0.1075  
Epoch 69/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1081 -  
val\_loss: 0.1050  
Epoch 70/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1074 -  
val\_loss: 0.1151  
Epoch 71/100  
115092/115092 [=====] - 18s 160us/step - loss: 0.1078 -  
val\_loss: 0.1182  
Epoch 72/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1068 -  
val\_loss: 0.1131  
Epoch 73/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1063 -  
val\_loss: 0.1046  
Epoch 74/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1056 -  
val\_loss: 0.1116  
Epoch 75/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1053 -  
val\_loss: 0.1073  
Epoch 76/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1056 -  
val\_loss: 0.1120  
Epoch 77/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1056 -  
val\_loss: 0.1048  
Epoch 78/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1051 -  
val\_loss: 0.0977  
Epoch 79/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1042 -  
val\_loss: 0.1168  
Epoch 80/100  
115092/115092 [=====] - 19s 169us/step - loss: 0.1048 -

val\_loss: 0.1058  
Epoch 81/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.1037 -  
val\_loss: 0.0987  
Epoch 82/100  
115092/115092 [=====] - 19s 162us/step - loss: 0.1044 -  
val\_loss: 0.0978  
Epoch 83/100  
115092/115092 [=====] - 19s 163us/step - loss: 0.1032 -  
val\_loss: 0.1057  
Epoch 84/100  
115092/115092 [=====] - 19s 161us/step - loss: 0.1028 -  
val\_loss: 0.1032  
Epoch 85/100  
115092/115092 [=====] - 19s 161us/step - loss: 0.1025 -  
val\_loss: 0.1204  
Epoch 86/100  
115092/115092 [=====] - 19s 164us/step - loss: 0.1019 -  
val\_loss: 0.0985  
Epoch 87/100  
115092/115092 [=====] - 18s 160us/step - loss: 0.1010 -  
val\_loss: 0.1022  
Epoch 88/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1007 -  
val\_loss: 0.0965  
Epoch 89/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1012 -  
val\_loss: 0.0964  
Epoch 90/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1008 -  
val\_loss: 0.1176  
Epoch 91/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.1002 -  
val\_loss: 0.1072  
Epoch 92/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.1007 -  
val\_loss: 0.1081  
Epoch 93/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0998 -  
val\_loss: 0.1093  
Epoch 94/100  
115092/115092 [=====] - 18s 158us/step - loss: 0.0994 -  
val\_loss: 0.1171  
Epoch 95/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0996 -  
val\_loss: 0.0996  
Epoch 96/100  
115092/115092 [=====] - 18s 159us/step - loss: 0.0995 -

```

val_loss: 0.0955
Epoch 97/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0985 -
val_loss: 0.0968
Epoch 98/100
115092/115092 [=====] - 18s 159us/step - loss: 0.0982 -
val_loss: 0.1178
Epoch 99/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0979 -
val_loss: 0.1069
Epoch 100/100
115092/115092 [=====] - 18s 158us/step - loss: 0.0970 -
val_loss: 0.0968

```

```
[34]: Y_testB = model.predict(X_valB).flatten()
```

```
[35]: Y_testB = np.round(Y_testB, 0)
```

```
[36]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        labelB = YA[i]
        predictionB = Y_testB[i]
        print("Estado: " + np.array2string(labelB) + ", predicted:" + np.
→array2string(predictionB))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 4., predicted:4.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 2., predicted:2.
Estado: 1., predicted:1.

```

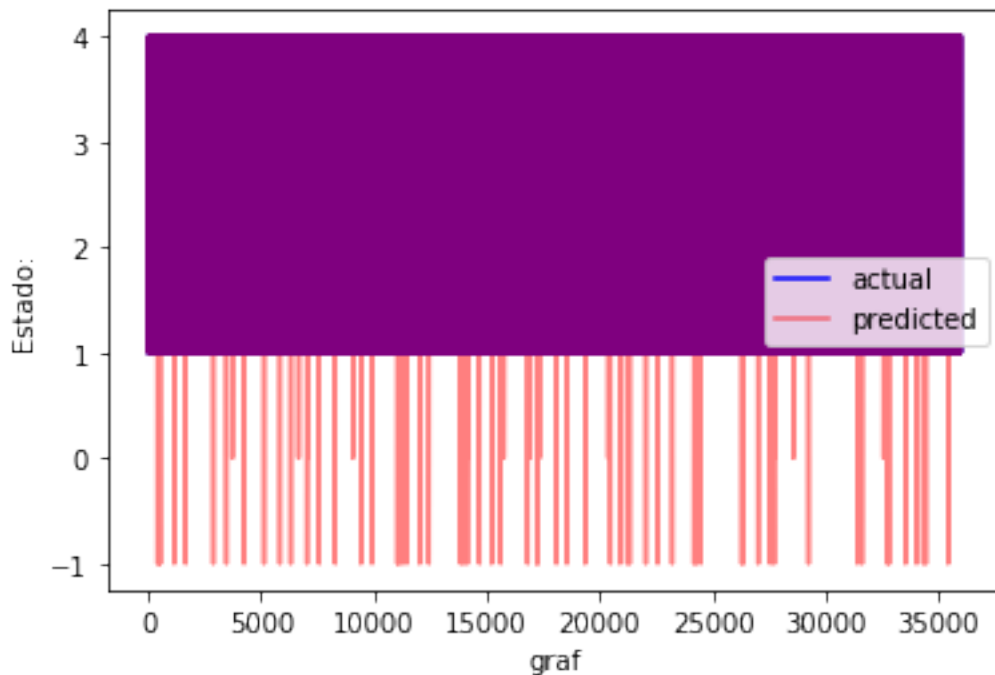


```
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

```
[37]: r2 = r2_score(Y_testB, Y_val)  
print (r2)
```

0.9236670228821766

```
[38]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_testA),  
        color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[39]: Y_val2 = np.array(Y_val.T)[0]  
Accu=Y_val2==Y_testB  
accur=np.sum(Accu)
```

```
accur/len(Y_val)
```

[39]: 0.9430311118525315

Unimos los datos quedandonos con el minimo media y maximo para ver si con alguna de las opciones podemos mejorar los resultados

```
[40]: YtA = np.asmatrix(Y_testA)
      YtB = np.asmatrix(Y_testB)
      ense1=np.zeros(len(Y_testA))
      ense2=np.zeros(len(Y_testA))
      ense3=np.zeros(len(Y_testA))
      Yt=np.concatenate((YtA.T,YtB.T),axis=1)
      for i in range(len(Yt)):
          ense1[i]=np.min(Yt[i,:])
          ense2[i]=np.max(Yt[i,:])
          ense3[i]=np.mean(Yt[i,:])

      ense3 =np.round(ense3, 0)
```

```
[45]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==ense1
      accur=np.sum(Accu)
      accur/len(Y_val)
```

[45]: 0.9559874329246254

```
[41]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==ense2
      accur=np.sum(Accu)
      accur/len(Y_val)
```

[41]: 0.9586009397503267

```
[46]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==ense3
      accur=np.sum(Accu)
      accur/len(Y_val)
```

[46]: 0.9556537937553868

```
[42]: r2 = r2_score(ense1, Y_val)
      print (r2)
```

0.9305066644684276

```
[43]: r2 = r2_score(ense2, Y_val)
      print (r2)
```

0.9386869691515516

```
[44]: r2 = r2_score(ense3, Y_val)
      print (r2)
```

0.9486139227380893

```
[ ]:
```

# TFM\_wrist\_data\_ENSEMBLE2-final

September 4, 2019

```
[1]: from keras.layers import Input
from keras.layers.core import Dense, Activation
from keras.models import Sequential, Model
from keras.layers import Activation
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
import pickle
import numpy as np
import sys
import os
import pandas
from pandas import set_option
from matplotlib import pyplot
from sklearn.model_selection import train_test_split
```

Using TensorFlow backend.

## 0.1 Ensemble

```
[2]: data = pickle.load(open('S2.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
```

```

l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT1=np.concatenate((B1,A2),axis=1)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]>4), 0)
MAT1 = np.delete(MAT1, np.where(MAT1[:,0]<=0), 0)

```

```

[3]: data = pickle.load(open('S3.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):

```

```

    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT2=np.concatenate((B1,A2),axis=1)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]>4), 0)
MAT2 = np.delete(MAT2, np.where(MAT2[:,0]<=0), 0)

```

```

[4]: data = pickle.load(open('S4.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind

```

```

l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=25*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT3=np.concatenate((B1,A2),axis=1)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]>4), 0)
MAT3 = np.delete(MAT3, np.where(MAT3[:,0]<=0), 0)

```

```

[5]: data = pickle.load(open('S5.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind

```

```

Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=35*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT4=np.concatenate((B1,A2),axis=1)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]>4), 0)
MAT4 = np.delete(MAT4, np.where(MAT4[:,0]<=0), 0)

```

```

[6]: data = pickle.load(open('S6.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']

```



```

mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT5=np.concatenate((B1,A2),axis=1)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]>4), 0)
MAT5 = np.delete(MAT5, np.where(MAT5[:,0]<=0), 0)

```

```

[7]: data = pickle.load(open('S7.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']

```

```

c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT6=np.concatenate((B1,A2),axis=1)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]>4), 0)
MAT6 = np.delete(MAT6, np.where(MAT6[:,0]<=0), 0)

```

```

[8]: data = pickle.load(open('S8.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT7=np.concatenate((B1,A2),axis=1)

```

```
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]>4), 0)
MAT7 = np.delete(MAT7, np.where(MAT7[:,0]<=0), 0)
```

```
[9]: data = pickle.load(open('S9.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
```

```

B1 = np.asmatrix(E)
B1=B1.T
MAT8=np.concatenate((B1,A2),axis=1)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]>4), 0)
MAT8 = np.delete(MAT8, np.where(MAT8[:,0]<=0), 0)

```

```

[10]: data = pickle.load(open('S10.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]

```

```

    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT9=np.concatenate((B1,A2),axis=1)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]>4), 0)
MAT9 = np.delete(MAT9, np.where(MAT9[:,0]<=0), 0)

```

```

[11]: data = pickle.load(open('S11.pkl','rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]

```

```

for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=26*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT10=np.concatenate((B1,A2),axis=1)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]>4), 0)
MAT10 = np.delete(MAT10, np.where(MAT10[:,0]<=0), 0)

```

```

[12]: data = pickle.load(open('S13.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]

```

```

    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT11=np.concatenate((B1,A2),axis=1)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]>4), 0)
MAT11 = np.delete(MAT11, np.where(MAT11[:,0]<=0), 0)

```

```

[13]: data = pickle.load(open('S14.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]

```



```

for i in range(14):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(15):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=27*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT12=np.concatenate((B1,A2),axis=1)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]>4), 0)
MAT12 = np.delete(MAT12, np.where(MAT12[:,0]<=0), 0)

```

```

[14]: data = pickle.load(open('S15.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]

```

```

    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=28*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT13=np.concatenate((B1,A2),axis=1)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]>4), 0)
MAT13 = np.delete(MAT13, np.where(MAT13[:,0]<=0), 0)

```

```

[15]: data = pickle.load(open('S16.pkl', 'rb'), encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]
    B.append(at)
l3=int(len(c)/Cal3)
C=[]

```

```

for i in range(13):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=24*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT14=np.concatenate((B1,A2),axis=1)
MAT14 = np.delete(MAT14, np.where(MAT14[:,0]>4), 0)
MAT14= np.delete(MAT14, np.where(MAT14[:,0]<=0), 0)

```

```

[16]: data = pickle.load(open('S17.pkl', 'rb'),encoding='latin1')
a=data['signal']['wrist']['ACC']
b=data['signal']['wrist']['BVP']
c=data['signal']['wrist']['EDA']
d=data['signal']['wrist']['TEMP']
A21=data['label']
mind=min(len(a),len(b),len(c),len(d),len(A21))
Cal1=len(a)/mind
Cal2=len(b)/mind
Cal3=len(c)/mind
Cal4=len(d)/mind
Cal5=len(A21)/mind
l1=int(len(a)/Cal1)
A=[]
for i in range(l1):
    k=i*Cal1
    at=a[int(k)]
    A.append(at)
l2=int(len(b)/Cal2)
B=[]
for i in range(l2):
    k=i*Cal2
    at=b[int(k)]

```

```

    B.append(at)
l3=int(len(c)/Cal3)
C=[]
for i in range(l3):
    k=i*Cal3
    at=c[int(k)]
    C.append(at)
l4=int(len(d)/Cal4)
D=[]
for i in range(l4):
    k=i*Cal4
    at=d[int(k)]
    D.append(at)
l5=int(len(A21)/Cal5)
E=[]
for i in range(l5):
    k=i*Cal5
    at=A21[int(k)]
    E.append(at)
A2a=29*(np.ones((mind,1)))
A2=np.concatenate((A,B,C,D,A2a),axis=1)
B1 = np.asmatrix(E)
B1=B1.T
MAT15=np.concatenate((B1,A2),axis=1)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]>4), 0)
MAT15 = np.delete(MAT15, np.where(MAT15[:,0]<=0), 0)

```

```

[17]: MAT=np.
    →concatenate((MAT1,MAT2,MAT3,MAT4,MAT5,MAT6,MAT7,MAT8,MAT9,MAT10,MAT11,MAT12,MAT13,MAT14,MAT

```

```

[18]: X = MAT[:, 1:8]
Y = MAT[:, 0]
validation_size = 0.2
seed = 7
X_train, X_val, Y_train, Y_val = train_test_split(X, Y,
    →test_size=validation_size, random_state=seed)

```

```

[19]: X_trainA= np.delete(X_train,3 , 1)
X_trainB= np.delete(X_train,4 , 1)
X_valA= np.delete(X_val,3, 1)
X_valB= np.delete(X_val,4 , 1)

```

```

[20]: model = Sequential([
    Dense(128, input_shape=(6,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(60),
    Activation('elu'),

```

```
Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')
```

WARNING: Logging before flag parsing goes to stderr.  
W0903 22:06:30.329254 19528 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:74: The name tf.get\_default\_graph  
is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

W0903 22:06:30.364161 19528 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:517: The name tf.placeholder is  
deprecated. Please use tf.compat.v1.placeholder instead.

W0903 22:06:30.376129 19528 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:4138: The name tf.random\_uniform is  
deprecated. Please use tf.random.uniform instead.

W0903 22:06:30.440954 19528 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-packages\keras\optimizers.py:790:  
The name tf.train.Optimizer is deprecated. Please use  
tf.compat.v1.train.Optimizer instead.

```
[21]: NUM_EPOCHS =200
      BATCH_SIZE = 20

      history = model.fit(X_trainA, Y_train, batch_size=BATCH_SIZE,
      ↪epochs=NUM_EPOCHS, validation_split=0.2)
```

W0903 22:06:30.655380 19528 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:986: The name tf.assign\_add is  
deprecated. Please use tf.compat.v1.assign\_add instead.

W0903 22:06:30.661365 19528 deprecation\_wrapper.py:119] From  
C:\Users\jorge\Anaconda3\envs\TFMGPU\lib\site-  
packages\keras\backend\tensorflow\_backend.py:973: The name tf.assign is  
deprecated. Please use tf.compat.v1.assign instead.

Train on 115092 samples, validate on 28773 samples  
Epoch 1/200

115092/115092 [=====] - 20s 175us/step - loss: 0.5623 -  
val\_loss: 0.3846  
Epoch 2/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.3386 -  
val\_loss: 0.3603  
Epoch 3/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.2668 -  
val\_loss: 0.2803  
Epoch 4/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.2250 -  
val\_loss: 0.2247  
Epoch 5/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.2010 -  
val\_loss: 0.2149  
Epoch 6/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.1836 -  
val\_loss: 0.2007  
Epoch 7/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.1706 -  
val\_loss: 0.1680  
Epoch 8/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.1591 -  
val\_loss: 0.1638  
Epoch 9/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.1493 -  
val\_loss: 0.1500  
Epoch 10/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.1411 -  
val\_loss: 0.1274  
Epoch 11/200  
115092/115092 [=====] - 17s 143us/step - loss: 0.1340 -  
val\_loss: 0.1309  
Epoch 12/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.1283 -  
val\_loss: 0.1240  
Epoch 13/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1240 -  
val\_loss: 0.1212  
Epoch 14/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.1201 -  
val\_loss: 0.1258  
Epoch 15/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.1169 -  
val\_loss: 0.1391  
Epoch 16/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.1144 -  
val\_loss: 0.1317  
Epoch 17/200

115092/115092 [=====] - 16s 139us/step - loss: 0.1124 -  
val\_loss: 0.1361  
Epoch 18/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.1097 -  
val\_loss: 0.1193  
Epoch 19/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.1073 -  
val\_loss: 0.1104  
Epoch 20/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.1054 -  
val\_loss: 0.1036  
Epoch 21/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.1031 -  
val\_loss: 0.1000  
Epoch 22/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.1013 -  
val\_loss: 0.1135  
Epoch 23/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.1000 -  
val\_loss: 0.0997  
Epoch 24/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0983 -  
val\_loss: 0.1090  
Epoch 25/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0970 -  
val\_loss: 0.1112  
Epoch 26/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0955 -  
val\_loss: 0.0986  
Epoch 27/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0941 -  
val\_loss: 0.0981  
Epoch 28/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0928 -  
val\_loss: 0.1028  
Epoch 29/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0917 -  
val\_loss: 0.0955  
Epoch 30/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0907 -  
val\_loss: 0.1047  
Epoch 31/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.0898 -  
val\_loss: 0.1090  
Epoch 32/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.0886 -  
val\_loss: 0.0887  
Epoch 33/200

115092/115092 [=====] - 16s 141us/step - loss: 0.0879 -  
val\_loss: 0.0874  
Epoch 34/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0869 -  
val\_loss: 0.0893  
Epoch 35/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0861 -  
val\_loss: 0.0974  
Epoch 36/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0857 -  
val\_loss: 0.0893  
Epoch 37/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0853 -  
val\_loss: 0.0955  
Epoch 38/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0846 -  
val\_loss: 0.0880  
Epoch 39/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0837 -  
val\_loss: 0.0817  
Epoch 40/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0828 -  
val\_loss: 0.0861  
Epoch 41/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0825 -  
val\_loss: 0.0968  
Epoch 42/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0821 -  
val\_loss: 0.0841  
Epoch 43/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0817 -  
val\_loss: 0.0798  
Epoch 44/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0809 -  
val\_loss: 0.0813  
Epoch 45/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0802 -  
val\_loss: 0.0903  
Epoch 46/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.0805 -  
val\_loss: 0.0861  
Epoch 47/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.0797 -  
val\_loss: 0.0906  
Epoch 48/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0790 -  
val\_loss: 0.0830  
Epoch 49/200



115092/115092 [=====] - 17s 145us/step - loss: 0.0785 -  
val\_loss: 0.0816  
Epoch 50/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0783 -  
val\_loss: 0.0914  
Epoch 51/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0780 -  
val\_loss: 0.0825  
Epoch 52/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0776 -  
val\_loss: 0.0947  
Epoch 53/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0770 -  
val\_loss: 0.0802  
Epoch 54/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0767 -  
val\_loss: 0.0829  
Epoch 55/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0764 -  
val\_loss: 0.0797  
Epoch 56/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0760 -  
val\_loss: 0.0835  
Epoch 57/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0756 -  
val\_loss: 0.0751  
Epoch 58/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0753 -  
val\_loss: 0.0909  
Epoch 59/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0749 -  
val\_loss: 0.0964  
Epoch 60/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0748 -  
val\_loss: 0.0913  
Epoch 61/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0742 -  
val\_loss: 0.0961  
Epoch 62/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0744 -  
val\_loss: 0.0790  
Epoch 63/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0735 -  
val\_loss: 0.0816  
Epoch 64/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0734 -  
val\_loss: 0.0790  
Epoch 65/200

115092/115092 [=====] - 16s 140us/step - loss: 0.0736 -  
val\_loss: 0.0787  
Epoch 66/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0731 -  
val\_loss: 0.0732  
Epoch 67/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0726 -  
val\_loss: 0.0994  
Epoch 68/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0725 -  
val\_loss: 0.0855  
Epoch 69/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0719 -  
val\_loss: 0.0763  
Epoch 70/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0719 -  
val\_loss: 0.0722  
Epoch 71/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0714 -  
val\_loss: 0.0850  
Epoch 72/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0719 -  
val\_loss: 0.0735  
Epoch 73/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0707 -  
val\_loss: 0.0790  
Epoch 74/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0713 -  
val\_loss: 0.0791  
Epoch 75/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0707 -  
val\_loss: 0.0722  
Epoch 76/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0707 -  
val\_loss: 0.0885  
Epoch 77/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0704 -  
val\_loss: 0.0775  
Epoch 78/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0699 -  
val\_loss: 0.0755  
Epoch 79/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0699 -  
val\_loss: 0.0666  
Epoch 80/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0696 -  
val\_loss: 0.0656  
Epoch 81/200

115092/115092 [=====] - 16s 139us/step - loss: 0.0692 -  
val\_loss: 0.0802  
Epoch 82/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0691 -  
val\_loss: 0.0826  
Epoch 83/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0689 -  
val\_loss: 0.0813  
Epoch 84/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.0685 -  
val\_loss: 0.0690  
Epoch 85/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.0683 -  
val\_loss: 0.0701  
Epoch 86/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0683 -  
val\_loss: 0.0690  
Epoch 87/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0676 -  
val\_loss: 0.0681  
Epoch 88/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0674 -  
val\_loss: 0.0724  
Epoch 89/200  
115092/115092 [=====] - 16s 137us/step - loss: 0.0677 -  
val\_loss: 0.0902  
Epoch 90/200  
115092/115092 [=====] - 16s 137us/step - loss: 0.0674 -  
val\_loss: 0.0902  
Epoch 91/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0671 -  
val\_loss: 0.0711  
Epoch 92/200  
115092/115092 [=====] - 16s 137us/step - loss: 0.0669 -  
val\_loss: 0.0611  
Epoch 93/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0668 -  
val\_loss: 0.0734  
Epoch 94/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0665 -  
val\_loss: 0.0742  
Epoch 95/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0663 -  
val\_loss: 0.0723  
Epoch 96/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0662 -  
val\_loss: 0.0654  
Epoch 97/200

115092/115092 [=====] - 16s 141us/step - loss: 0.0658 -  
val\_loss: 0.0657  
Epoch 98/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0659 -  
val\_loss: 0.0758  
Epoch 99/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0655 -  
val\_loss: 0.0678  
Epoch 100/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0655 -  
val\_loss: 0.0749  
Epoch 101/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0658 -  
val\_loss: 0.0771  
Epoch 102/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0652 -  
val\_loss: 0.0921  
Epoch 103/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0652 -  
val\_loss: 0.0775  
Epoch 104/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0651 -  
val\_loss: 0.0655  
Epoch 105/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0650 -  
val\_loss: 0.0794  
Epoch 106/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0653 -  
val\_loss: 0.0665  
Epoch 107/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0649 -  
val\_loss: 0.0685  
Epoch 108/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0650 -  
val\_loss: 0.0804  
Epoch 109/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0649 -  
val\_loss: 0.0735  
Epoch 110/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0643 -  
val\_loss: 0.0726  
Epoch 111/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0639 -  
val\_loss: 0.0745  
Epoch 112/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0642 -  
val\_loss: 0.0598  
Epoch 113/200

115092/115092 [=====] - 17s 145us/step - loss: 0.0642 -  
val\_loss: 0.0724  
Epoch 114/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0642 -  
val\_loss: 0.0621  
Epoch 115/200  
115092/115092 [=====] - 16s 137us/step - loss: 0.0640 -  
val\_loss: 0.0751  
Epoch 116/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0636 -  
val\_loss: 0.0732  
Epoch 117/200  
115092/115092 [=====] - 16s 137us/step - loss: 0.0634 -  
val\_loss: 0.0782  
Epoch 118/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0634 -  
val\_loss: 0.0577  
Epoch 119/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0631 -  
val\_loss: 0.0787  
Epoch 120/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0636 -  
val\_loss: 0.0907  
Epoch 121/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0628 -  
val\_loss: 0.0714  
Epoch 122/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0631 -  
val\_loss: 0.0578  
Epoch 123/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0624 -  
val\_loss: 0.0754  
Epoch 124/200  
115092/115092 [=====] - 16s 135us/step - loss: 0.0629 -  
val\_loss: 0.0648  
Epoch 125/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0626 -  
val\_loss: 0.0718  
Epoch 126/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0626 -  
val\_loss: 0.0697  
Epoch 127/200  
115092/115092 [=====] - 16s 135us/step - loss: 0.0627 -  
val\_loss: 0.0677  
Epoch 128/200  
115092/115092 [=====] - 16s 135us/step - loss: 0.0625 -  
val\_loss: 0.0628  
Epoch 129/200

115092/115092 [=====] - 16s 136us/step - loss: 0.0622 -  
val\_loss: 0.0719  
Epoch 130/200  
115092/115092 [=====] - 16s 135us/step - loss: 0.0621 -  
val\_loss: 0.0597  
Epoch 131/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0620 -  
val\_loss: 0.0634  
Epoch 132/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0618 -  
val\_loss: 0.0632  
Epoch 133/200  
115092/115092 [=====] - 16s 136us/step - loss: 0.0618 -  
val\_loss: 0.0620  
Epoch 134/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0616 -  
val\_loss: 0.0786  
Epoch 135/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0615 -  
val\_loss: 0.0713  
Epoch 136/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0615 -  
val\_loss: 0.0629  
Epoch 137/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0609 -  
val\_loss: 0.0527  
Epoch 138/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0616 -  
val\_loss: 0.0633  
Epoch 139/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0618 -  
val\_loss: 0.0739  
Epoch 140/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0613 -  
val\_loss: 0.0644  
Epoch 141/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0611 -  
val\_loss: 0.0728  
Epoch 142/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0614 -  
val\_loss: 0.0855  
Epoch 143/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0608 -  
val\_loss: 0.0645  
Epoch 144/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0611 -  
val\_loss: 0.0693  
Epoch 145/200

115092/115092 [=====] - 17s 145us/step - loss: 0.0609 -  
val\_loss: 0.0850  
Epoch 146/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0610 -  
val\_loss: 0.0709  
Epoch 147/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0606 -  
val\_loss: 0.0625  
Epoch 148/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0607 -  
val\_loss: 0.0661  
Epoch 149/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0602 -  
val\_loss: 0.0803  
Epoch 150/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0603 -  
val\_loss: 0.0702  
Epoch 151/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0602 -  
val\_loss: 0.0625  
Epoch 152/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0601 -  
val\_loss: 0.0675  
Epoch 153/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.0603 -  
val\_loss: 0.0695  
Epoch 154/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0600 -  
val\_loss: 0.0669  
Epoch 155/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0601 -  
val\_loss: 0.0644  
Epoch 156/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0600 -  
val\_loss: 0.0754  
Epoch 157/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.0598 -  
val\_loss: 0.0768  
Epoch 158/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0595 -  
val\_loss: 0.0649  
Epoch 159/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.0599 -  
val\_loss: 0.0737  
Epoch 160/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0600 -  
val\_loss: 0.0528  
Epoch 161/200

115092/115092 [=====] - 16s 140us/step - loss: 0.0596 -  
val\_loss: 0.0688  
Epoch 162/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0598 -  
val\_loss: 0.0584  
Epoch 163/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0595 -  
val\_loss: 0.0903  
Epoch 164/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0595 -  
val\_loss: 0.0657  
Epoch 165/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0595 -  
val\_loss: 0.0596  
Epoch 166/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0592 -  
val\_loss: 0.0615  
Epoch 167/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0592 -  
val\_loss: 0.0605  
Epoch 168/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0591 -  
val\_loss: 0.0703  
Epoch 169/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0597 -  
val\_loss: 0.0676  
Epoch 170/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.0591 -  
val\_loss: 0.0707  
Epoch 171/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0590 -  
val\_loss: 0.0654  
Epoch 172/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0589 -  
val\_loss: 0.0729  
Epoch 173/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0588 -  
val\_loss: 0.0621  
Epoch 174/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0592 -  
val\_loss: 0.0622  
Epoch 175/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0591 -  
val\_loss: 0.0646  
Epoch 176/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.0589 -  
val\_loss: 0.0722  
Epoch 177/200



115092/115092 [=====] - 17s 145us/step - loss: 0.0590 -  
val\_loss: 0.0635  
Epoch 178/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0588 -  
val\_loss: 0.0639  
Epoch 179/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0583 -  
val\_loss: 0.0682  
Epoch 180/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0584 -  
val\_loss: 0.0749  
Epoch 181/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.0583 -  
val\_loss: 0.0621  
Epoch 182/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.0585 -  
val\_loss: 0.0579  
Epoch 183/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0582 -  
val\_loss: 0.0713  
Epoch 184/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0585 -  
val\_loss: 0.0687  
Epoch 185/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0584 -  
val\_loss: 0.0713  
Epoch 186/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0588 -  
val\_loss: 0.0675  
Epoch 187/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0588 -  
val\_loss: 0.0595  
Epoch 188/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0582 -  
val\_loss: 0.0747  
Epoch 189/200  
115092/115092 [=====] - 16s 139us/step - loss: 0.0579 -  
val\_loss: 0.0604  
Epoch 190/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.0583 -  
val\_loss: 0.0606  
Epoch 191/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0581 -  
val\_loss: 0.0571  
Epoch 192/200  
115092/115092 [=====] - 16s 138us/step - loss: 0.0585 -  
val\_loss: 0.0756  
Epoch 193/200

```

115092/115092 [=====] - 16s 138us/step - loss: 0.0580 -
val_loss: 0.0600
Epoch 194/200
115092/115092 [=====] - 16s 138us/step - loss: 0.0581 -
val_loss: 0.0661
Epoch 195/200
115092/115092 [=====] - 16s 138us/step - loss: 0.0580 -
val_loss: 0.0547
Epoch 196/200
115092/115092 [=====] - 16s 138us/step - loss: 0.0582 -
val_loss: 0.0648
Epoch 197/200
115092/115092 [=====] - 16s 139us/step - loss: 0.0581 -
val_loss: 0.0634
Epoch 198/200
115092/115092 [=====] - 16s 138us/step - loss: 0.0578 -
val_loss: 0.0550
Epoch 199/200
115092/115092 [=====] - 16s 138us/step - loss: 0.0579 -
val_loss: 0.0635
Epoch 200/200
115092/115092 [=====] - 16s 139us/step - loss: 0.0582 -
val_loss: 0.0692

```

```
[22]: Y_testA = model.predict(X_valA).flatten()
```

```
[23]: Y_testA = np.round(Y_testA, 0)
```

```
[24]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        label = YA[i]
        predictionA = Y_testA[i]
        print("Estado: "+ np.array2string(label) + ", predicted:" + np.
        ↳array2string(predictionA))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 1., predicted:1.

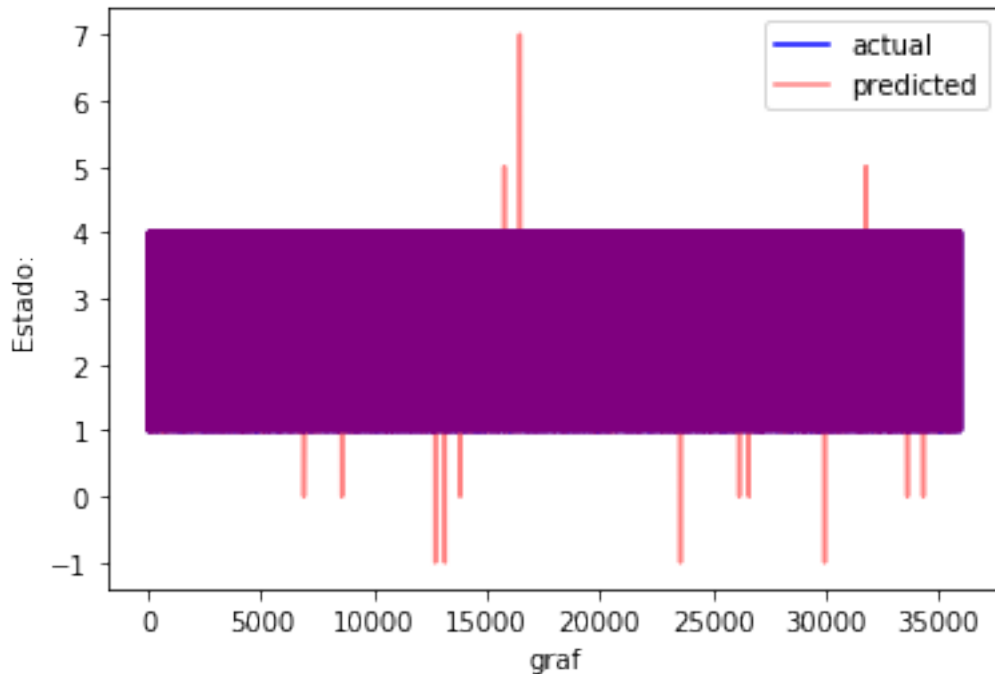
```

```
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

```
[25]: from sklearn.metrics import r2_score  
r2 = r2_score(Y_testA, Y_val)  
print (r2)
```

0.9623221863076288

```
[26]: plt.plot((Y_val),  
             color="b", label="actual")  
plt.plot((Y_testA),  
         color="r", alpha=0.5, label="predicted")  
plt.xlabel("graf")  
plt.ylabel("Estado:")  
plt.legend(loc="best")  
plt.show()
```



```
[27]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_testA
accur=np.sum(Accu)
accur/len(Y_val)
```

```
[27]: 0.9718352934634527
```

```
[28]: model = Sequential([
    Dense(128, input_shape=(6,)),
    Activation('elu'),
    Dense(70),
    Activation('elu'),
    Dense(60),
    Activation('elu'),
    Dense(1),
    Activation('elu'),
])

model.compile(optimizer='Adadelta',loss='mae')
```

```
[29]: NUM_EPOCHS =200
BATCH_SIZE = 20

history = model.fit(X_trainB, Y_train, batch_size=BATCH_SIZE,
    →epochs=NUM_EPOCHS, validation_split=0.2)
```

Train on 115092 samples, validate on 28773 samples

Epoch 1/200

115092/115092 [=====] - 17s 149us/step - loss: 0.6444 -  
val\_loss: 0.4960

Epoch 2/200

115092/115092 [=====] - 17s 145us/step - loss: 0.4209 -  
val\_loss: 0.4074

Epoch 3/200

115092/115092 [=====] - 17s 145us/step - loss: 0.3398 -  
val\_loss: 0.3533

Epoch 4/200

115092/115092 [=====] - 17s 145us/step - loss: 0.2947 -  
val\_loss: 0.3078

Epoch 5/200

115092/115092 [=====] - 17s 145us/step - loss: 0.2652 -  
val\_loss: 0.2337

Epoch 6/200

115092/115092 [=====] - 17s 146us/step - loss: 0.2450 -  
val\_loss: 0.2362

Epoch 7/200

115092/115092 [=====] - 17s 147us/step - loss: 0.2311 -  
val\_loss: 0.2506

Epoch 8/200

115092/115092 [=====] - 17s 147us/step - loss: 0.2195 -  
val\_loss: 0.2046

Epoch 9/200

115092/115092 [=====] - 17s 146us/step - loss: 0.2107 -  
val\_loss: 0.2227

Epoch 10/200

115092/115092 [=====] - 17s 145us/step - loss: 0.2043 -  
val\_loss: 0.2069

Epoch 11/200

115092/115092 [=====] - 17s 145us/step - loss: 0.1981 -  
val\_loss: 0.2119

Epoch 12/200

115092/115092 [=====] - 17s 146us/step - loss: 0.1929 -  
val\_loss: 0.1847

Epoch 13/200

115092/115092 [=====] - 17s 145us/step - loss: 0.1881 -  
val\_loss: 0.1772

Epoch 14/200

115092/115092 [=====] - 17s 148us/step - loss: 0.1843 -  
val\_loss: 0.1850

Epoch 15/200

115092/115092 [=====] - 17s 146us/step - loss: 0.1802 -  
val\_loss: 0.1848

Epoch 16/200

115092/115092 [=====] - 17s 145us/step - loss: 0.1766 -

val\_loss: 0.1691  
Epoch 17/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1731 -  
val\_loss: 0.1793  
Epoch 18/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1704 -  
val\_loss: 0.1650  
Epoch 19/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1685 -  
val\_loss: 0.1750  
Epoch 20/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1657 -  
val\_loss: 0.2017  
Epoch 21/200  
115092/115092 [=====] - 18s 153us/step - loss: 0.1641 -  
val\_loss: 0.1774  
Epoch 22/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1622 -  
val\_loss: 0.1709  
Epoch 23/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1598 -  
val\_loss: 0.1615  
Epoch 24/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1578 -  
val\_loss: 0.1844  
Epoch 25/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1559 -  
val\_loss: 0.1554  
Epoch 26/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1544 -  
val\_loss: 0.1484  
Epoch 27/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1527 -  
val\_loss: 0.1693  
Epoch 28/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1514 -  
val\_loss: 0.1678  
Epoch 29/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1499 -  
val\_loss: 0.1496  
Epoch 30/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1486 -  
val\_loss: 0.1473  
Epoch 31/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1478 -  
val\_loss: 0.1547  
Epoch 32/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1456 -

```
val_loss: 0.1678
Epoch 33/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1445 -
val_loss: 0.1546
Epoch 34/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1432 -
val_loss: 0.1553
Epoch 35/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1432 -
val_loss: 0.1860
Epoch 36/200
115092/115092 [=====] - 17s 148us/step - loss: 0.1413 -
val_loss: 0.1444
Epoch 37/200
115092/115092 [=====] - 17s 148us/step - loss: 0.1409 -
val_loss: 0.1547
Epoch 38/200
115092/115092 [=====] - 17s 148us/step - loss: 0.1395 -
val_loss: 0.1414
Epoch 39/200
115092/115092 [=====] - 17s 149us/step - loss: 0.1386 -
val_loss: 0.1397
Epoch 40/200
115092/115092 [=====] - 17s 150us/step - loss: 0.1374 -
val_loss: 0.1514
Epoch 41/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1366 -
val_loss: 0.1453
Epoch 42/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1352 -
val_loss: 0.1370
Epoch 43/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1352 -
val_loss: 0.1332
Epoch 44/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1339 -
val_loss: 0.1560
Epoch 45/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1330 -
val_loss: 0.1462
Epoch 46/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1327 -
val_loss: 0.1369
Epoch 47/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1333 -
val_loss: 0.1353
Epoch 48/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1312 -
```

val\_loss: 0.1438  
Epoch 49/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1311 -  
val\_loss: 0.1373  
Epoch 50/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1308 -  
val\_loss: 0.1400  
Epoch 51/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1303 -  
val\_loss: 0.1248  
Epoch 52/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.1296 -  
val\_loss: 0.1410  
Epoch 53/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1286 -  
val\_loss: 0.1485  
Epoch 54/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1284 -  
val\_loss: 0.1577  
Epoch 55/200  
115092/115092 [=====] - 18s 153us/step - loss: 0.1275 -  
val\_loss: 0.1312  
Epoch 56/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1272 -  
val\_loss: 0.1275  
Epoch 57/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1259 -  
val\_loss: 0.1431  
Epoch 58/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1261 -  
val\_loss: 0.1315  
Epoch 59/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1244 -  
val\_loss: 0.1290  
Epoch 60/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.1240 -  
val\_loss: 0.1200  
Epoch 61/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1244 -  
val\_loss: 0.1366  
Epoch 62/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1241 -  
val\_loss: 0.1476  
Epoch 63/200  
115092/115092 [=====] - 17s 151us/step - loss: 0.1224 -  
val\_loss: 0.1337  
Epoch 64/200  
115092/115092 [=====] - 17s 150us/step - loss: 0.1224 -



val\_loss: 0.1350  
Epoch 65/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1218 -  
val\_loss: 0.1338  
Epoch 66/200  
115092/115092 [=====] - 17s 150us/step - loss: 0.1217 -  
val\_loss: 0.1361  
Epoch 67/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1213 -  
val\_loss: 0.1269  
Epoch 68/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1210 -  
val\_loss: 0.1278  
Epoch 69/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1202 -  
val\_loss: 0.1323  
Epoch 70/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1199 -  
val\_loss: 0.1355  
Epoch 71/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1189 -  
val\_loss: 0.1184  
Epoch 72/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1189 -  
val\_loss: 0.1222  
Epoch 73/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1184 -  
val\_loss: 0.1208  
Epoch 74/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1181 -  
val\_loss: 0.1359  
Epoch 75/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1180 -  
val\_loss: 0.1308  
Epoch 76/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1174 -  
val\_loss: 0.1293  
Epoch 77/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1163 -  
val\_loss: 0.1172  
Epoch 78/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1173 -  
val\_loss: 0.1223  
Epoch 79/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1168 -  
val\_loss: 0.1184  
Epoch 80/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1164 -

val\_loss: 0.1106  
Epoch 81/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1167 -  
val\_loss: 0.1480  
Epoch 82/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1157 -  
val\_loss: 0.1256  
Epoch 83/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1155 -  
val\_loss: 0.1180  
Epoch 84/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1150 -  
val\_loss: 0.1245  
Epoch 85/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1149 -  
val\_loss: 0.1282  
Epoch 86/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1150 -  
val\_loss: 0.1138  
Epoch 87/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.1144 -  
val\_loss: 0.1100  
Epoch 88/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1140 -  
val\_loss: 0.1084  
Epoch 89/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.1136 -  
val\_loss: 0.1219  
Epoch 90/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1136 -  
val\_loss: 0.1238  
Epoch 91/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1133 -  
val\_loss: 0.1328  
Epoch 92/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1126 -  
val\_loss: 0.1134  
Epoch 93/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1128 -  
val\_loss: 0.1277  
Epoch 94/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1125 -  
val\_loss: 0.1223  
Epoch 95/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1127 -  
val\_loss: 0.1170  
Epoch 96/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1124 -

val\_loss: 0.1332  
Epoch 97/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1119 -  
val\_loss: 0.1346  
Epoch 98/200  
115092/115092 [=====] - 18s 154us/step - loss: 0.1123 -  
val\_loss: 0.1160  
Epoch 99/200  
115092/115092 [=====] - 17s 150us/step - loss: 0.1119 -  
val\_loss: 0.1123  
Epoch 100/200  
115092/115092 [=====] - 17s 148us/step - loss: 0.1118 -  
val\_loss: 0.1169  
Epoch 101/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1113 -  
val\_loss: 0.1151  
Epoch 102/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1109 -  
val\_loss: 0.1426  
Epoch 103/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1111 -  
val\_loss: 0.1010  
Epoch 104/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1108 -  
val\_loss: 0.1463  
Epoch 105/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1105 -  
val\_loss: 0.1223  
Epoch 106/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.1106 -  
val\_loss: 0.1102  
Epoch 107/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.1108 -  
val\_loss: 0.1317  
Epoch 108/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.1103 -  
val\_loss: 0.1114  
Epoch 109/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1100 -  
val\_loss: 0.1230  
Epoch 110/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1092 -  
val\_loss: 0.1144  
Epoch 111/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1097 -  
val\_loss: 0.1059  
Epoch 112/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1098 -

```
val_loss: 0.1163
Epoch 113/200
115092/115092 [=====] - 17s 143us/step - loss: 0.1098 -
val_loss: 0.1138
Epoch 114/200
115092/115092 [=====] - 17s 143us/step - loss: 0.1096 -
val_loss: 0.1347
Epoch 115/200
115092/115092 [=====] - 17s 148us/step - loss: 0.1092 -
val_loss: 0.1270
Epoch 116/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1093 -
val_loss: 0.1092
Epoch 117/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1087 -
val_loss: 0.1200
Epoch 118/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1086 -
val_loss: 0.1133
Epoch 119/200
115092/115092 [=====] - 16s 142us/step - loss: 0.1087 -
val_loss: 0.1038
Epoch 120/200
115092/115092 [=====] - 17s 144us/step - loss: 0.1084 -
val_loss: 0.1117
Epoch 121/200
115092/115092 [=====] - 17s 144us/step - loss: 0.1089 -
val_loss: 0.1108
Epoch 122/200
115092/115092 [=====] - 16s 142us/step - loss: 0.1084 -
val_loss: 0.1067
Epoch 123/200
115092/115092 [=====] - 16s 142us/step - loss: 0.1079 -
val_loss: 0.1163
Epoch 124/200
115092/115092 [=====] - 16s 141us/step - loss: 0.1084 -
val_loss: 0.1300
Epoch 125/200
115092/115092 [=====] - 16s 140us/step - loss: 0.1082 -
val_loss: 0.1308
Epoch 126/200
115092/115092 [=====] - 16s 142us/step - loss: 0.1080 -
val_loss: 0.1068
Epoch 127/200
115092/115092 [=====] - 16s 142us/step - loss: 0.1075 -
val_loss: 0.1108
Epoch 128/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1073 -
```

val\_loss: 0.1269  
Epoch 129/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1071 -  
val\_loss: 0.1223  
Epoch 130/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1073 -  
val\_loss: 0.1094  
Epoch 131/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1073 -  
val\_loss: 0.1216  
Epoch 132/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1067 -  
val\_loss: 0.1176  
Epoch 133/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1065 -  
val\_loss: 0.0967  
Epoch 134/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1064 -  
val\_loss: 0.1095  
Epoch 135/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1060 -  
val\_loss: 0.1152  
Epoch 136/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1064 -  
val\_loss: 0.1155  
Epoch 137/200  
115092/115092 [=====] - 16s 140us/step - loss: 0.1065 -  
val\_loss: 0.1291  
Epoch 138/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.1058 -  
val\_loss: 0.1020  
Epoch 139/200  
115092/115092 [=====] - 16s 141us/step - loss: 0.1054 -  
val\_loss: 0.1261  
Epoch 140/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1052 -  
val\_loss: 0.1136  
Epoch 141/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1057 -  
val\_loss: 0.1058  
Epoch 142/200  
115092/115092 [=====] - 17s 143us/step - loss: 0.1053 -  
val\_loss: 0.1028  
Epoch 143/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1051 -  
val\_loss: 0.1033  
Epoch 144/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1051 -

```
val_loss: 0.1090
Epoch 145/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1053 -
val_loss: 0.1050
Epoch 146/200
115092/115092 [=====] - 16s 141us/step - loss: 0.1047 -
val_loss: 0.1041
Epoch 147/200
115092/115092 [=====] - 18s 160us/step - loss: 0.1047 -
val_loss: 0.1113
Epoch 148/200
115092/115092 [=====] - 19s 164us/step - loss: 0.1052 -
val_loss: 0.1038
Epoch 149/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1047 -
val_loss: 0.1003
Epoch 150/200
115092/115092 [=====] - 17s 152us/step - loss: 0.1046 -
val_loss: 0.1121
Epoch 151/200
115092/115092 [=====] - 17s 150us/step - loss: 0.1039 -
val_loss: 0.1151
Epoch 152/200
115092/115092 [=====] - 17s 149us/step - loss: 0.1044 -
val_loss: 0.1154
Epoch 153/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1038 -
val_loss: 0.1178
Epoch 154/200
115092/115092 [=====] - 17s 148us/step - loss: 0.1045 -
val_loss: 0.1108
Epoch 155/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1045 -
val_loss: 0.1021
Epoch 156/200
115092/115092 [=====] - 18s 152us/step - loss: 0.1043 -
val_loss: 0.1185
Epoch 157/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1040 -
val_loss: 0.1153
Epoch 158/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1031 -
val_loss: 0.1024
Epoch 159/200
115092/115092 [=====] - 17s 151us/step - loss: 0.1038 -
val_loss: 0.1036
Epoch 160/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1038 -
```

val\_loss: 0.1239  
Epoch 161/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1036 -  
val\_loss: 0.0982  
Epoch 162/200  
115092/115092 [=====] - 17s 146us/step - loss: 0.1035 -  
val\_loss: 0.1105  
Epoch 163/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1037 -  
val\_loss: 0.1134  
Epoch 164/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1037 -  
val\_loss: 0.1120  
Epoch 165/200  
115092/115092 [=====] - 17s 149us/step - loss: 0.1030 -  
val\_loss: 0.1108  
Epoch 166/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1032 -  
val\_loss: 0.1073  
Epoch 167/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1033 -  
val\_loss: 0.0950  
Epoch 168/200  
115092/115092 [=====] - 16s 142us/step - loss: 0.1026 -  
val\_loss: 0.1012  
Epoch 169/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1031 -  
val\_loss: 0.1053  
Epoch 170/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1025 -  
val\_loss: 0.1211  
Epoch 171/200  
115092/115092 [=====] - 17s 151us/step - loss: 0.1026 -  
val\_loss: 0.1054  
Epoch 172/200  
115092/115092 [=====] - 17s 143us/step - loss: 0.1030 -  
val\_loss: 0.1028  
Epoch 173/200  
115092/115092 [=====] - 17s 147us/step - loss: 0.1025 -  
val\_loss: 0.1181  
Epoch 174/200  
115092/115092 [=====] - 17s 144us/step - loss: 0.1024 -  
val\_loss: 0.1123  
Epoch 175/200  
115092/115092 [=====] - 16s 143us/step - loss: 0.1025 -  
val\_loss: 0.1001  
Epoch 176/200  
115092/115092 [=====] - 17s 145us/step - loss: 0.1017 -

```
val_loss: 0.1080
Epoch 177/200
115092/115092 [=====] - 16s 143us/step - loss: 0.1023 -
val_loss: 0.1189
Epoch 178/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1023 -
val_loss: 0.1135
Epoch 179/200
115092/115092 [=====] - 16s 143us/step - loss: 0.1016 -
val_loss: 0.0995
Epoch 180/200
115092/115092 [=====] - 16s 142us/step - loss: 0.1020 -
val_loss: 0.1069
Epoch 181/200
115092/115092 [=====] - 16s 143us/step - loss: 0.1022 -
val_loss: 0.1106
Epoch 182/200
115092/115092 [=====] - 17s 144us/step - loss: 0.1014 -
val_loss: 0.0946
Epoch 183/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1013 -
val_loss: 0.1164
Epoch 184/200
115092/115092 [=====] - 17s 144us/step - loss: 0.1020 -
val_loss: 0.0955
Epoch 185/200
115092/115092 [=====] - 17s 144us/step - loss: 0.1019 -
val_loss: 0.1013
Epoch 186/200
115092/115092 [=====] - 17s 144us/step - loss: 0.1019 -
val_loss: 0.1122
Epoch 187/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1013 -
val_loss: 0.1167
Epoch 188/200
115092/115092 [=====] - 16s 143us/step - loss: 0.1013 -
val_loss: 0.1096
Epoch 189/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1010 -
val_loss: 0.0990
Epoch 190/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1013 -
val_loss: 0.1040
Epoch 191/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1014 -
val_loss: 0.1204
Epoch 192/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1006 -
```



```

val_loss: 0.1054
Epoch 193/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1007 -
val_loss: 0.1065
Epoch 194/200
115092/115092 [=====] - 17s 145us/step - loss: 0.1007 -
val_loss: 0.1027
Epoch 195/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1012 -
val_loss: 0.0985
Epoch 196/200
115092/115092 [=====] - 17s 148us/step - loss: 0.1006 -
val_loss: 0.0982
Epoch 197/200
115092/115092 [=====] - 17s 146us/step - loss: 0.1003 -
val_loss: 0.1237
Epoch 198/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1009 -
val_loss: 0.1182
Epoch 199/200
115092/115092 [=====] - 17s 147us/step - loss: 0.1007 -
val_loss: 0.1021
Epoch 200/200
115092/115092 [=====] - 17s 143us/step - loss: 0.1004 -
val_loss: 0.1063

```

```
[30]: Y_testB = model.predict(X_valB).flatten()
```

```
[31]: Y_testB = np.round(Y_testB, 0)
```

```
[32]: for i in range(30):
        YA= np.squeeze(np.asarray(Y_val))
        labelB = YA[i]
        predictionB = Y_testB[i]
        print("Estado: "+ np.array2string(labelB) + ", predicted:" + np.
        →array2string(predictionB))

```

```

Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 3., predicted:3.
Estado: 1., predicted:1.
Estado: 3., predicted:3.
Estado: 4., predicted:4.
Estado: 1., predicted:1.
Estado: 1., predicted:1.
Estado: 2., predicted:2.
Estado: 1., predicted:1.
Estado: 2., predicted:2.

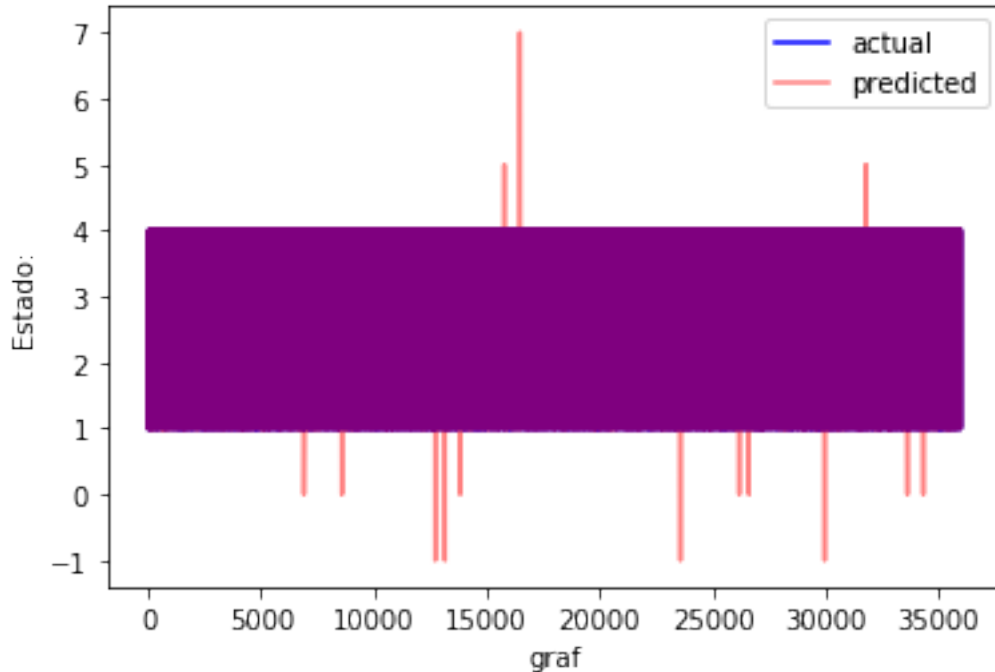
```

```
Estado: 1., predicted:1.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 3., predicted:3.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 2., predicted:2.  
Estado: 4., predicted:4.  
Estado: 2., predicted:2.  
Estado: 1., predicted:1.  
Estado: 3., predicted:3.  
Estado: 1., predicted:1.  
Estado: 1., predicted:1.
```

```
[33]: r2 = r2_score(Y_testB, Y_val)  
      print (r2)
```

0.9340475520483761

```
[34]: plt.plot((Y_val),  
              color="b", label="actual")  
      plt.plot((Y_testA),  
              color="r", alpha=0.5, label="predicted")  
      plt.xlabel("graf")  
      plt.ylabel("Estado:")  
      plt.legend(loc="best")  
      plt.show()
```



```
[35]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==Y_testB
accur=np.sum(Accu)
accur/len(Y_val)
```

[35]: 0.9520393694219701

Unimos los datos quedandonos con el minimo media y maximo para ver si con alguna de las opciones podemos mejorar los resultados

```
[36]: YtA = np.asmatrix(Y_testA)
YtB = np.asmatrix(Y_testB)
ense1=np.zeros(len(Y_testA))
ense2=np.zeros(len(Y_testA))
ense3=np.zeros(len(Y_testA))
Yt=np.concatenate((YtA.T,YtB.T),axis=1)
for i in range(len(Yt)):
    ense1[i]=np.min(Yt[i,:])
    ense2[i]=np.max(Yt[i,:])
    ense3[i]=np.mean(Yt[i,:])

ense3 =np.round(ense3, 0)
```

```
[37]: Y_val2 = np.array(Y_val.T)[0]
Accu=Y_val2==ense1
accur=np.sum(Accu)
accur/len(Y_val)
```

[37]: 0.9547362860399811

```
[38]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==ense2
      accur=np.sum(Accu)
      accur/len(Y_val)
```

[38]: 0.9691383768454417

```
[39]: Y_val2 = np.array(Y_val.T)[0]
      Accu=Y_val2==ense3
      accur=np.sum(Accu)
      accur/len(Y_val)
```

[39]: 0.964995690494064

```
[40]: r2 = r2_score(ense1, Y_val)
      print (r2)
```

0.9414155730076385

```
[41]: r2 = r2_score(ense2, Y_val)
      print (r2)
```

0.9546724540831304

```
[42]: r2 = r2_score(ense3, Y_val)
      print (r2)
```

0.960546544725396

[ ]:

[ ]:

[ ]:

